

# Pneumatic Location Clamp

Model SWT



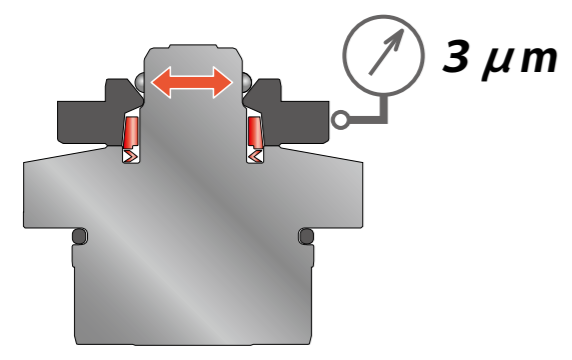
## Locates and clamps simultaneously.

Locating Repeatability : 3 μm All Stainless Steel

PAT.

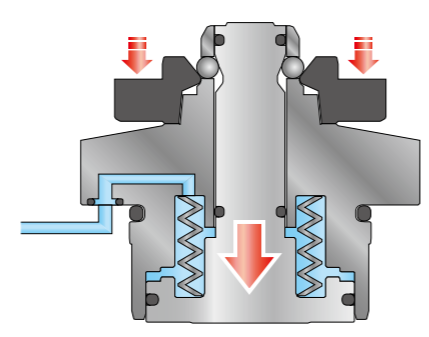
### • Repetitive Locating with High Accuracy

Locating Repeatability : 3 μm  
Used with a combination of the clamp and block.  
Mount the block on the object for locating.



### • Clamping Function

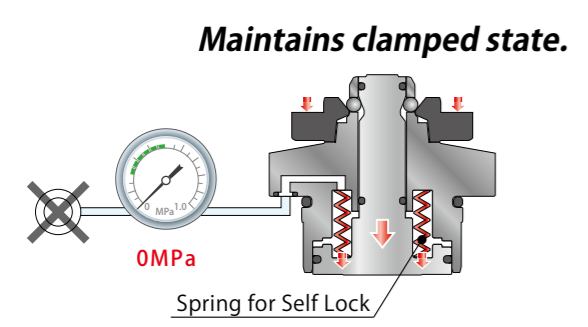
Clamping force is ranged from 0.7kN ~ 9.0kN.  
Clamps with air pressure and spring for self locking.  
Clamping force is selectable for your needs.



### • Self Lock (Safety) Function (Holding Force at zero pneumatic pressure)

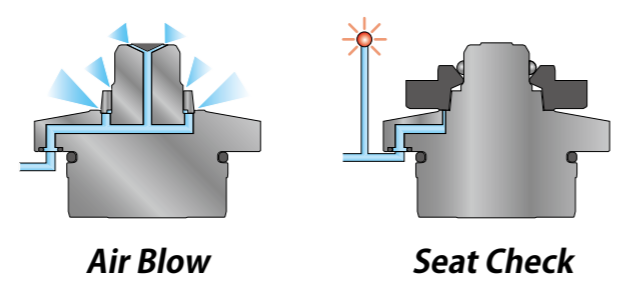
The internal mechanical lock operates and clamping force and holding force achieved. When pneumatic pressure is at zero, it will stay locked with mechanical lock.

※ For locating more than the minimum operating air pressure is required.



### • Air Blow and Seat Check

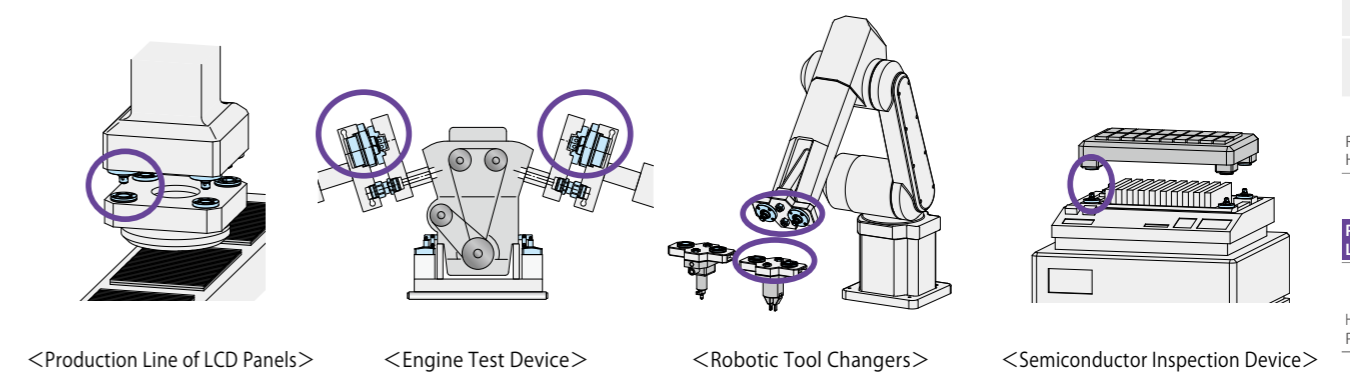
Foreign substance is removed by air blow.  
Seating surface is provided with the air hole, seat check is possible if gap sensor is used.



## Advantages

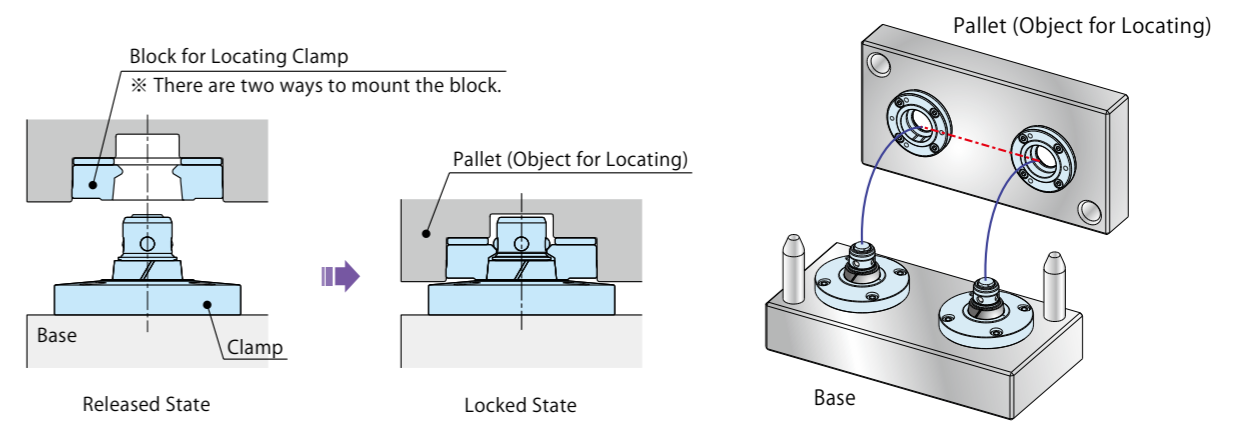
### • Setup improvement enhances productivity.

Pneumatic locating clamp locates with high accuracy and clamps simultaneously. (Fixture alignment and inspection are eliminated.) Fixture change over is faster and easier, thus by eliminating alignment inspection for accuracy which is done in many different ways.



## Application Examples

※ Refer to P.51 for detailed action description.

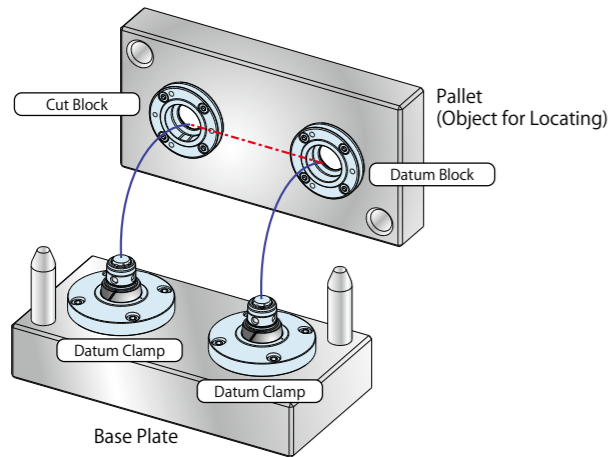


	Model SWT → P.61	Model SWTJ → P.65	Model SWTB → P.63
Classification	Double Action Air Lock / Air Release	Flange Shaped Block	Embedded Block
Operating Pressure Range	0.35~1MPa	-	-
Features	<ul style="list-style-type: none"> <li>Clamping force varies according to air pressure.</li> <li>Self-Lock Function with Spring</li> <li>Material : Stainless</li> </ul>	<ul style="list-style-type: none"> <li>Simple Mounting</li> <li>Material : Stainless</li> </ul>	<ul style="list-style-type: none"> <li>Straight Mounting</li> <li>Material : Stainless</li> </ul>
Accessories	-	-	Level Adjustment Collar (Only for SWTB) Material : Equal to S45C VZ-VSC → P.63

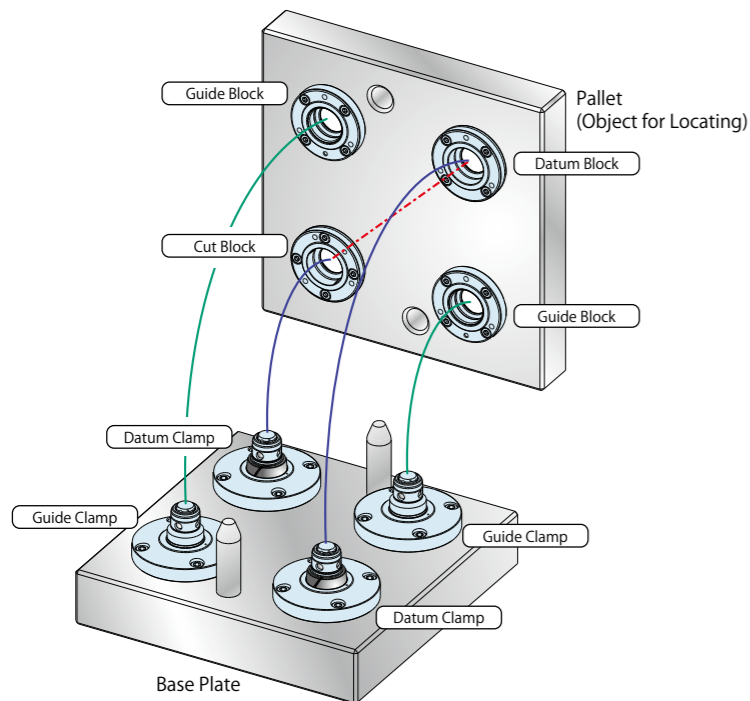
- Locating + Clamp
- Locating
- Clamp
- Support
- Valve · Coupler
- Cautions · Others
- Robotic Hand Changer
  - SWR
- Pneumatic Location Clamp
  - SWT
- High-Power Pneumatic Pallet Clamp
  - WVS

System References

Using Two Air Location Clamps

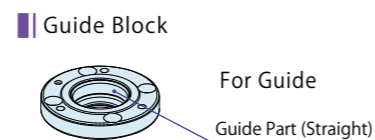
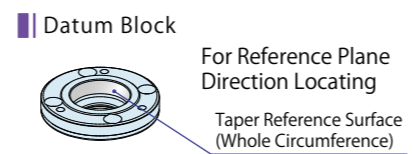
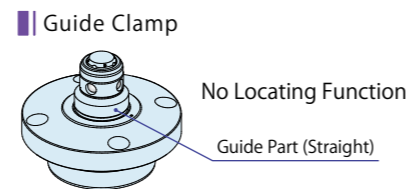
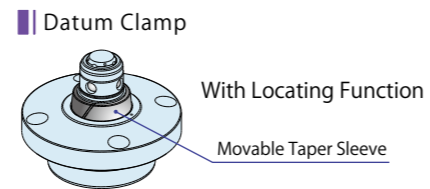


Using Four Air Location Clamps



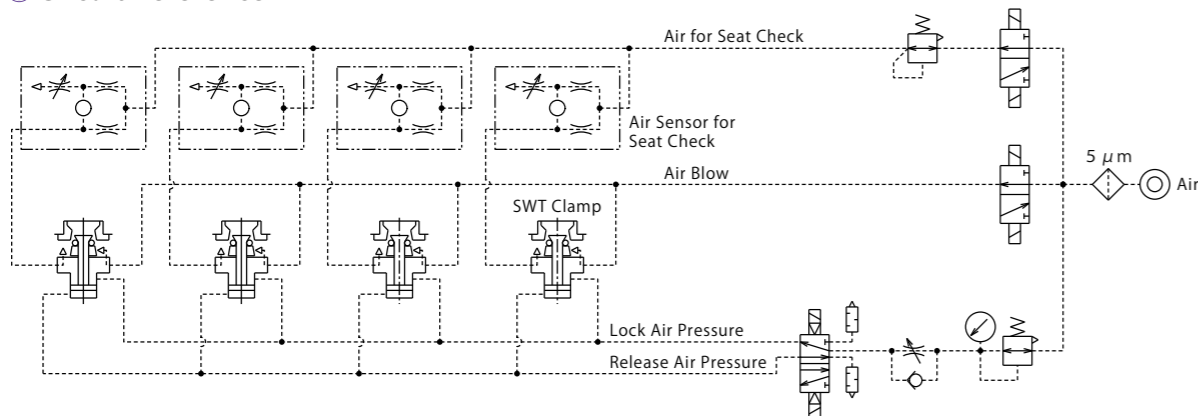
Apparatus and Function

※ For the combination of clamps and blocks, please refer to the P.55.



※ Free block does not have a guide function.

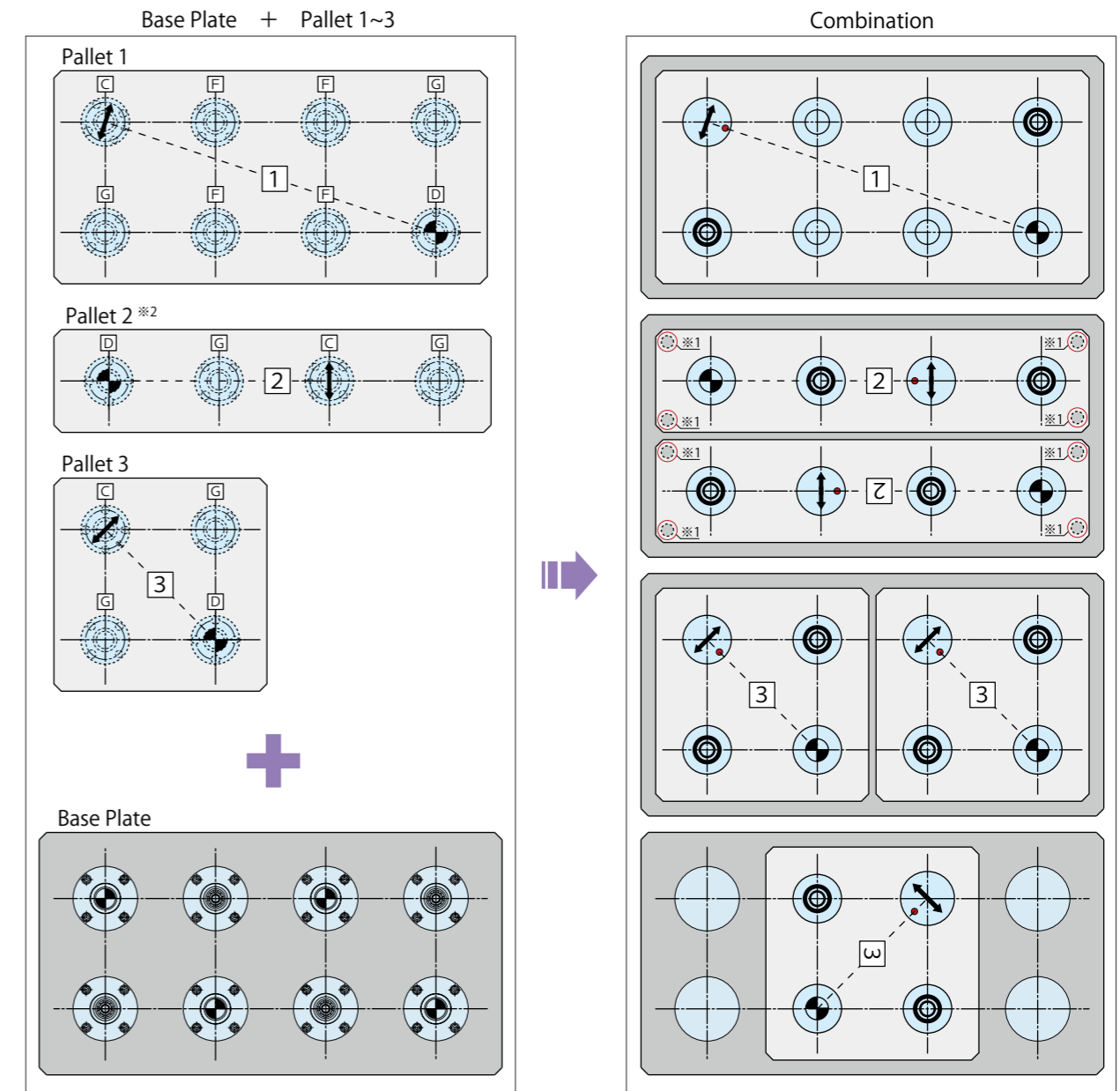
Circuit Reference



Note 1. It is recommended to use air blow line with at least  $\phi 6$  in order to ensure effective air flow. Please supply clean filtered air.

Configuration Sample of Pallets with Different Sizes

In case there are a variety of pallets with different sizes for the base plate, the clamp and block can be combined for use.



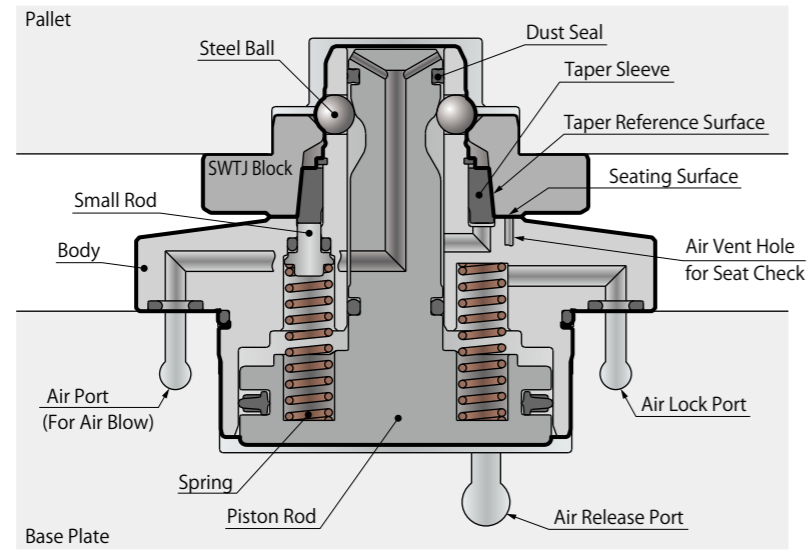
Combination of Clamp and Block

Clamp Installed on the Base Plate	+	Block Installed on the Pallet	⇒	Function when Combined
Datum Clamp	+	Datum Block	⇒	Clamping Function + Locating Function (Reference Point)
Datum Clamp	+	Cut Block	⇒	Clamping Function + Locating Function (One Direction)
Guide Clamp	+	Guide Block	⇒	Clamping Function + Guide Function
Datum Clamp or Guide Clamp	+	Free Block	⇒	Clamping Function

Notes

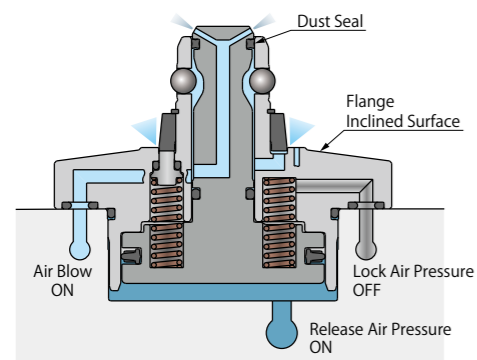
- ※1. In case the clamp/block configuration is linear, it is recommended to provide additional supports for stability.
- ※2. The spring pin position is indicated. With the datum block as reference, unidirectional positioning is done via the cut block. The cut block positioning plane must be tangent to the datum block. (The spring pin is positioned on the line connecting the centers of the datum block and cut block.)

● Cross Section



Material of the Product: SUS (Except for Packing, Shipping Ring, Level Adjustment Collar)

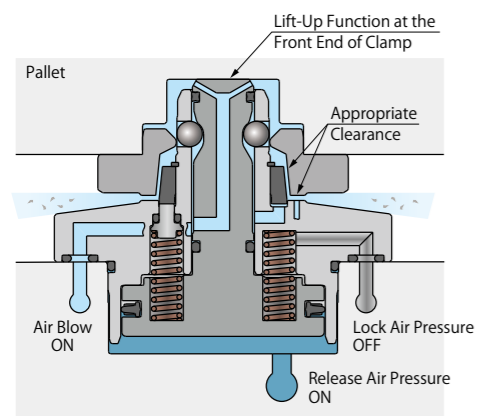
● Action Description



Before Loading Pallet

- Air blow prevents debris contamination.
- Dust seal prevents foreign objects from entering and keeps steel ball area clean.
- The flange inclined surface allows foreign substances and fluid to flow easily.
- The slit of taper sleeve (one place) is protected with rubber plate to prevent invasion of cutting chips.

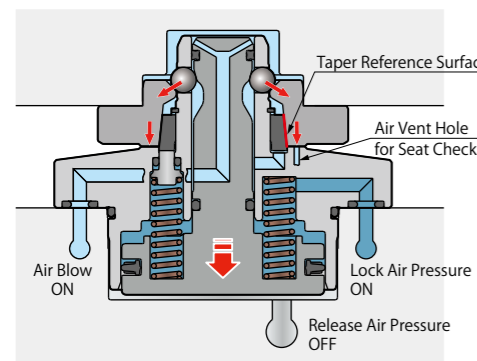
After Loading Pallet



When Loading Pallet

- When loading the pallet,
- The pallet is set on the raised piston rod cap.
- At this time there is clearance between the datum surfaces allowing air flow to remove contaminants. This allows to effectively remove chips and cutting oil by the air blow.
- When unloading the pallet,
- The close contacting of taper seating surface is released with lift-up force.

When Unloading Pallet



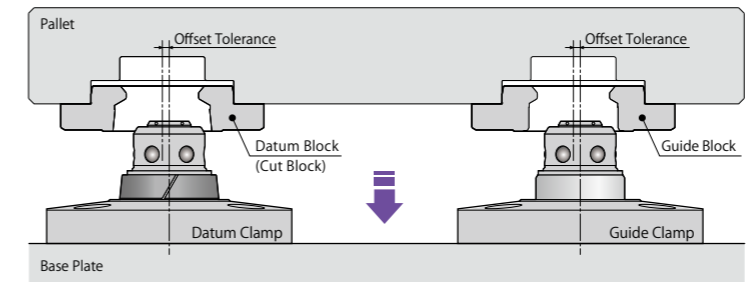
When Clamping

- When release air pressure is OFF and lock air pressure is ON, the air pressure and spring force lowers the piston rod and the steel balls engage the block bringing it to the seating surface.
- The pallet is positioned with high accuracy via the taper sleeve as it contacts the taper surface of the block.
- The seating surface includes an air vent for seat check (via air catch sensor).

When Clamping

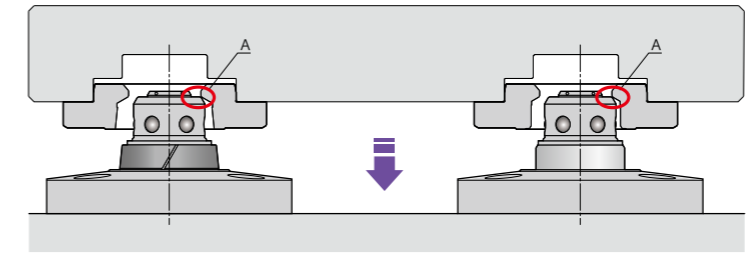
● Action Description during Loading/Unloading

1. Air pressure releases the clamp. Position of pallet while loading must be kept within the offset tolerance.

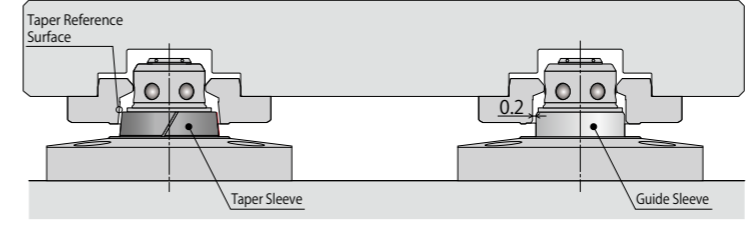


It is recommended to use rough guides to contain the pallet within the offset tolerance.

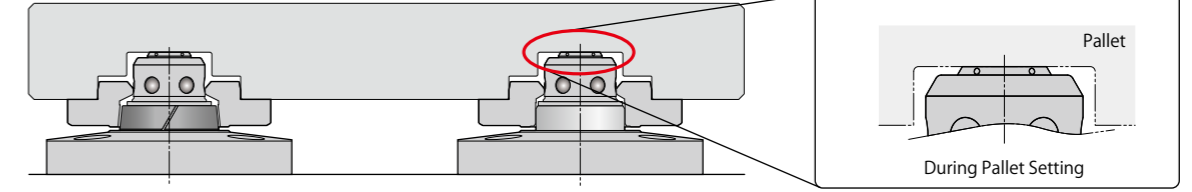
2. When the pallet is lowered, it should be positioned so the blocks contact the rod as shown on A.



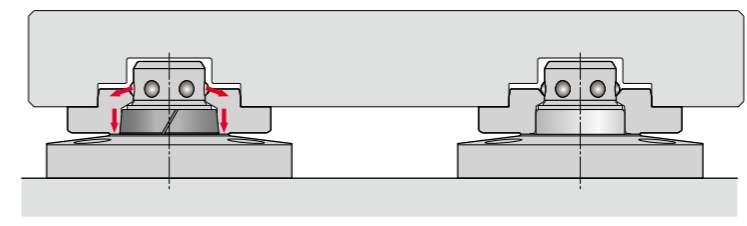
3. As the pallet is further lowered, it is positioned within 0.2mm of the reference axis via the guide sleeve and guide block. (Guide Function) Clearance between the datum clamp and taper reference surface created by guide function prevents interference.



4. Loading is finished when pallet is resting on piston rod. At this time, the appropriate clearance between seating surface and taper reference is created by lift up function, which makes it thus more effective that the cutting chips are removed by air blow.



5. When release air pressure is OFF and lock air pressure is ON, the block is pressed on the seating surface with air pressure and spring force. When the block is pressed, the taper reference surface is contacted for locating.



Locating + Clamp

Locating

Clamp

Support

Valve · Coupler

Cautions · Others

Robotic Hand Changer

SWR

Pneumatic Location Clamp

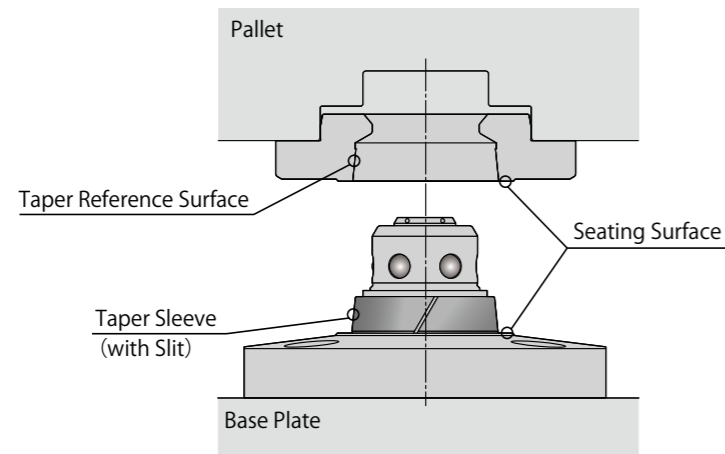
SWT

High-Power Pneumatic Pallet Clamp

WVS

● Description of Movable Taper Sleeve

Locating Method: Dual Surface with Movable Taper Sleeve

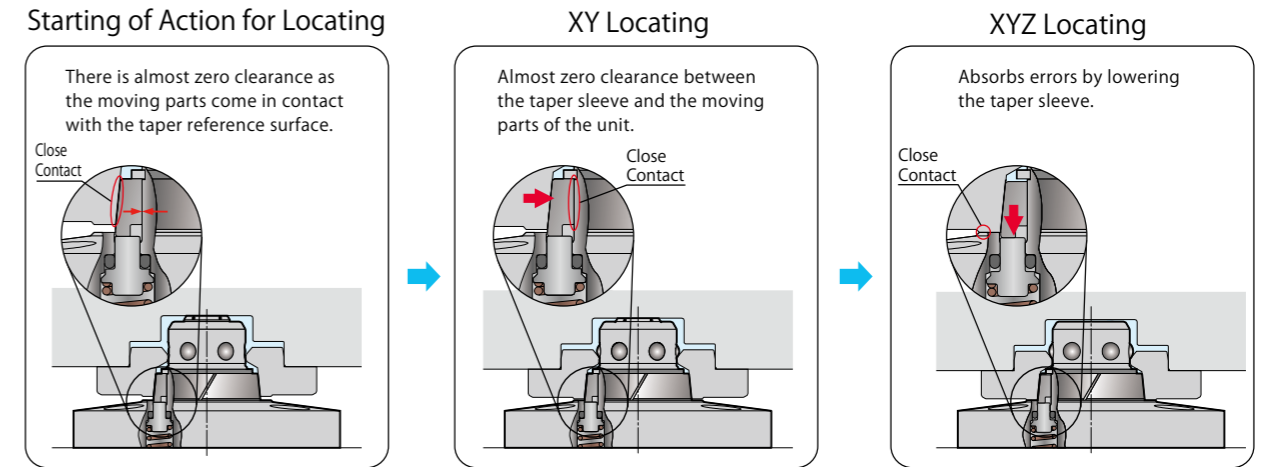


The Benefits of Movable Taper Sleeve

With marginal error absorbed by the movable taper sleeve, the clearance between the clamp, taper sleeve and block is eliminated enabling the repetitive location accuracy and stabilized clamping force.

- ① Absorbs tolerance variations in each location clamp and block.
- ② Absorbs wear of locating part due to long time use.
- ③ Absorbs space variations of mounting holes.
- ④ Absorbs space variations due to temperature change.

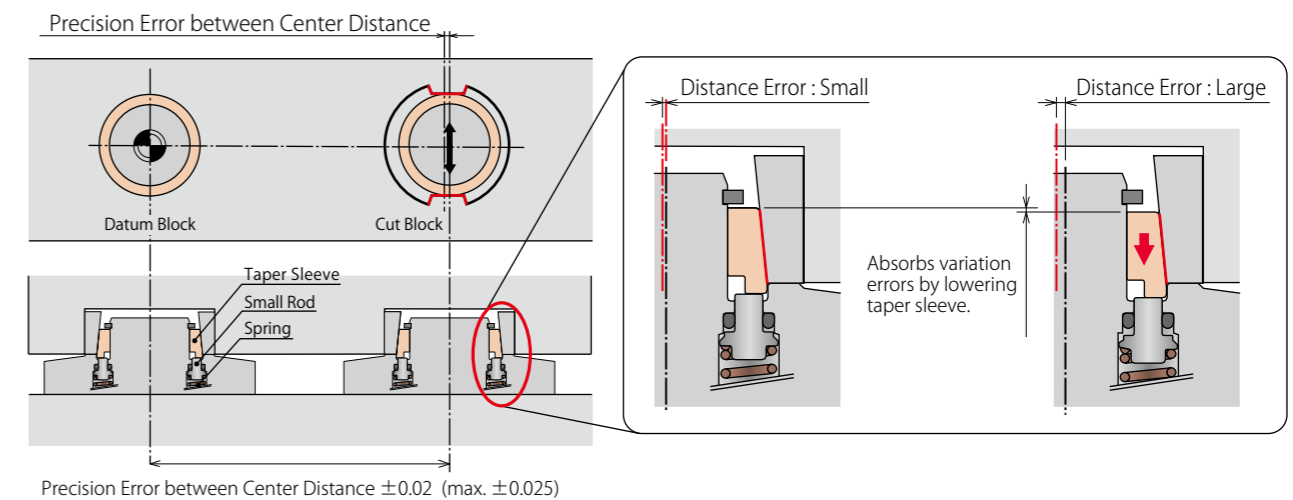
Movement and Error Absorbed by the Movable Taper Sleeve (①/②)



Movable taper sleeve absorbs distance error. (③/④)

Absorbs distance variations minimizing the wear of locating parts and prevents deformation of clamp/block.

※The precision assurance function is absolutely necessary especially when plates are transported or multiple fixture changeovers are needed.



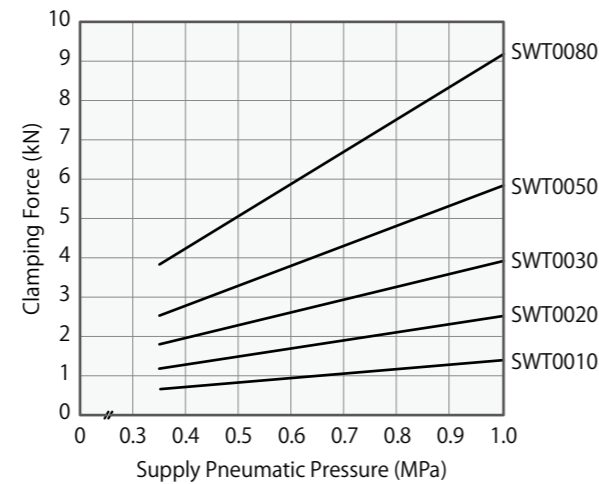
Model No. Indication (Clamp)

SWT 0 **03** 0 - M **D**

1      2      3

1 Clamping Force

- 01 : Clamping Force 0.8kN (Pneumatic Pressure 0.5MPa)
  - 02 : Clamping Force 1.5kN (Pneumatic Pressure 0.5MPa)
  - 03 : Clamping Force 2.3kN (Pneumatic Pressure 0.5MPa)
  - 05 : Clamping Force 3.3kN (Pneumatic Pressure 0.5MPa)
  - 08 : Clamping Force 5.1kN (Pneumatic Pressure 0.5MPa)
- ※ Refer to clamping force.  
Refer to Performance Curve and Specification for detail.

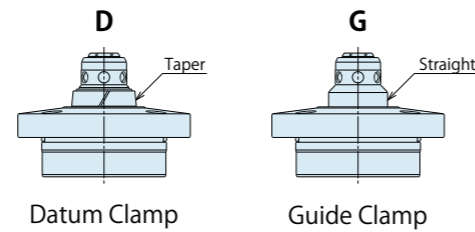


2 Design No.

0 : Revision Number

3 Functions

- D : Datum Clamp (Especially Used for Locating)
- G : Guide Clamp (Especially Used for Guide)



Combination of Clamp and Block

Clamp Model No.	Block Model No.	Function
SWT-MD (Datum Clamp)	SWTB□-D / SWTJ□-D (Datum Block)	Clamping + Locating at a Reference Point
SWT-MD (Datum Clamp)	SWTB□-C / SWTJ□-C (Cut Block)	Clamping + One Direction Locating
SWT-MG (Guide Clamp)	SWTB□-G / SWTJ□-G (Guide Block)	Clamping + Guide
SWT-M□ (Datum / Guide Clamp)	SWTB□-F / SWTJ□-F (Free Block)	Clamping

Note  
1. Please refer to the following "SWT-SWTB/SWTJ Block Compatible Lists" for the detailed form of the combination.

SWT—SWTB/SWTJ Block Compatible Lists

Clamp Model No.	SWT0010	SWT0020	SWT0030	SWT0050	SWT0080
SWT Block Model No. (Material : SUS)	SWTB010 SWTJ010	SWTB020 SWTJ020	SWTB030 SWTJ030	SWTB050 SWTJ050	SWTB080 SWTJ080
WVS Block Model No. (Material : SCM)	-	VSB020 VSJ020	VSB060 VSJ060	VSB100 VSJ100	VSB160 VSJ160

Note  
1. Please refer to the above "Combination of Clamp and Block" for functions.

Model No. Indication (Block)

SWTB : Embedded Block

SWTB **03** 0 - **D**

1      2      3      4

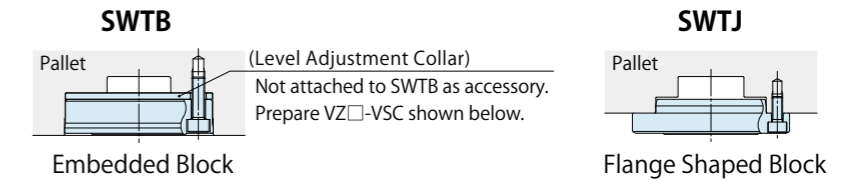
SWTJ : Flange Shaped Block

SWTJ **03** 0 - **D**

1      2      3      4

1 Shape of Block

- SWTB : Embedded Block
- SWTJ : Flange Shaped Block



2 Accommodate SWT Clamp Model

- 01 : SWT0010
- 02 : SWT0020
- 03 : SWT0030
- 05 : SWT0050
- 08 : SWT0080

3 Design No.

0 : Revision Number

4 Functions

- D : Datum Block (Especially Used for Reference Locating)
- C : Cut Block (Especially Used for One Direction Locating)
- G : Guide Block (Especially Used for Guide)
- F : Free Block (Shared by Multiple Pallets with Different Sizes)

Model No. Indication (Level Adjustment Spacer)

※ This product is only for the embedded block of SWTB.  
※ Material : Equal to S45C

Other Mounting Examples (Reference)

※ Please contact us for mounting methods as shown in the drawing below.

VZ 0 **06** 0 - VSC

1      2



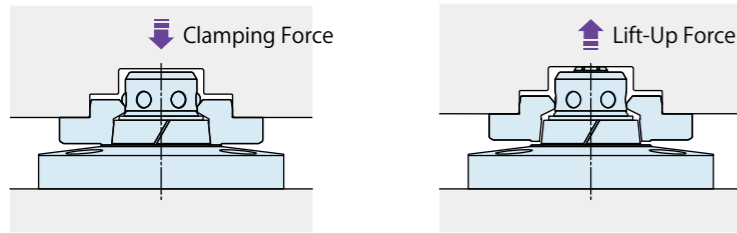
1 Accommodate SWTB Block Model No.

- 01 : SWTB010-□
- 02 : SWTB020-□
- 06 : SWTB030-□
- 10 : SWTB050-□
- 16 : SWTB080-□

2 Design No.

0 : Revision Number

Clamping Force / Lift-Up Force

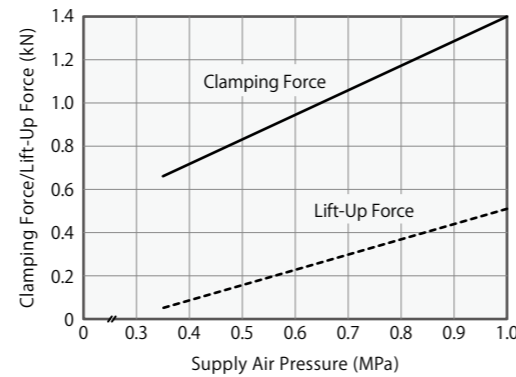


Notes

- This graph shows the value for single clamp.
  - This graph shows the relationship between Supply Air Pressure and Clamping Force (solid line) / Lift-Up Force (dotted line).
- ※1. It shows holding force at 0MPa air pressure and does not satisfy specifications.

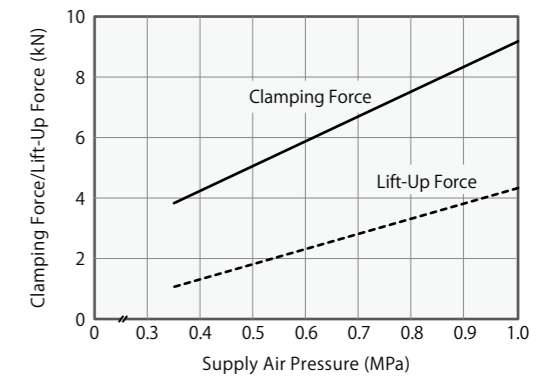
SWT0010-M□

Supply Air Pressure (MPa)	Clamping Force (kN)	Lift-Up Force (kN)
1.0	1.40	0.51
0.9	1.29	0.44
0.8	1.17	0.37
0.7	1.06	0.30
0.6	0.94	0.23
0.5	0.83	0.16
0.4	0.72	0.08
Holding Force at 0 MPa ※1	0.4	-
Operating Pressure Range (MPa)	0.35 ~ 1.0	



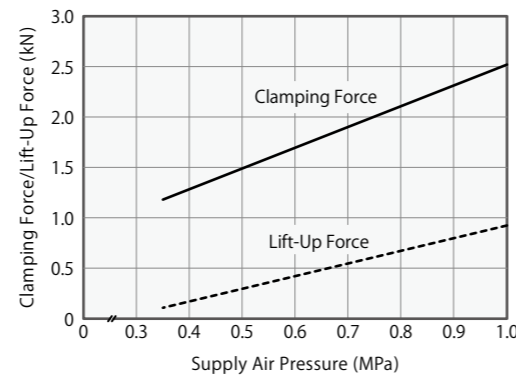
SWT0080-M□

Supply Air Pressure (MPa)	Clamping Force (kN)	Lift-Up Force (kN)
1.0	9.18	4.33
0.9	8.36	3.83
0.8	7.53	3.33
0.7	6.71	2.82
0.6	5.89	2.32
0.5	5.06	1.82
0.4	4.24	1.31
Holding Force at 0 MPa ※1	1.5	-
Operating Pressure Range (MPa)	0.35 ~ 1.0	



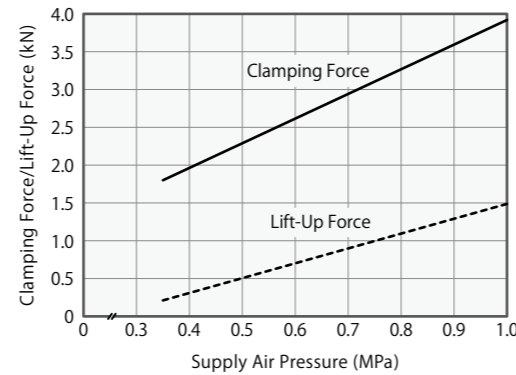
SWT0020-M□

Supply Air Pressure (MPa)	Clamping Force (kN)	Lift-Up Force (kN)
1.0	2.52	0.92
0.9	2.31	0.80
0.8	2.11	0.67
0.7	1.90	0.55
0.6	1.70	0.42
0.5	1.49	0.30
0.4	1.28	0.17
Holding Force at 0 MPa ※1	0.7	-
Operating Pressure Range (MPa)	0.35 ~ 1.0	



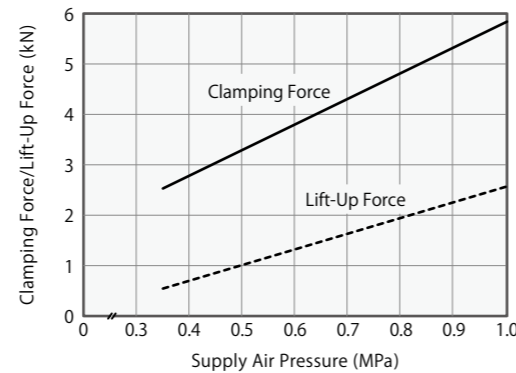
SWT0030-M□

Supply Air Pressure (MPa)	Clamping Force (kN)	Lift-Up Force (kN)
1.0	3.92	1.49
0.9	3.59	1.29
0.8	3.27	1.09
0.7	2.94	0.90
0.6	2.62	0.70
0.5	2.29	0.51
0.4	1.96	0.31
Holding Force at 0 MPa ※1	1.0	-
Operating Pressure Range (MPa)	0.35 ~ 1.0	

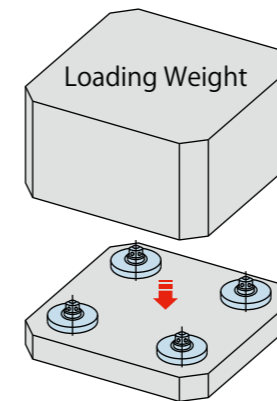


SWT0050-M□

Supply Air Pressure (MPa)	Clamping Force (kN)	Lift-Up Force (kN)
1.0	5.84	2.57
0.9	5.33	2.26
0.8	4.82	1.95
0.7	4.31	1.64
0.6	3.80	1.32
0.5	3.29	1.01
0.4	2.78	0.70
Holding Force at 0 MPa ※1	1.4	-
Operating Pressure Range (MPa)	0.35 ~ 1.0	



Loading Weight



Standard loading weight is  $\text{Lift-Up Force} \times \text{Number of Clamps} \times 0.8$  and it should be less than the maximum loading weight.

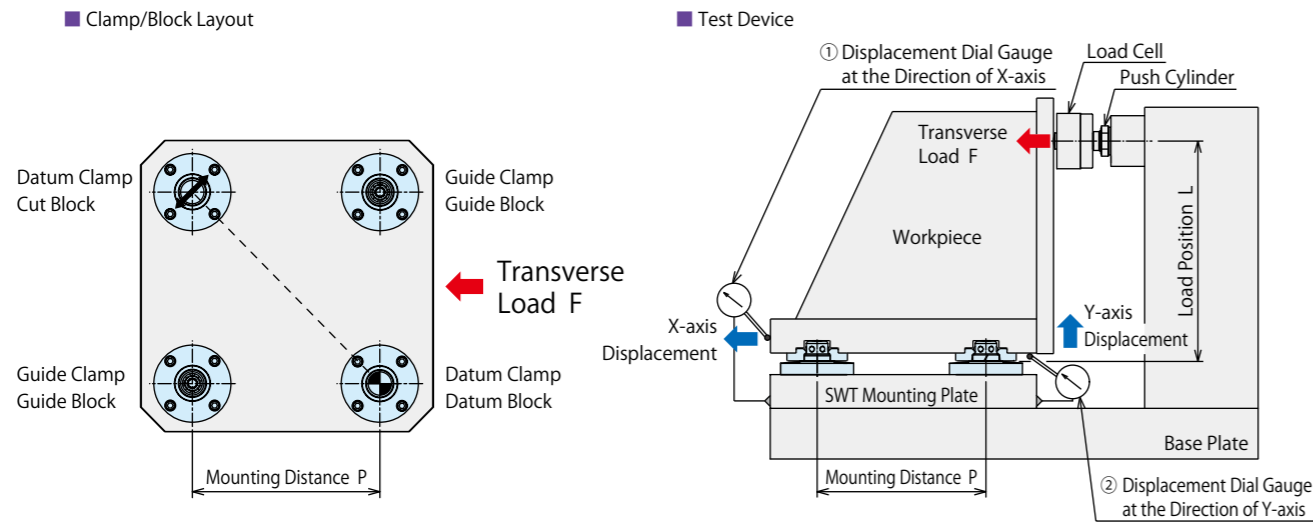
Model No.	SWT0010-M□	SWT0020-M□	SWT0030-M□	SWT0050-M□	SWT0080-M□	
Maximum Loading Weight ※2	kg	200	400	600	800	1200

Note

- ※2. It indicates the weight of pallet in horizontal position (placed flat) that SWT can locate regardless of number of clamps. Release air pressure is determined with the loading weight (fixture). (Loading weight should be less than 80% of the lift-up force (Number of Clamps×Lift-Up Force)). When using pallet in vertical direction, please refer to P.69.

### Displacement against Transverse Load

※ The displacement is the predicted reference value based on the test data under the conditions shown below.  
 Displacement may vary according to conditions of fixtures. The displayed values are reference based on the test data.



#### How to Read Displacement

(Ex.) When using SWT0010

##### Components

- [Clamp]**
  - SWT0010-MD×2 Units
  - SWT0010-MG×2 Units
- [Block]**
  - SWTJ010-D×1 Unit
  - SWTJ010-C×1 Unit
  - SWTJ010-G×2 Units

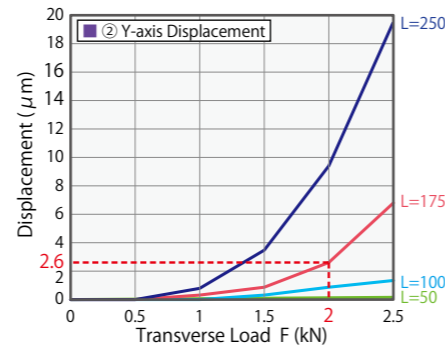
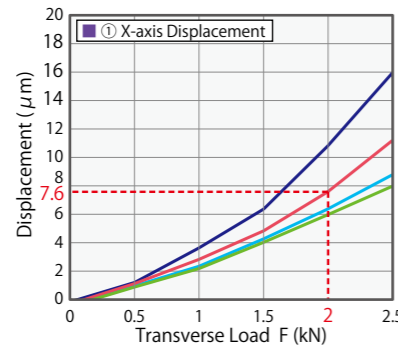
- Conditions**
  - Mounting Distance P=120mm
  - Load Position L=175mm
  - Supply Air Pressure 0.5MPa
  - Transverse Load F=2kN

##### Displacement

- ① X-axis displacement is about 7.6 μm.
- ② Y-axis displacement is about 2.6 μm.

##### Note

1. Please contact us in case the conditions are different.

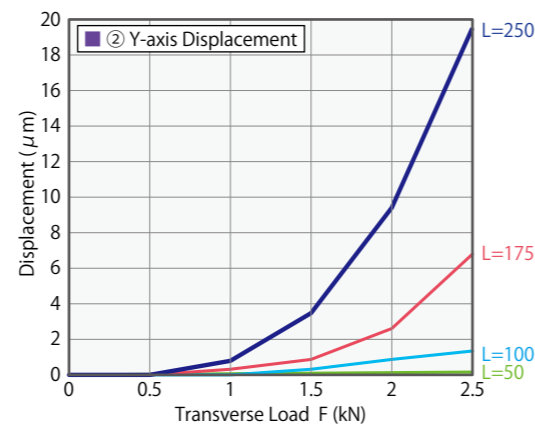
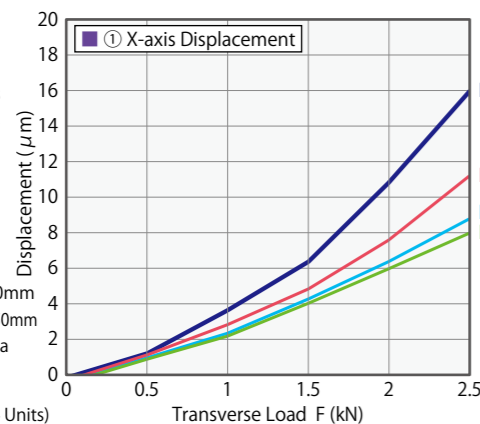


#### SWT0010

- Components**
  - [Clamp]**
    - SWT0010-MD×2 Units
    - SWT0010-MG×2 Units
  - [Block]**
    - SWTJ010-D×1 Unit
    - SWTJ010-C×1 Unit
    - SWTJ010-G×2 Units

- Conditions**
  - Mounting Distance P=120mm
  - Load Position L=50~250mm
  - Supply Air Pressure 0.5MPa

- Clamping Force**
  - Total 3.3kN (0.83kN×4 Units)

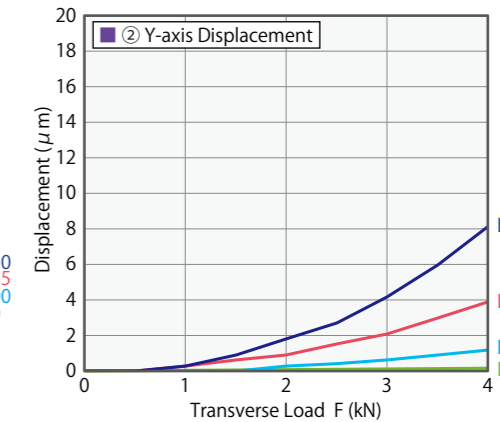
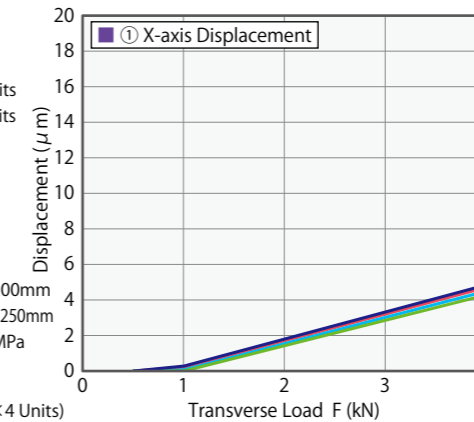


#### SWT0020

- Components**
  - [Clamp]**
    - SWT0020-MD×2 Units
    - SWT0020-MG×2 Units
  - [Block]**
    - SWTJ020-D×1 Unit
    - SWTJ020-C×1 Unit
    - SWTJ020-G×2 Units

- Conditions**
  - Mounting Distance P=200mm
  - Load Position L=50~250mm
  - Supply Air Pressure 0.5MPa

- Clamping Force**
  - Total 6.0kN (1.49kN×4 Units)

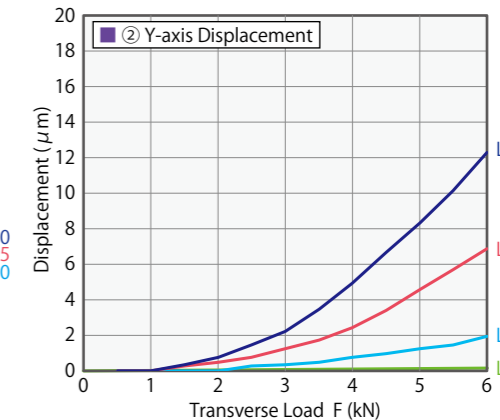
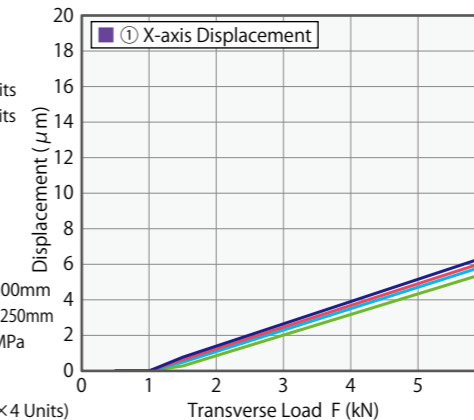


#### SWT0030

- Components**
  - [Clamp]**
    - SWT0030-MD×2 Units
    - SWT0030-MG×2 Units
  - [Block]**
    - SWTJ030-D×1 Unit
    - SWTJ030-C×1 Unit
    - SWTJ030-G×2 Units

- Conditions**
  - Mounting Distance P=200mm
  - Load Position L=50~250mm
  - Supply Air Pressure 0.5MPa

- Clamping Force**
  - Total 9.2 kN (2.29kN×4 Units)

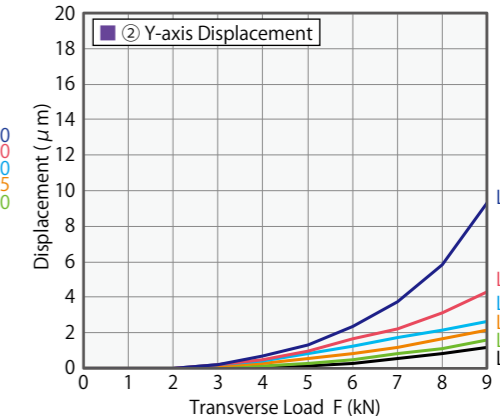
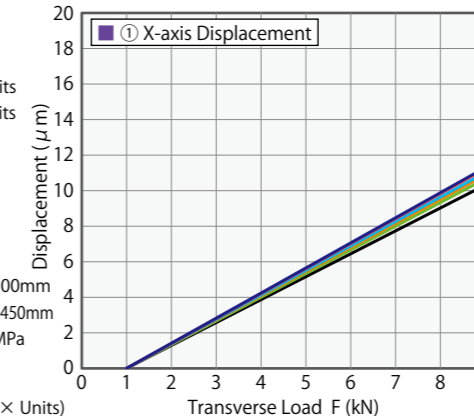


#### SWT0050

- Components**
  - [Clamp]**
    - SWT0050-MD×2 Units
    - SWT0050-MG×2 Units
  - [Block]**
    - SWTJ050-D×1 Unit
    - SWTJ050-C×1 Unit
    - SWTJ050-G×2 Units

- Conditions**
  - Mounting Distance P=300mm
  - Load Position L=50~450mm
  - Supply Air Pressure 0.5MPa

- Clamping Force**
  - Total 13.2kN (3.29kN×4 Units)

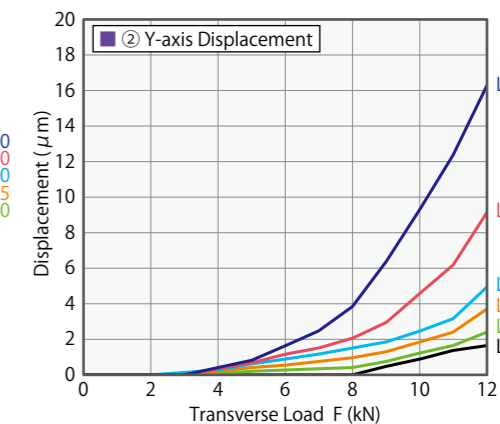
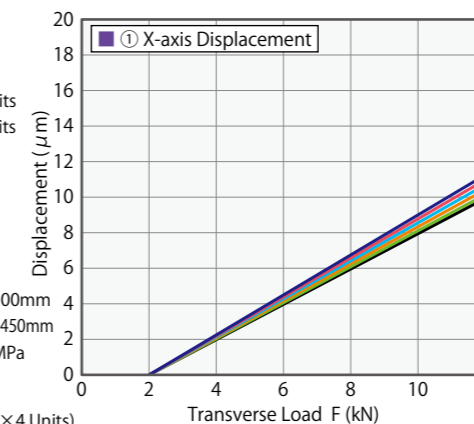


#### SWT0080

- Components**
  - [Clamp]**
    - SWT0080-MD×2 Units
    - SWT0080-MG×2 Units
  - [Block]**
    - SWTJ080-D×1 Unit
    - SWTJ080-C×1 Unit
    - SWTJ080-G×2 Units

- Conditions**
  - Mounting Distance P=300mm
  - Load Position L=50~450mm
  - Supply Air Pressure 0.5MPa

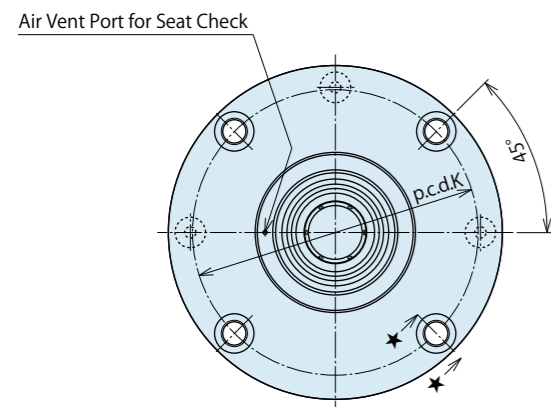
- Clamping Force**
  - Total 20.2kN (5.06kN×4 Units)



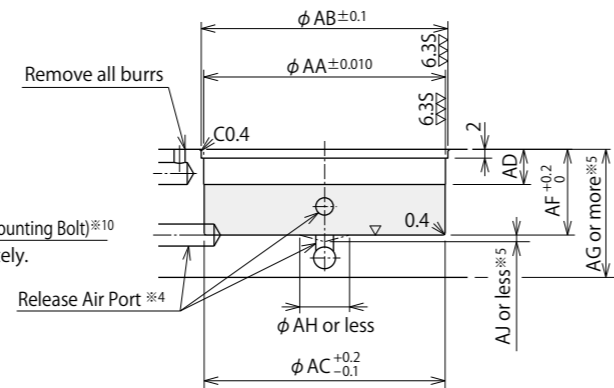
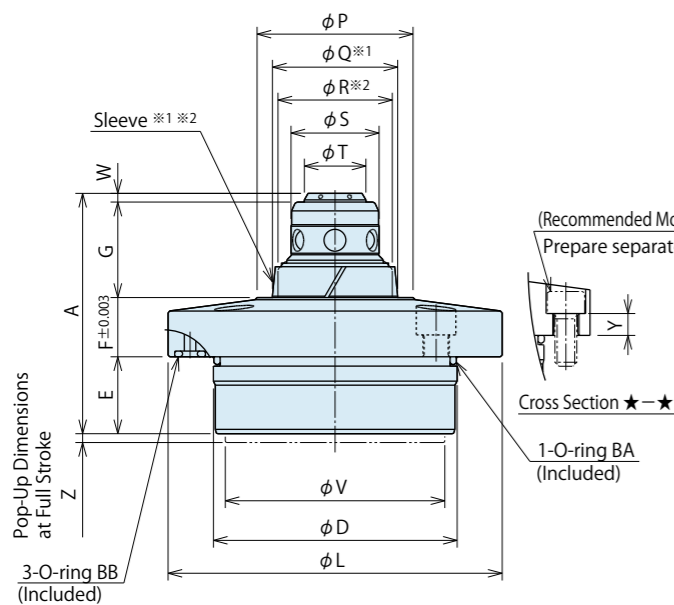
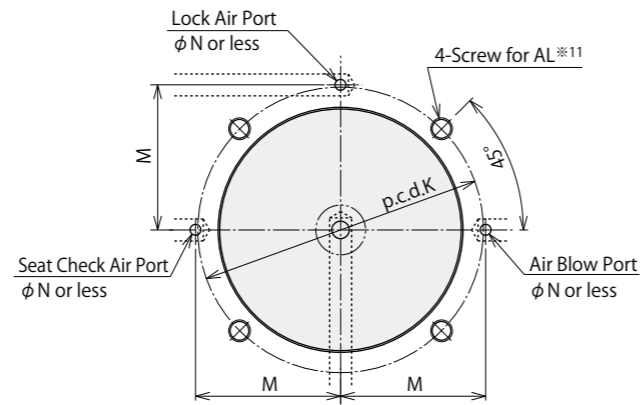
- Locating + Clamp
- Locating
- Clamp
- Support
- Valve · Coupler
- Cautions · Others
- Robotic Hand Changer
- SWR
- Pneumatic Location Clamp
- SWT
- High-Power Pneumatic Pallet Clamp
- WVS

External Dimensions

※This drawing shows the released state of SWT.



Machining Dimensions of Mounting Area



- Notes
- Remove all burrs around the hole intersection.
  - The release air port is within  $\square$  range.
  - The base thickness (AG) and remaining depth after boring (AJ) are reference values when the base material is S50C.

Specifications

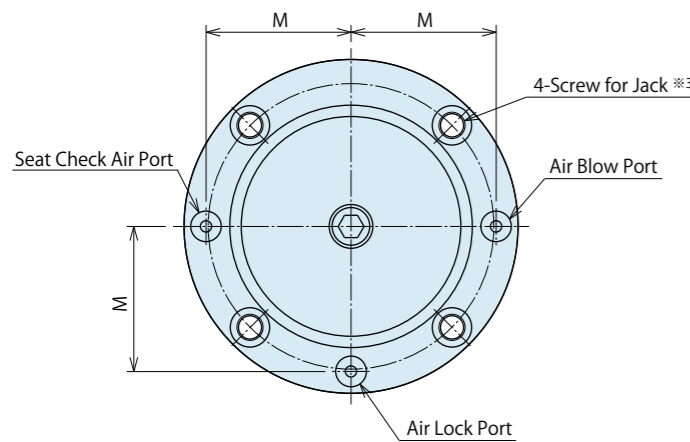
Model No.	SWT0010-M□	SWT0020-M□	SWT0030-M□	SWT0050-M□	SWT0080-M□	
Locating Repeatability	mm 0.003					
Full Stroke	2.8	3.4	3.4	4.0	4.5	
Lift Up Stroke	mm 1.0					
Offset Tolerance when fixture pallet is set	1.0	1.0	1.5	1.5	1.5	
Max. Loading Weight ※8	200	400	600	800	1200	
Cylinder Capacity ※7	Lock	1.79	3.88	6.14	11.33	20.58
	Release	1.98	4.27	6.68	12.47	22.62
Holding Force at 0 MPa ※7 ※9	kN 0.4, 0.7, 1.0, 1.2, 1.5					
Max. Operating Pressure	MPa 1.0					
Min. Operating Pressure	MPa 0.35					
Withstanding Pressure	MPa 1.5					
Air Blow Pressure	MPa 0.4~0.5					
Operating Temperature	°C 0~70					
Usable Fluid	Dry Air					
Mass※7	0.25	0.5	0.8	1.3	2.5	

- Notes
- The specifications per one unit.
  - It indicates the weight of pallet in horizontal position (placed flat) that SWT can locate regardless of number of clamps. Release air pressure is determined with the loading weight (fixture). (Loading weight should be less than 80% of the lift-up force (Number of Clamps×Lift-Up Force)). When using pallet in vertical direction, please refer to P.69.
  - It shows holding force at 0MPa air pressure and does not satisfy specifications.

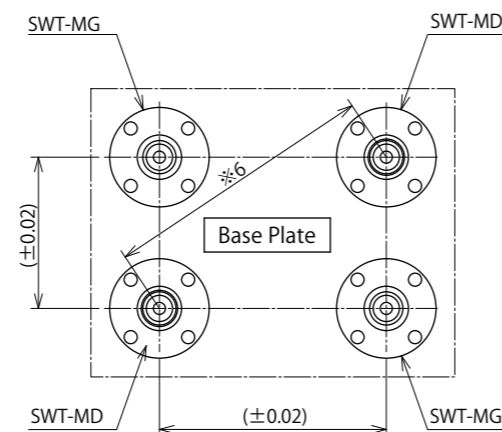
External Dimensions and Machining Dimensions for Mounting

Model No.	SWT0010-M□	SWT0020-M□	SWT0030-M□	SWT0050-M□	SWT0080-M□	
A	42.3	51.7	54.7	62.2	71.2	
D	SWT-MD	34.5 <sup>+0.030</sup> / <sub>+0.011</sub>	45 <sup>+0.030</sup> / <sub>+0.011</sub>	55 <sup>+0.030</sup> / <sub>+0.011</sub>	69 <sup>+0.030</sup> / <sub>+0.011</sub>	87.5 <sup>+0.030</sup> / <sub>+0.011</sub>
	SWT-MG	34.5 <sup>0</sup> / <sub>-0.020</sub>	45 <sup>0</sup> / <sub>-0.020</sub>	55 <sup>0</sup> / <sub>-0.020</sub>	69 <sup>0</sup> / <sub>-0.020</sub>	87.5 <sup>0</sup> / <sub>-0.020</sub>
E	13.1	16	17.5	18	20	
F	10	12	13.5	16	20	
G	17.8	21.7	21.7	26.5	29.5	
K	44	55	65	81	102.5	
L	53	66	76	94	118.5	
M	22	28	33	41	51.5	
N	2	2.5	2.5	3	5	
P	26	32	35.5	44	51	
Q	20	25	28.5	36	42	
R	17.8	22.5	26	32.3	38.3	
S	14	18	20	26	32	
T	9	12	14	18.8	22.4	
V	30	40	50	63	80	
W	1.4	2	2	1.7	1.7	
Y ※11	4.3	4	5	6	8.2	
Z	1.4	2	2	2	3	
AA	34.5	45	55	69	87.5	
AB	34.7	45.2	55.2	69.2	87.7	
AC	34.3	44.8	54.8	68.8	87.3	
AD	8	8	8	9	10	
AF	14.5	18	19.5	20	23	
AG	18	22	24	25	28	
AH	7	9	11	14	17	
AJ	2.5	2.5	2.5	2.5	2.5	
AL (Nominal×Pitch×Depth) ※11	M4×0.7×8 or more	M5×0.8×10 or more	M5×0.8×10 or more	M6×1×10 or more	M8×1.25×14 or more	
1-O-ring BA	AS568-026(70°)	AS568-030(70°)	AS568-033(70°)	AS568-037(70°)	AS568-042(70°)	
3-O-ring BB	AS568-005(70°)	AS568-007(70°)	AS568-007(70°)	1AP5	1AP7	
(Recommended Mounting Bolt) ※10	M4×0.7×10 or more	M5×0.8×12 or more	M5×0.8×12 or more	M6×1×14 or more	M8×1.25×20 or more	
Screw for Jack	M5×0.8	M6×1	M6×1	M8×1.25	M10×1.5	

- Notes
- Mounting bolt is not included. Please prepare it separately. (Refer to P.67 for further information.)
  - Determine AL thread depth for mounting bolt according to 'Y' dimension.



Distance Accuracy of Each Clamp

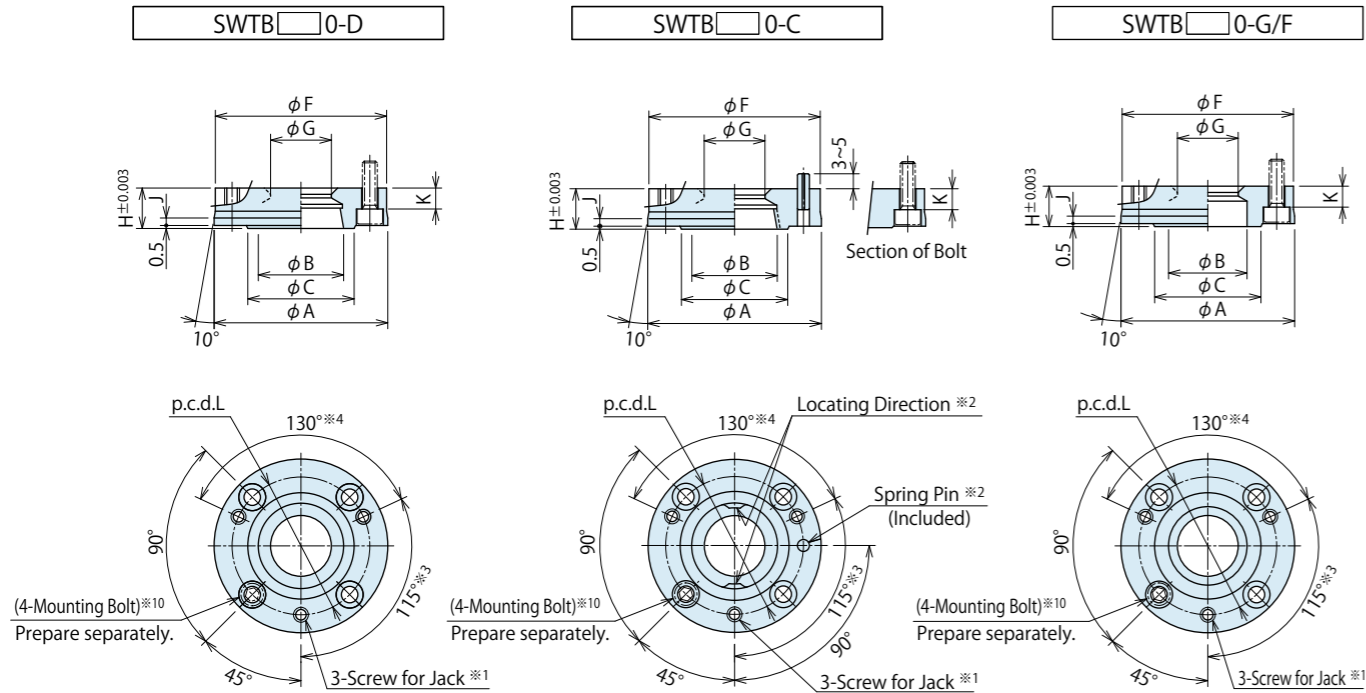


- Note
- Please make sure the distance accuracy of each datum clamp is below  $\pm 0.025$ mm between the clamps with the longest distance.

- Notes
- φ Q shows the dimensions of sleeve (taper) of datum clamp (SWT-MD).
  - φ R shows the dimensions of sleeve (straight) of guide clamp (SWT-MG).
  - The screw for jack is used when removing the clamp. (See P.70 for usage.)

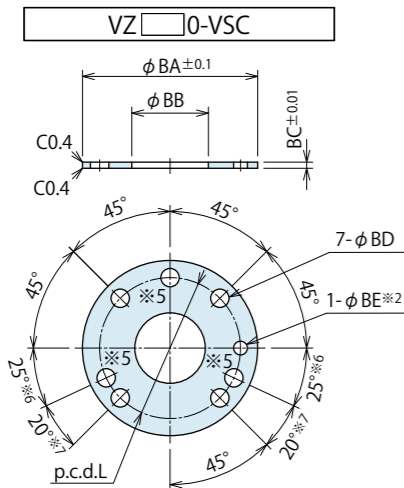


External Dimensions



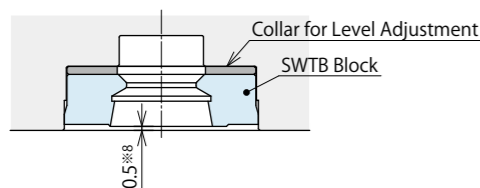
- Notes
- ※1. The screw for jack is used when removing SWTB block.
  - ※2. The spring pin is used for phasing of SWTB-C locating direction.
  - ※3. 114° for SWTB010-□
  - ※4. 132° for SWTB010-□

Dimensions of Collar for Level Adjustment



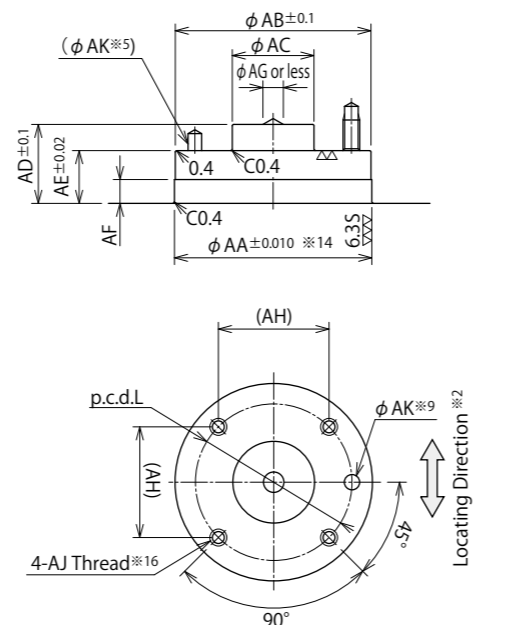
- Notes
- Please refer to the drawing above in case the collar for level adjustment is prepared by yourself.
  - (3 parts) are for jack screw. Align them with the phase of jack screw of SWTB block.
  - 24° for VZ0010-VSC
  - 21° for VZ0010-VSC

※Mounting of Collar for Level Adjustment.



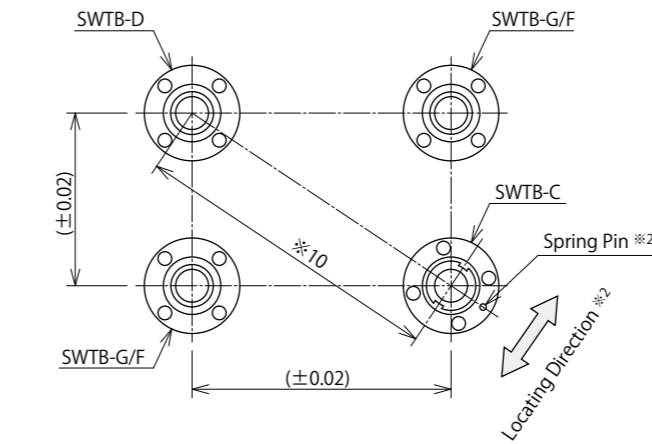
※8. Clearance between the seating area of SWTB block and block bottom.

Machining Dimensions of Mounting Area



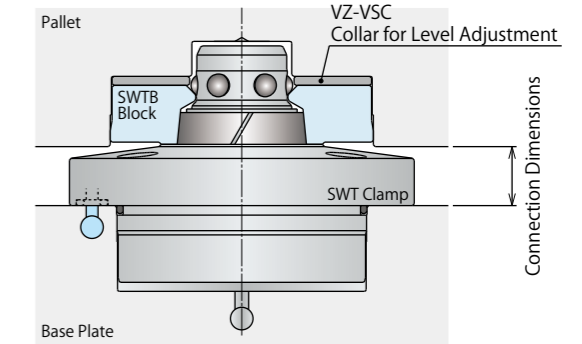
- Notes
- This drawing shows the case where the clearance between the seating area of SWTB block and pallet bottom is 0.5mm when the collar for level adjustment is used.
  - phi AK hole is used for phasing of SWTB-C positioning direction. Please make sure phi AK hole is at the line connecting the centers of SWTB-D and SWTB-C. This machining is only necessary for SWTB-C.

Mounting Distance Accuracy and SWTB-C Phase



Note  
※10. Please make sure the precision between block pitches is within ±0.025mm between the blocks with the longest distance.

Connection Dimensions



External Dimensions and Machining Dimensions for Mounting

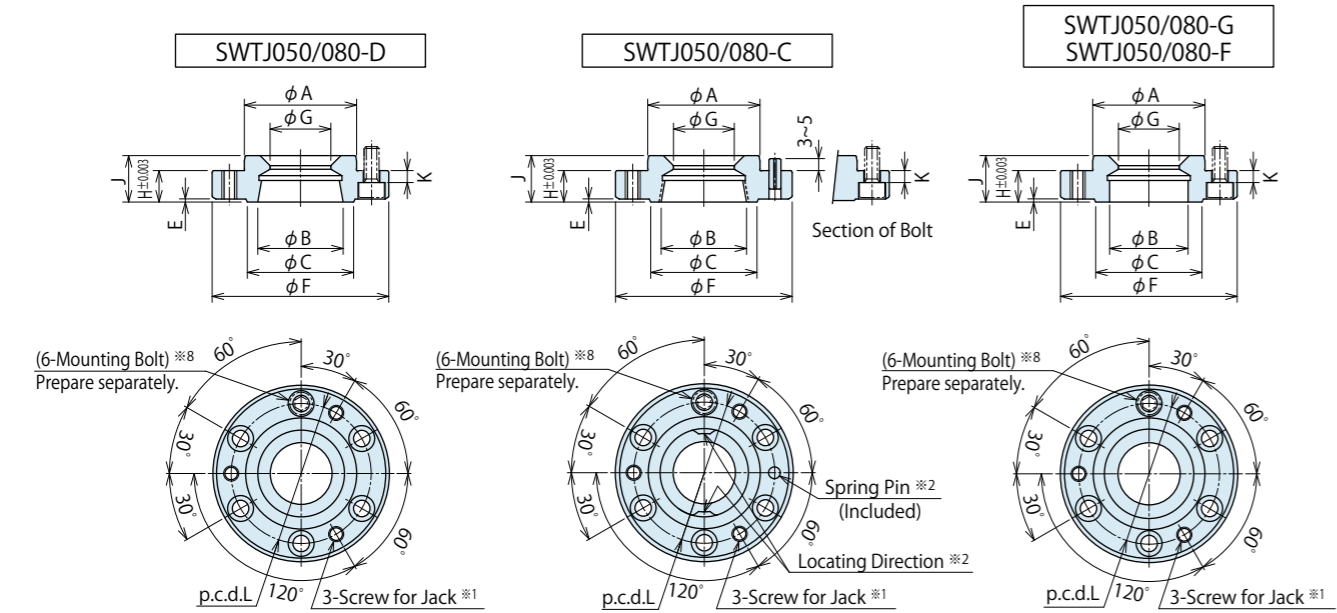
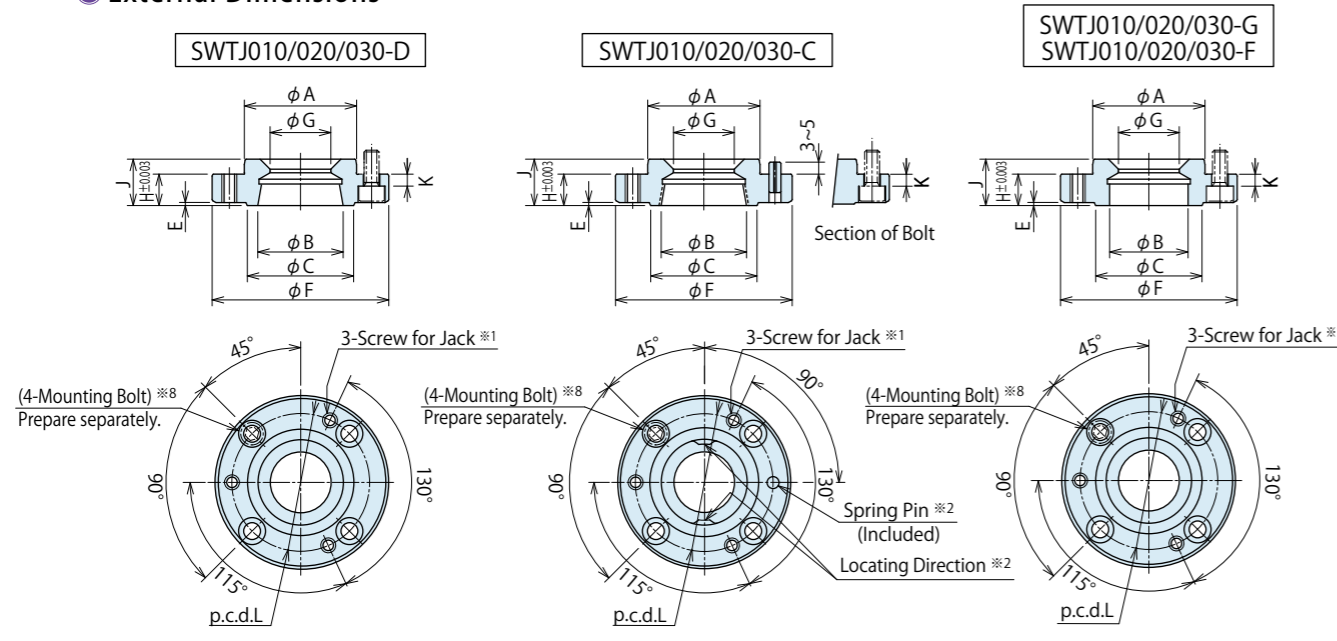
Model No.	SWTB010-D SWTB010-C	SWTB010-G SWTB010-F	SWTB020-D SWTB020-C	SWTB020-G SWTB020-F	SWTB030-D SWTB030-C	SWTB030-G SWTB030-F	SWTB050-D SWTB050-C	SWTB050-G SWTB050-F	SWTB080-D SWTB080-C	SWTB080-G SWTB080-F
A	43 <sup>+0.027</sup> / <sub>+0.011</sub>	43g7 <sup>-0.009</sup> / <sub>-0.034</sub>	50 <sup>+0.027</sup> / <sub>+0.011</sub>	50g7 <sup>-0.009</sup> / <sub>-0.034</sub>	58m6 <sup>+0.030</sup> / <sub>+0.011</sub>	58g7 <sup>-0.010</sup> / <sub>-0.040</sub>	70m6 <sup>+0.030</sup> / <sub>+0.011</sub>	70g7 <sup>-0.010</sup> / <sub>-0.040</sub>	83m6 <sup>+0.035</sup> / <sub>+0.013</sub>	83g7 <sup>-0.012</sup> / <sub>-0.047</sub>
B	20	18 (20.5) <sup>※11</sup>	25	22.7 (25.5) <sup>※11</sup>	28.5	26.2 (29) <sup>※11</sup>	36	32.5 (36.5) <sup>※11</sup>	42	38.5 (42.5) <sup>※11</sup>
C	26	32	32	35.5	44	51	44	49.2	51	51
F	42.5	49.2	49.2	57.2	69.2	82.2	69.2	82.2	82.2	82.2
G	14.25	18.3	18.3	20.3	26.3	32.3	26.3	32.3	32.3	32.3
H	10	13	13	13	16.5	17.5	16.5	17.5	17.5	17.5
J	2.5	2.5	2.5	2.5	2.5	3	2.5	3	3	3
K	5	8	8	7	9.5	8.5	9.5	8.5	8.5	8.5
L	34	40	40	46	56	66	56	66	66	66
AA <sup>※14</sup>	43	50	50	58	70	83	70	83	83	83
AB	42.8	49.5	49.5	57.5	69.5	82.5	69.5	82.5	82.5	82.5
AC	18	22	22	24	30	36	30	36	36	36
AD	18.7	23.2	23.2	23.2	27.7	30.7	27.7	30.7	30.7	30.7
AE	12.5	15.5	15.5	15.5	20	21	20	21	21	21
AF	6	7	7	7	8	8	8	8	8	8
AG	3	3	3	3	5	5	5	5	5	5
(AH)	24.04	28.28	28.28	32.53	39.6	46.67	39.6	46.67	46.67	46.67
AJ (Nominal×Pitch×Depth) <sup>※16</sup>	M4×0.7×6 or more	M4×0.7×7 or more	M4×0.7×7 or more	M5×0.8×8 or more	M6×1×10 or more	M8×1.25×14.5 or more	M4×0.7×6 or more	M4×0.7×7 or more	M5×0.8×8 or more	M6×1×10 or more
AK	phi 3.4 Depth 5	-	phi 3.4 Depth 5	-	phi 4.5 Depth 5	-	phi 4.5 Depth 5	-	phi 4.5 Depth 5	-
(Recommended Mounting Bolt) <sup>※15</sup>	M4×0.7×12	M4×0.7×16	M4×0.7×16	M5×0.8×16	M6×1×20	M8×1.25×25	M4×0.7×12	M4×0.7×16	M5×0.8×16	M6×1×20
Screw for Jack	M4×0.7	M4×0.7	M4×0.7	M5×0.8	M6×1	M8×1.25	M4×0.7	M4×0.7	M5×0.8	M6×1
Spring Pin <sup>※12</sup>	phi 3×10	-	phi 3×10	-	phi 4×10	-	phi 4×10	-	phi 4×10	-
Mass	0.08 kg	0.15 kg	0.15 kg	0.2 kg	0.35 kg	0.5 kg	0.08 kg	0.15 kg	0.15 kg	0.2 kg
Appropriate Clamp	SWT0010-MD SWT0010-MG <sup>※13</sup>	SWT0020-MD SWT0020-MG <sup>※13</sup>	SWT0020-MD SWT0020-MG <sup>※13</sup>	SWT0030-MD SWT0030-MG <sup>※13</sup>	SWT0050-MD SWT0050-MG <sup>※13</sup>	SWT0080-MD SWT0080-MG <sup>※13</sup>	SWT0010-MD SWT0010-MG <sup>※13</sup>	SWT0020-MD SWT0020-MG <sup>※13</sup>	SWT0030-MD SWT0030-MG <sup>※13</sup>	SWT0050-MD SWT0050-MG <sup>※13</sup>
Connection Dimensions	When Lock: 9.5 When Release: 10.5	11.5 12.5	11.5 12.5	13 14	15.5 16.5	19.5 20.5	9.5 10.5	11.5 12.5	13 14	15.5 16.5

Model	VZ0010-VSC	VZ0020-VSC	VZ0060-VSC	VZ0100-VSC	VZ0160-VSC
BA	42.5	49.2	57.2	69.2	82.2
BB	19	23	25	32	38
BC	2	2	2	3	3
BD	5	5	6	7.5	10
BE	3.4	3.4	4.5	4.5	4.5
Mass	0.016 kg	0.021 kg	0.03 kg	0.062 kg	0.085 kg

- Notes
- Material of SWTB Block : SUS, Material of VZ□-VSC Level Adjustment Collar : Equivalent to S45C
  - The dimensions in ( ) display that of SWTB-F.
  - The spring pin is included only in SWTB-C.
  - The guide block (SWTB-G) is used only for guide clamp (SWT□-MG) and the free block (SWTB-F) can be used for both datum clamp (SWT□-MD) and guide clamp (SWT□-MG).
  - Pallet with low rigidity (thin pallet or pallet made of aluminum etc.) may be deformed when mounting SWTB block. In this case, tolerance of mounting hole machining dimension AA±0.010 should be close to +0.010 (the upper limit of the tolerance).
  - Mounting bolt is not included. Please prepare it separately. (Refer to P.67 for further information.)
  - Determine AJ thread depth for mounting bolt according to 'K' and 'BC' dimension.

Locating + Clamp  
Locating  
Clamp  
Support  
Valve · Coupler  
Cautions · Others  
Robotic Hand Changer  
SWR  
Pneumatic Location Clamp  
SWT  
High-Power Pneumatic Pallet Clamp  
WVS

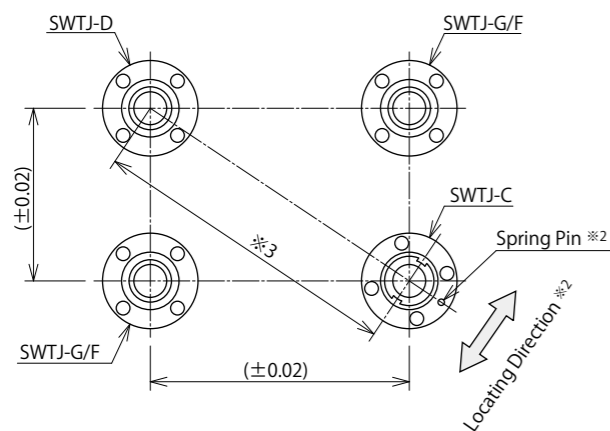
External Dimensions



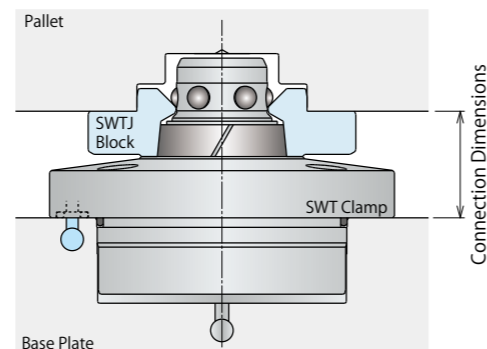
Notes

- ※1. The screw for jack is used when removing SWTJ block.
- ※2. The spring pin is used for phasing of SWTJ-C locating direction.

Mounting Distance Accuracy and SWTJ-C Phase



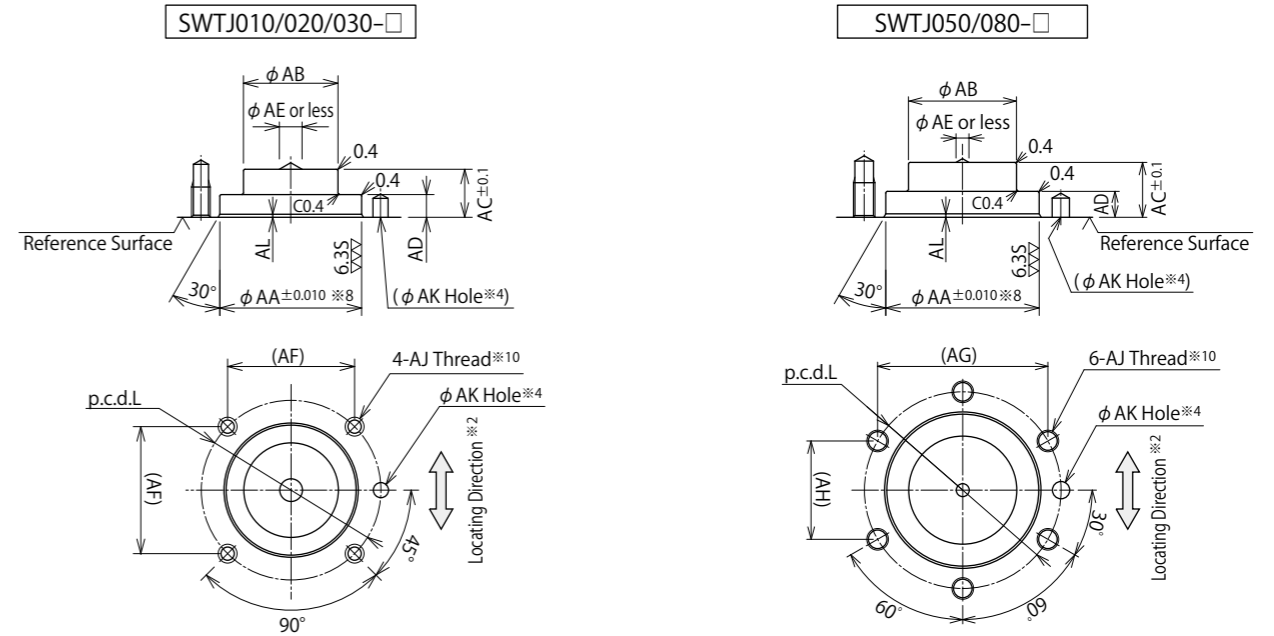
Connection Dimensions



Note

- ※3. Please make sure the precision between block pitches is within ±0.025mm between the blocks with the longest distance.

Machining Dimensions of Mounting Area



Notes

- ※4. φ AK hole is used for phasing of SWTJ-C positioning direction. Please make sure φ AK hole is at the line connecting the centers of SWTJ-D and SWTJ-C. This machining is only necessary for SWTJ-C.

External Dimensions and Machining Dimensions for Mounting

Model No.	SWTJ010-D		SWTJ010-G		SWTJ020-D		SWTJ020-G		SWTJ030-D		SWTJ030-G		SWTJ050-D		SWTJ050-G		SWTJ080-D		SWTJ080-G		
	SWTJ010-C	SWTJ010-F	SWTJ020-C	SWTJ020-F	SWTJ030-C	SWTJ030-F	SWTJ050-C	SWTJ050-F	SWTJ080-C	SWTJ080-F	SWTJ080-C	SWTJ080-F									
A	26 +0.024 +0.011	26g7 -0.007 -0.028	31.5 +0.027 +0.011	31.5g7 -0.009 -0.034	37.5 +0.027 +0.011	37.5g7 -0.009 -0.034	52m6 +0.030 +0.011	52g7 -0.010 -0.040	62m6 +0.030 +0.011	62g7 -0.010 -0.040											
B	20	18 (20.5) <sup>※5</sup>	25	22.7 (25.5) <sup>※5</sup>	28.5	26.2 (29) <sup>※5</sup>	36	32.5 (36.5) <sup>※5</sup>	42	38.5 (42.5) <sup>※5</sup>											
C	26		32		35.5		44		51												
E	0.3		0.5		0.5		0.5		0.5												
F	43		49		59		74		89												
G	14.25		18.3		20.3		26.3		32.3												
H	7		8		10		10		12												
J	11		13		15		16.5		18.5												
K <sup>※10</sup>	2.5		3.3		4.2		4.2		5.2												
L	34		40		47.5		62.5		75												
AA <sup>※8</sup>	26		31.5		37.5		52		62												
AB	18		22		25		31		38												
AC	11.2		14.7		12.7		17.2		18.2												
AD	5		6		6		7.5		7.5												
AE	3		3		3		5		5												
(AF)	24.04		28.28		33.59		-		-												
(AG)	-		-		-		54.13		64.95												
(AH)	-		-		-		31.25		37.5												
AJ (Nominal×Pitch×Depth) <sup>※10</sup>	M4×0.7×7 or more		M4×0.7×8 or more		M5×0.8×9 or more		M5×0.8×9 or more		M6×1×10 or more												
AK	φ3.4 Depth 5	-	φ3.4 Depth 5	-	φ4.5 Depth 5	-	φ4.5 Depth 5	-	φ4.5 Depth 5	-											
AL	0.8		0.8		0.8		0.8		0.84												
(Recommended Mounting Bolt) <sup>※9</sup>	M4×0.7×8 or more		M4×0.7×10 or more		M5×0.8×12 or more		M5×0.8×12 or more		M6×1×14 or more												
Screw for Jack	M4×0.7		M4×0.7		M5×0.8		M5×0.8		M6×1												
Spring Pin <sup>※6</sup>	φ3×10	-	φ3×10	-	φ4×10	-	φ4×10	-	φ4×10	-											
Mass	0.07kg		0.1kg		0.18kg		0.3kg		0.55kg												
Appropriate Clamp	SWT0010-MD	SWT0010-MG	SWT0020-MD	SWT0020-MG	SWT0030-MD	SWT0030-MG	SWT0050-MD	SWT0050-MG	SWT0080-MD	SWT0080-MG											
Connection	When Lock	17	20	23.5	26	32															
Dimensions	When Release	18	21	24.5	27	33															

Notes

- 1. Material of SWTJ Block : SUS
- ※5. The dimensions in ( ) display that of SWTJ-F.
- ※6. The spring pin is included only in SWTJ-C.
- ※7. The guide block (SWTJ-G) is used only for guide clamp (SWT□-MG) and the free block (SWTJ-F) can be used for both datum clamp (SWT□-MD) and guide clamp (SWT□-MG).
- ※8. Pallet with low rigidity (thin pallet or pallet made of aluminum etc.) may be deformed when mounting SWTJ block. In this case, tolerance of mounting hole machining dimension AA±0.010 should be close to +0.010 (the upper limit of the tolerance).
- ※9. Mounting bolt is not included. Please prepare it separately. (Refer to P.67 for further information.)
- ※10. Determine AJ thread depth for mounting bolt according to 'K' dimension.

● Accessory : Pneumatic Location Clamp Mounting Bolt

Mounting bolts are not included in pneumatic location clamp (Model No. SWT/SWTB/SWTJ).  
If you require mounting bolts (Material : SCM Strength Grade 12.9), prepare the bolts shown below.  
(For SUS bolts etc., they should be prepared by customer.)

Model No. Indication

**SWZ** **03** **0** - **SWT** **1**

1 2 3



1 Applicable Model No.

- 01 : SWT0010, SWTB010, SWTJ010
- 02 : SWT0020, SWTB020, SWTJ020
- 03 : SWT0030, SWTB030, SWTJ030
- 05 : SWT0050, SWTB050, SWTJ050
- 08 : SWT0080, SWTB080, SWTJ080

2 Design No.

0 : Revision Number

3 Functions

- SWT** : A Set of Bolts for SWT (Clamp)
- SWTB** : A Set of Bolts for SWTB (Embedded Block)
- SWTJ** : A Set of Bolts for SWTJ (Flange Shaped Block)

Model No.	SWZ010-SWT1	SWZ020-SWT1	SWZ030-SWT1	SWZ050-SWT1	SWZ080-SWT1
Applicable Model	SWT0010-M□	SWT0020-M□	SWT0030-M□	SWT0050-M□	SWT0080-M□
Bolt Size	M4×0.7×10	M5×0.8×12	M5×0.8×12	M6×1×14	M8×1.25×20
Number of Bolts	4 (For One Clamp)				

Model No.	SWZ010-SWTB1	SWZ020-SWTB1	SWZ030-SWTB1	SWZ050-SWTB1	SWZ080-SWTB1
Applicable Model	SWTB010-□	SWTB020-□	SWTB030-□	SWTB050-□	SWTB080-□
Bolt Size	M4×0.7×12	M4×0.7×16	M5×0.8×16	M6×1×20	M8×1.25×25
Number of Bolts	4 (For One Block)				

Model No.	SWZ010-SWTJ1	SWZ020-SWTJ1	SWZ030-SWTJ1	SWZ050-SWTJ1	SWZ080-SWTJ1
Applicable Model	SWTJ010-□	SWTJ020-□	SWTJ030-□	SWTJ050-□	SWTJ080-□
Bolt Size	M4×0.7×8	M4×0.7×10	M5×0.8×12	M5×0.8×12	M6×1×14
Number of Bolts	4 (For One Block)			6 (For One Block)	

Notes

- 1. Material of Bolt : SCM (Strength Grade : 12.9)
- ※1. The number of bolts shows the quantity of bolts for one set.  
(Number of bolts per one set is required for mounting one clamp or one block.)  
(Ex. If you require SWT0020-MD (Clamp)×2 units, order 2 sets of SWZ020-SWT1.)

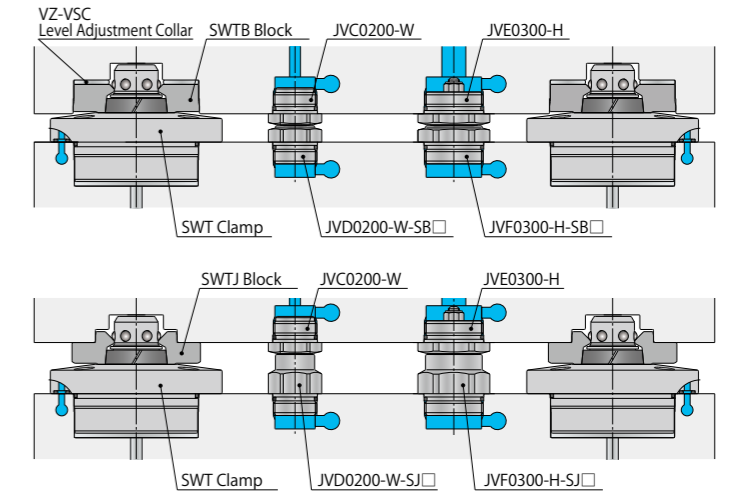
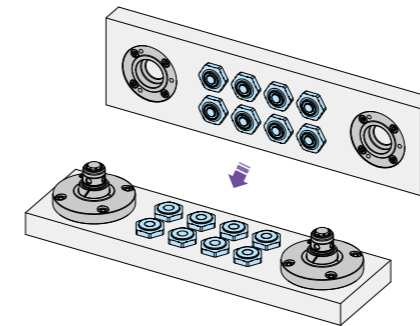
● Related Products

Auto Coupler (Oil/Air/Coolant) model JVC/JVD, JVE/JVF → P.329~P.336

Coupler with the minimum connection stroke enhances automation.  
Compact and able to install in limited spaces.

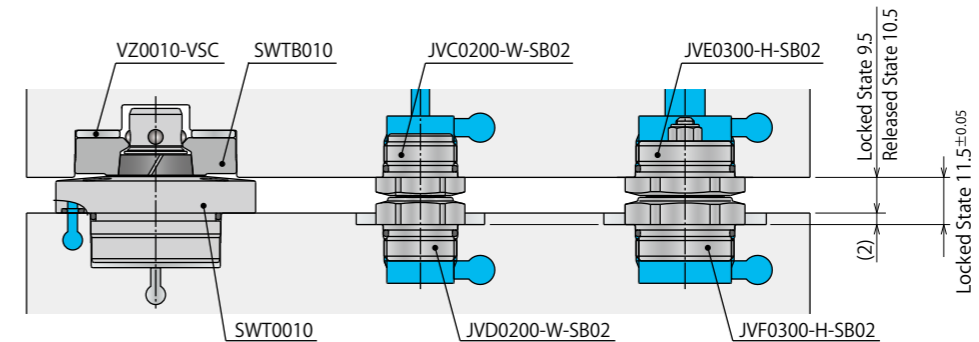


Image



Connection Reference when using SWTB010

Spot facing shown below is required only when using JVC/JVD, JVE/JVF with the combination of SWT0010 and SWTB010.



Locating + Clamp  
Locating  
Clamp  
Support  
Valve · Coupler  
Cautions · Others

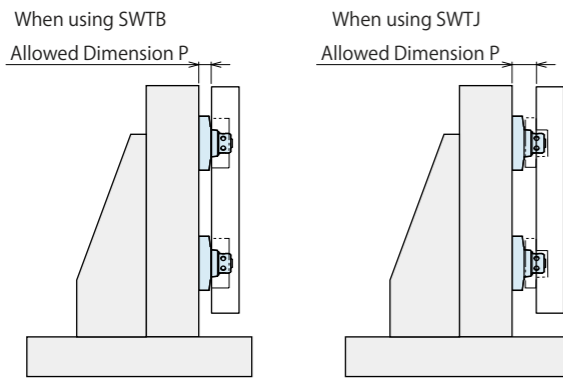
Robotic Hand Changer  
SWR

Pneumatic Location Clamp  
SWT  
High-Power Pneumatic Pallet Clamp  
WVS

**Cautions**

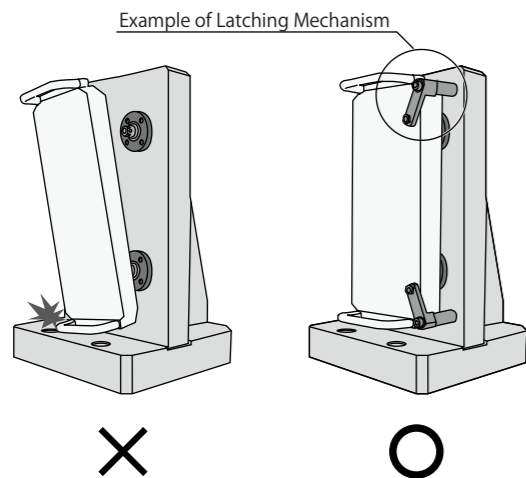
**Notes for Design**

- 1) Check Specifications
  - Please use each product according to the specifications.
- 2) Notes for Circuit Design
  - Never supply pressure simultaneously to lock and release ports. If incorrectly designed, the machine may malfunction, sustain damage or have reduced performance.
  - It is recommended to use the air flow path over  $\phi 6\text{mm}$ .
- 3) When the pallet is in vertical position.
  - When the workpiece · pallet is being set, make sure it is in proper proximity and square to the clamps.
  - If it is locked out of position, the machine or clamps may be damaged.



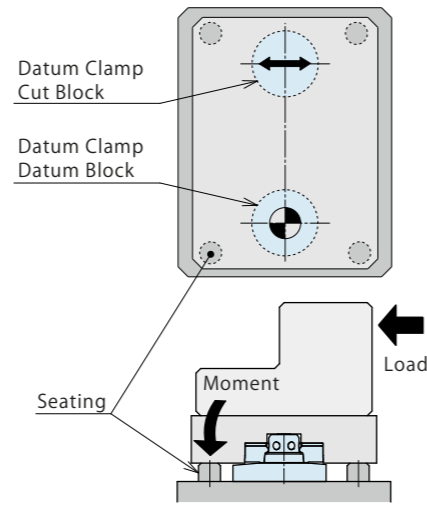
Model No.	SWT0010	SWT0020	SWT0030	SWT0050	SWT0080
SWTB Block	11	13	14.5	17	21
SWTJ Block	18.5	21.5	25	27.5	33.5

- As the workpiece · pallet may fall down during releasing, it is recommended to set up the latching mechanism to prevent it from falling down.
- When the pallet is used in vertical position (hanging on the wall), the internal moving parts tend to wear out. Confirm the positioning precision in a regular manner. In case the allowed range is exceeded, change the machine.

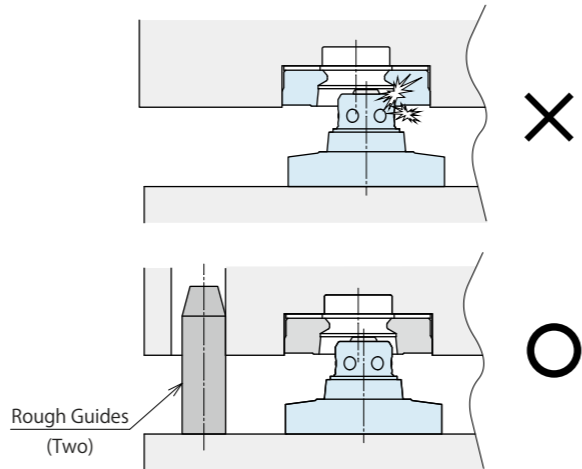


- When the pallet is in horizontal position (leveled), make sure the weight of the workpiece · pallet is less than the lift force of the clamps and maximum load of the machine.
- When the pallet is in vertical position, make sure the weight of workpiece · pallet is 10% of the clamping force.
- Please contact us in case the pallet is in other positions.

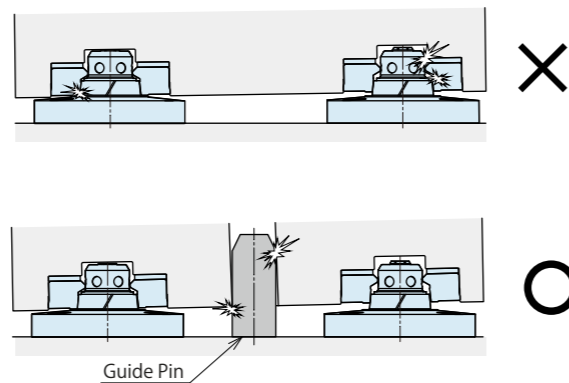
- 4) Seat Setting
  - In case the clamp/block configuration is linear, it is recommended to provide additional supports for stability.



- 5) Setting of Rough Guide
  - If the position of the pallet (fixture) during loading is outside the clamp offset tolerance, the clamp may prematurely contact the seating/taper surface of the block (SWTB/SWTJ-D) causing damage affecting locating precision. It is recommended to use rough guides to contain the pallet within the offset tolerance.



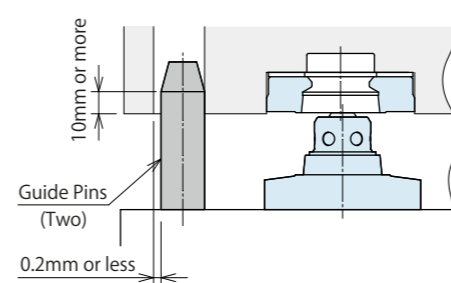
- The pallet must be level when lowering or lifting from the location clamps. If necessary, provide guide pins to keep the pallet level during loading and unloading.



- 6) Prepare a guide in case not using the guide block (SWTB/SWTJ-G).
  - The combination of guide clamp (SWT-G) and guide block (SWTB/SWTJ-G) ensures the protective function of datum clamp. The guide should be set up in case the guide block is not used in the applications below.

When only the combination of datum clamps (2) and datum block (SWTB/SWTJ-D) cut block (SWTB/SWTJ-C) is used.

When only the combination of datum clamp and free block (SWTB/SWTJ-F) is used to rotate the fixture plate.

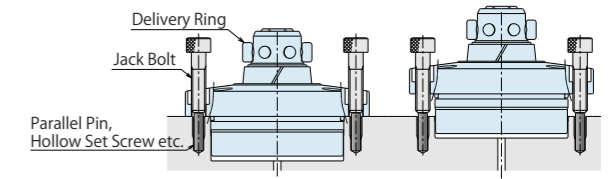


**Installation Notes**

- 1) Check the fluid to use.
  - Please supply filtered clean dry air.
  - Oil supply with a lubricator etc. is unnecessary.
- 2) Procedure before Piping
  - The pipeline, piping connector and fixture circuits should be cleaned and flushed thoroughly. The dust and cutting chips in the circuit may lead to fluid leakage and malfunction.
  - There is no filter provided with this product for prevention of contaminants in the air circuit.
- 3) Applying Sealing Tape
  - Wrap with tape 1 to 2 times following the screwing direction. Wrapping in the wrong direction will cause leaks and malfunction.
  - Pieces of the sealing tape can lead to air leaks and malfunction.
  - When piping, be careful that contaminant such as sealing tape does not enter in products.
- 4) Mounting the Body
  - Tighten hexagon socket bolts (Accessories : SWZ□0-□1 Mounting Bolt, SCM Bolt Strength Grade 12.9) with the torque shown in the chart below. Tighten them evenly to prevent twisting or jamming.

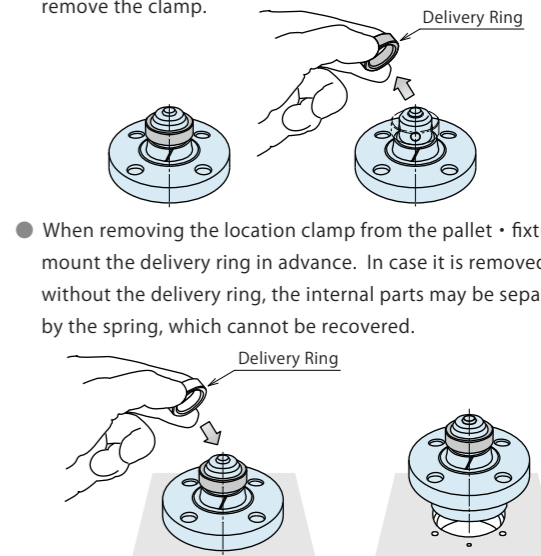
Clamp Model No.	Block Model No.	Thread Size	Tightening Torque (N·m)
SWT	SWTB	SWTJ	
SWT0010	SWTB010	SWTJ010	M4×0.7 3.2
SWT0020	SWTB020	SWTJ020	M5×0.8 6.3
SWT0030	SWTB030	SWTJ030	M5×0.8 6.3
SWT0050	SWTB050	SWTJ050	M6×1 10
SWT0080	SWTB080	SWTJ080	M8×1.25 25

- 5) Removal
  - Mount the delivery ring.
  - Use jack bolts to remove the clamp in parallel.
  - Protect the thread part with parallel pins as shown in the drawing below in order for the jack bolts not to damage the thread part of mounting bolt.



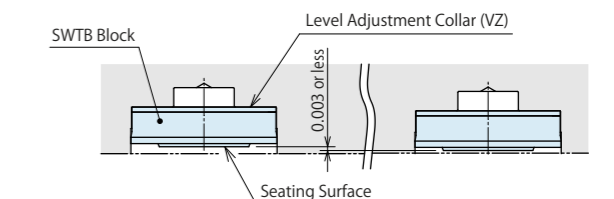
**6) Delivery Ring [Important]**

- The delivery ring is used to prevent separation of parts of individual clamps.
- The clamp will be equipped with a delivery ring for shipment. After the location clamp is mounted on the fixture, remove the delivery ring before use. (When the delivery ring is removed, ensure to supply the release pneumatic pressure.)
- Please take good care of the delivery ring as it is necessary to remove the clamp.



- 7) Level Adjustment of SWTB Block Seating Surface
  - When the pallet · fixture are assembled in the blocks, adjust the level of block seating surface in the way described below. (Recommended Level Adjustment: within  $\pm 0.003\text{mm}$ )

- ① Mount the level adjustment collar first and the block in the pallet · fixture, and tighten them with the specified torque.
- ② Measure the level of different block seating surfaces.
- ③ In case the levels are not even, remove the blocks, and grind the level adjustment collars so that the level range is within  $\pm 0.003\text{mm}$ .
- ④ Once again, assemble the block · level adjustment collar into the pallet · fixture and confirm the levels.



※ Please refer to P.363 for common cautions. · Notes on Handling · Maintenance/Inspection · Warranty

Locating + Clamp

Locating

Clamp

Support

Valve · Coupler

Cautions · Others

Robotic Hand Changer

SWR

Pneumatic Location Clamp

SWT

High-Power Pneumatic Pallet Clamp

WVS

# High-Power Pneumatic Pallet Clamp

Model WVS



## High Clamping Force with Built-in Mechanical Locking System

PAT.P.

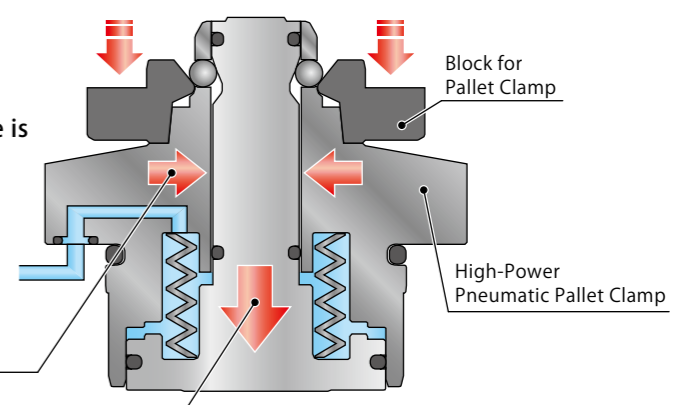
### • Strong Clamping Force

Available in four body sizes cylinder output force is

**4kN / 6kN / 10kN / 16kN**

Stronger Holding Force with **Mechanical Lock**

**With Mechanical Lock Function**  
Clamping Force which Replaces Hydraulic Clamp

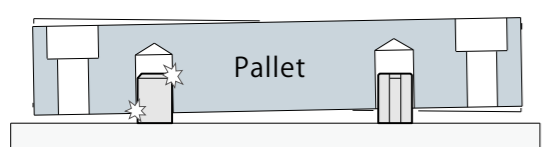


※Clamping force varies depending on the operating pressure.  
※This drawing is images. The parts constitution is different.

## Work Efficiency

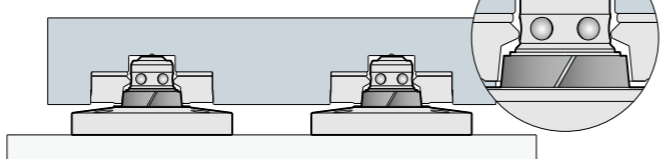
It is very difficult to position heavy pallets and plates on fixed pins. For pallet clamp, anyone can change fixtures with high accuracy. This enables smooth pallet loading/unloading. Suitable for Automatic Pallet Change with Robots.

Fixed Pin + Manual Tightening with Bolt

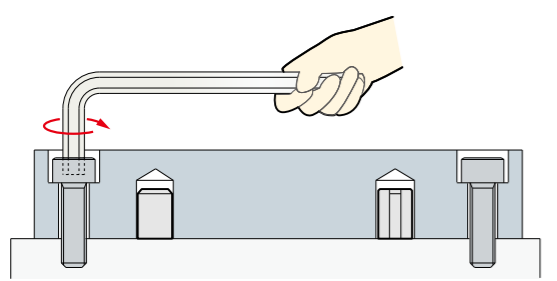


Difficult to Load • Apt to Get Stuck

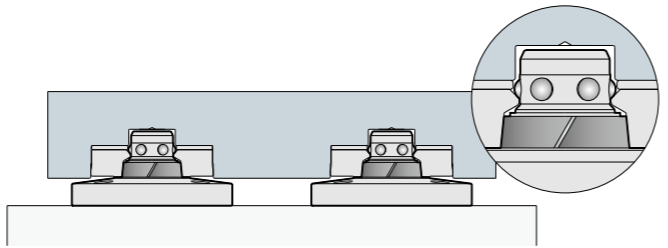
High-Power Pneumatic Pallet Clamp



Easy to Load (Suitable for Automation)



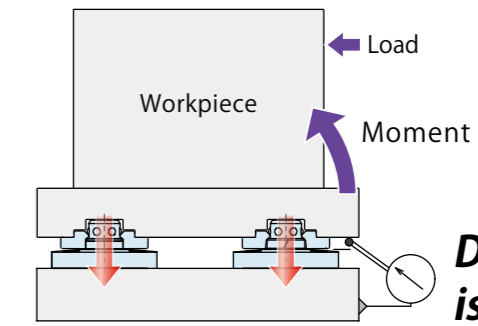
Manual Tightening Accuracy Correction Required



Locking in Mere Seconds  
No Accuracy Correction Required  
Locating Repeatability : 3 μm

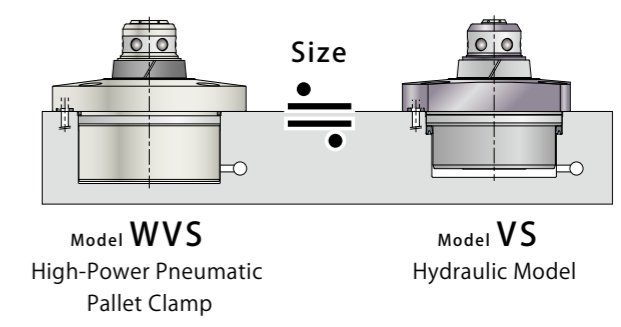
### • High Rigidity

Clamping force is suppressed to necessary minimum by the powerful holding force beyond clamping force.



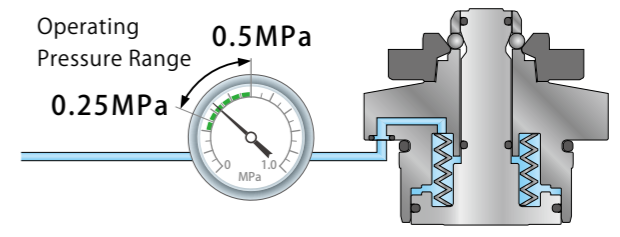
### • Compact

WVS is the same size as a hydraulic clamp (model VS). It withstands high cutting load.



### • Energy Saving

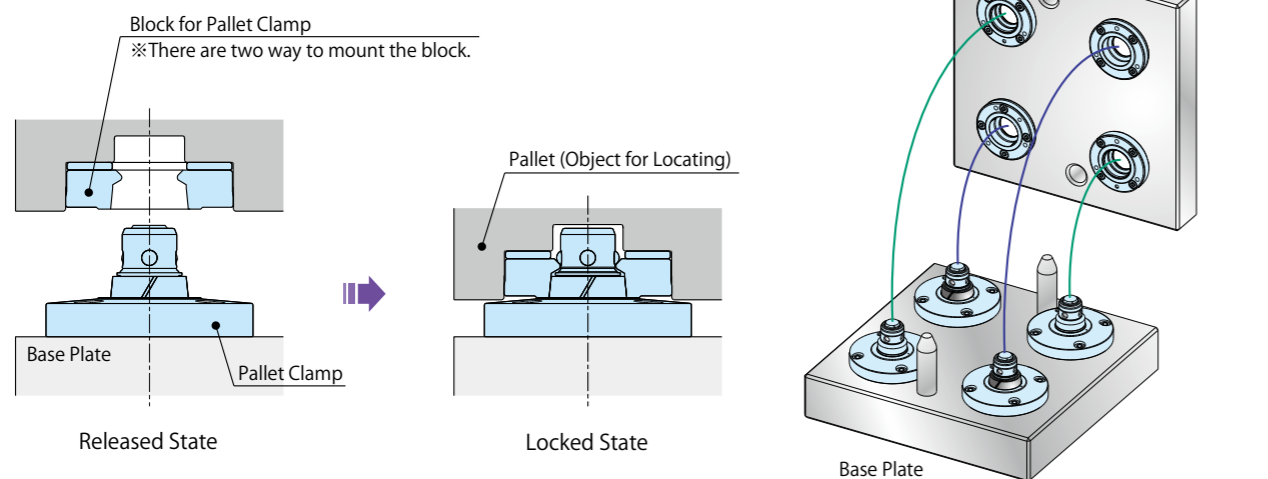
Higher clamping force achieved by low operating pressure. No need to use air booster.



- Locating + Clamp
- Locating
- Clamp
- Support
- Valve • Coupler
- Cautions • Others
- Robotic Hand Changer
- SWR
- Pneumatic Location Clamp
- SWT
- High-Power Pneumatic Pallet Clamp
- WVS

## Function Description

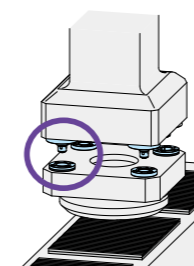
※Refer to the P.77 for detail.



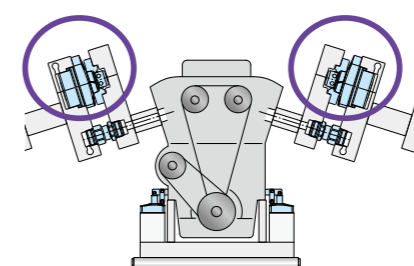
## Advantages

### Setup improvement enhances productivity.

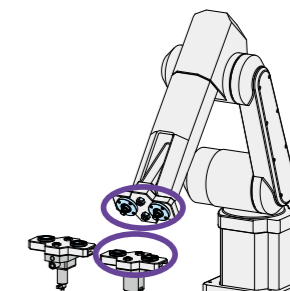
High-Power Pallet Clamp locates with high accuracy and clamps simultaneously. (Fixture alignment and inspection are eliminated.) Fixture change over is faster and easier, thus by eliminating alignment inspection for accuracy which is done in many different ways.



< Production Line of LCD Panels >



< Engine Test Device >

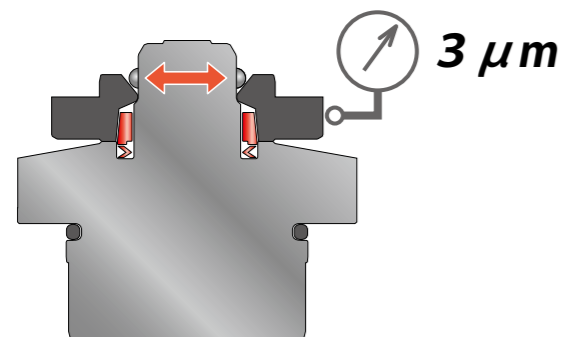


< Robot Tool Change Hand >

## Repetitive Locating with High Accuracy

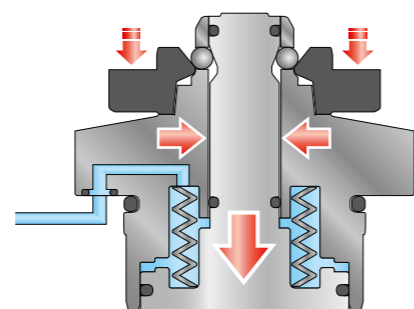
Locating Repeatability : 3 μm

Fixture alignment inspection is eliminated in the machining center.



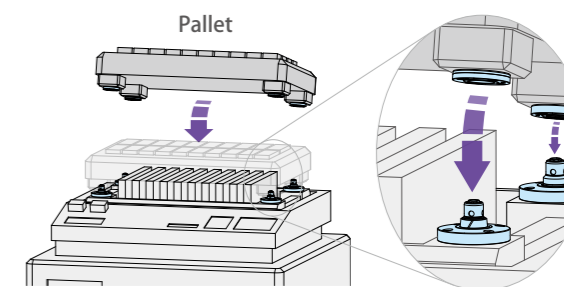
## Clamping Function

Clamping force is ranged from 2.4kN ~ 15.7kN. Strong clamping force.



### Efficient use of machine by eliminating non-productive time like fixture setting etc is done outside.

Since the fixture setting is outside, the machine idle time is reduced.



Manual Pallet Change

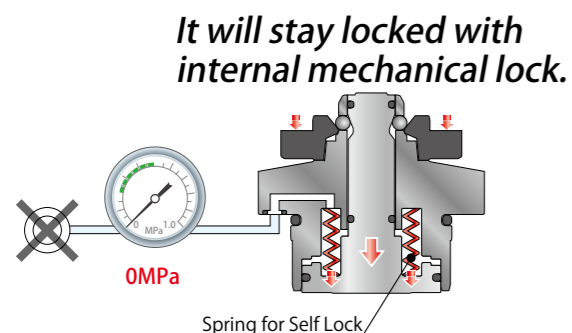
Pallet alignment is **Instant**

Pallet sharing system is very efficient for many variants with small batch production requirements.

## Self Lock (Safety) Function

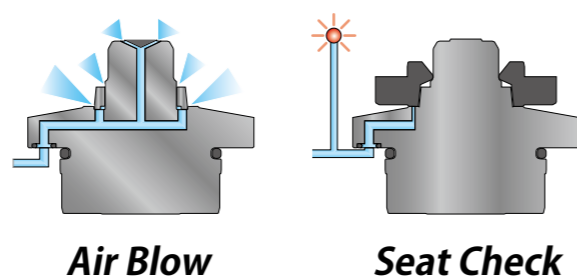
(Holding force when air pressure becomes zero)




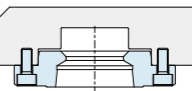
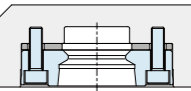
The internal mechanical lock operates and clamping force and holding force achieved. When pneumatic pressure is at zero, it will stay locked due internal mechanical lock.



## Air-Blow and Seat Check

Foreign substance is removed by air blow. Seating surface is provided with the air hole, seat check is possible if gap sensor is used.

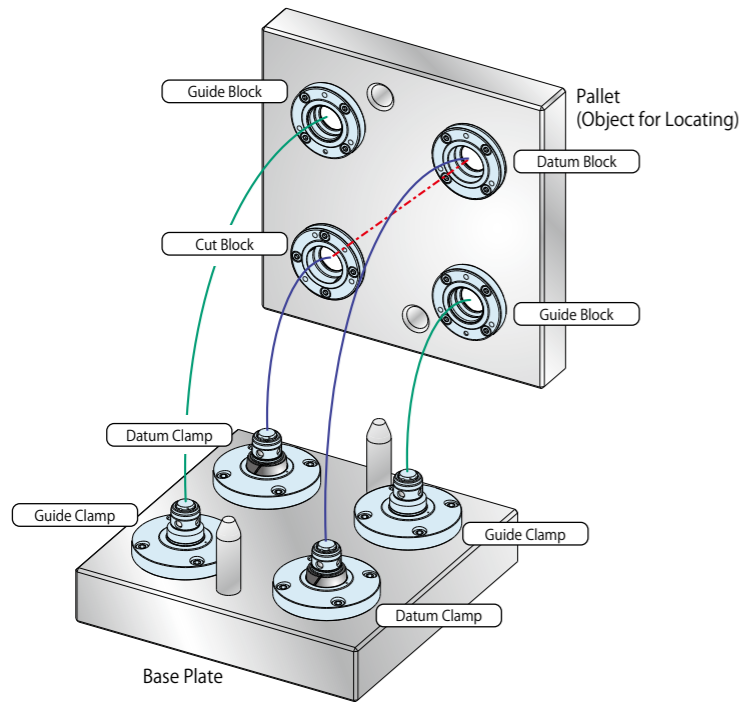


	 Model <b>WVS</b> → P.87	 Model <b>VSJ</b> → P.91	 Model <b>VSB</b> → P.89
Classification	Double Action Air Lock / Air Release	Flange Shaped Block	Embedded Block
Operating Pressure Range	0.25~0.5 MPa	-	-
Features	<ul style="list-style-type: none"> <li>Strong Clamping Force with Mechanical Lock</li> <li>With Self Lock by Spring</li> </ul>	 Simple Mounting	 Straight Mounting
Accessories	-	-	Level Adjustment Collar (VSB Only) VZ-VSC → P.89

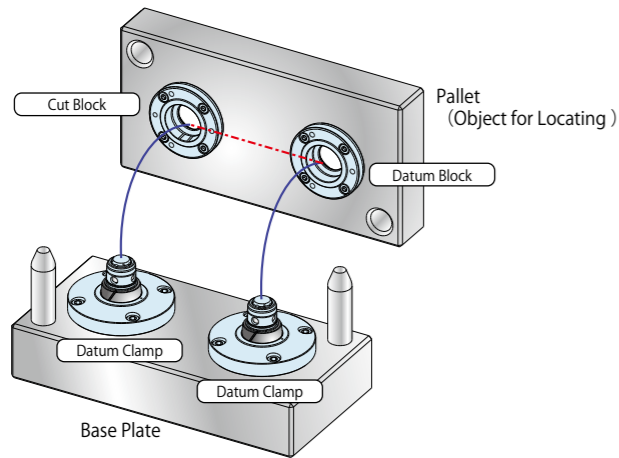
- Locating + Clamp
- Locating
- Clamp
- Support
- Valve · Coupler
- Cautions · Others
- Robotic Hand Changer
  - SWR
- Pneumatic Location Clamp
  - SWT
- High-Power Pneumatic Pallet Clamp
  - WVS

## System References

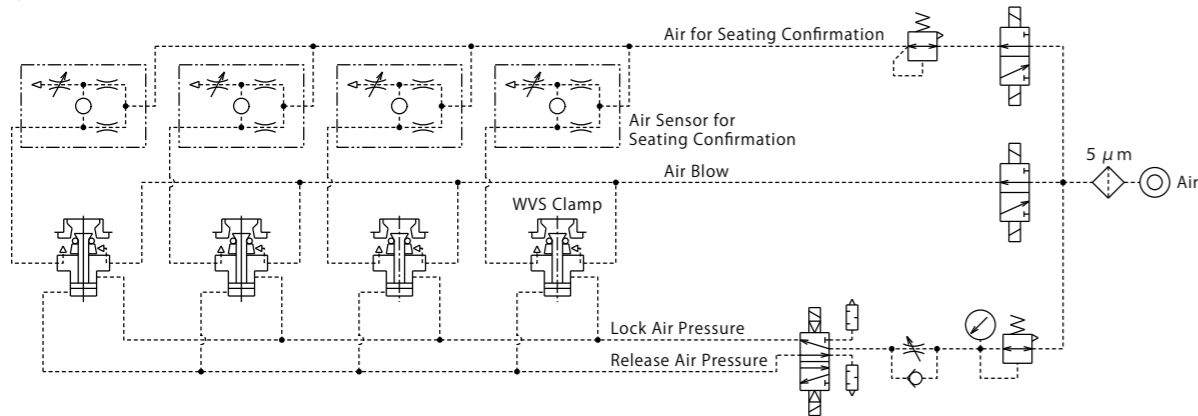
### Using Four Pneumatic Pallet Clamps



### Using Two Pneumatic Pallet Clamps



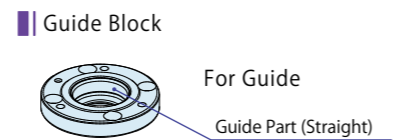
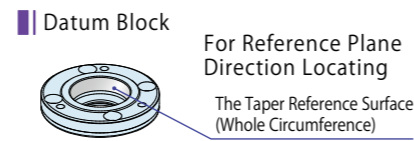
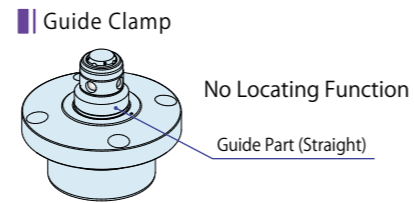
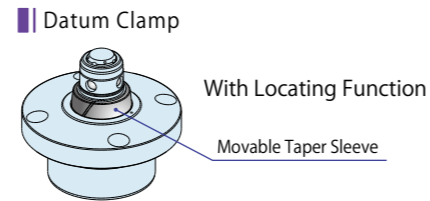
## Circuit Reference



Note 1. It is recommended to use air blow line with at least  $\phi 6$  in order to ensure effective air flow. Please supply clean filtered air.

### Apparatus and Function

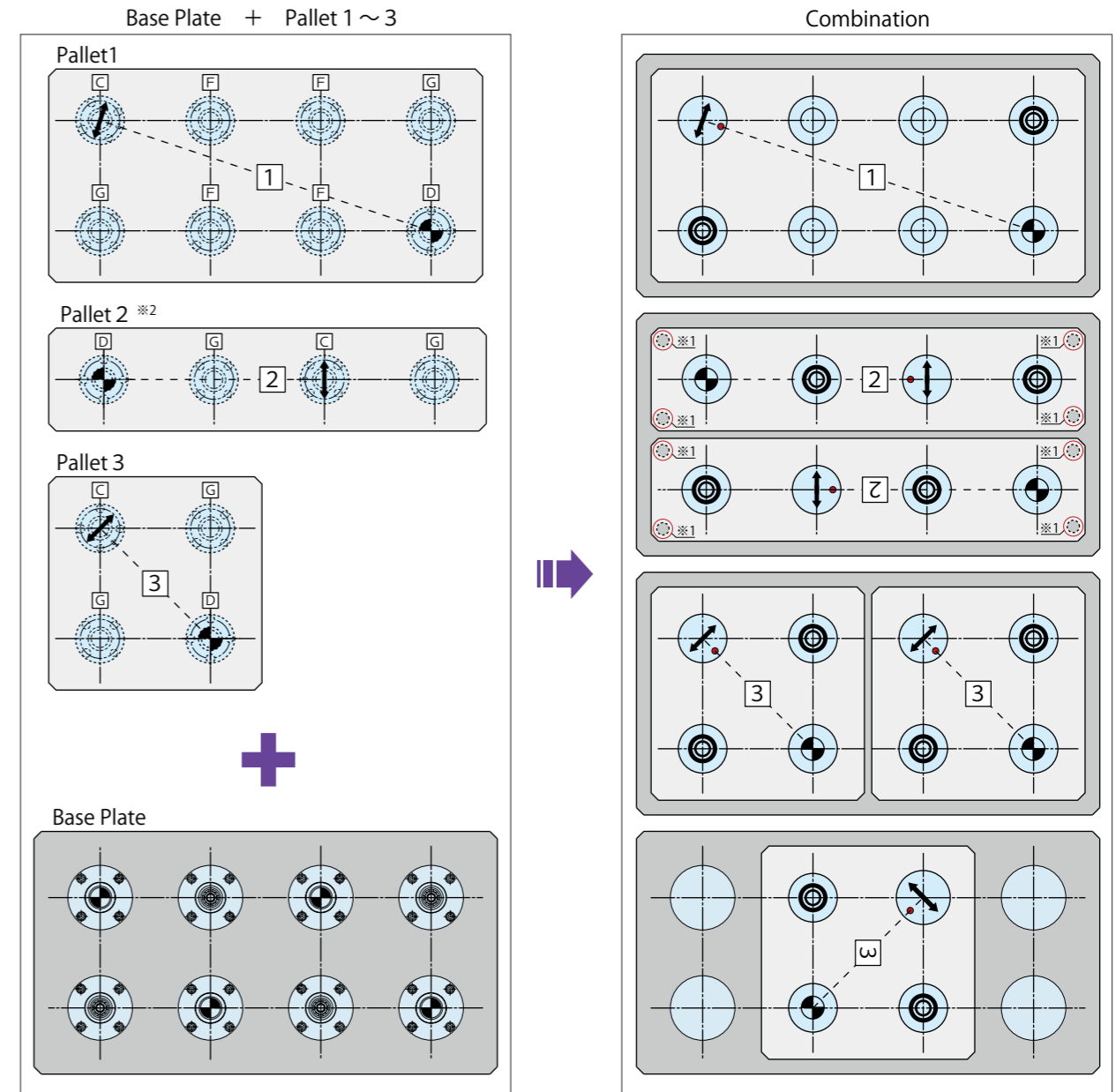
※ For Information about combination between clamps and blocks, please look at the P.81.



※ Free block does not have a guide function.

## Configuration Sample of Pallets with Different Sizes

In case there are a variety of pallets with different sizes for the base plate, the clamp and block can be combined for use.



### Combination of Clamp and Block

Equipment installed on the base plate	+	Equipment installed on the pallet	⇒	Functions when they are combined
Datum Clamp	+	Datum Block	⇒	Clamping Function + Locating Function (Reference Point)
Datum Clamp	+	Cut Block ※2	⇒	Clamping Function + Locating Function (One Direction)
Guide Clamp	+	Guide Block	⇒	Clamping Function + Guide Function
Datum Clamp or Guide Clamp	+	Free Block	⇒	Clamping Function

### Notes

- ※1. In case the clamp/block configuration is linear, it is recommended to provide additional supports for stability.
- ※2. The spring pin position is indicated. With the datum block as reference, unidirectional positioning is done via the cut block. The cut block positioning plane must be tangent to the datum block. (The spring pin is positioned on the line connecting the centers of the datum block and cut block.)

Locating + Clamp

Locating

Clamp

Support

Valve · Coupler

Cautions · Others

Robotic Hand Changer

SWR

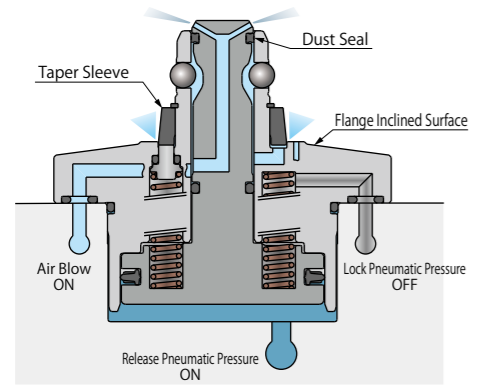
Pneumatic Location Clamp

SWT

High-Power Pneumatic Pallet Clamp

WVS

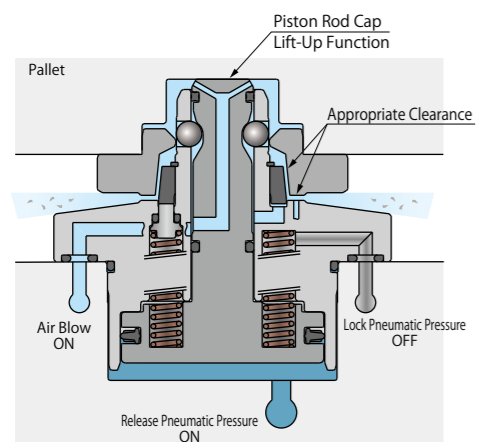
## Action Description ※ This is a simplified drawing. Actual components are different.



Before Loading the Pallet

- Air blow prevents debris contamination.
- Dust seal prevents foreign objects from entering and keeps steel ball area clean.
- The flange top is designed as inclined surface so that cutting powder and cutting oil can flow easily.
- The slitting part of taper sleeve (one place) is protected with lever plate to prevent invasion of cutting powder.

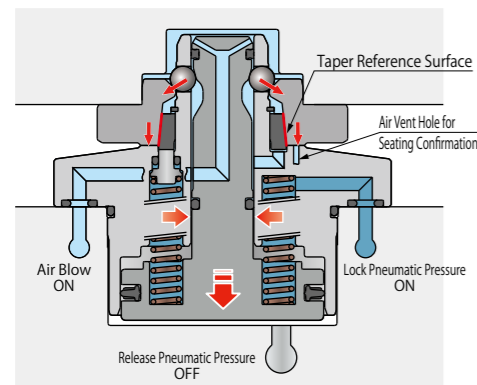
After Unloading the Pallet



When Loading the Pallet

- When the pallet is transported in
- The pallet is set on the raised piston rod cap. At this time there is clearance between the datum surfaces allowing air flow to remove contaminants. This allows to effectively remove chips and cutting oil by the air blower.
- When the pallet is transported out
- The close contacting of taper seating surface is released with lift-up force.

When Unloading the Pallet



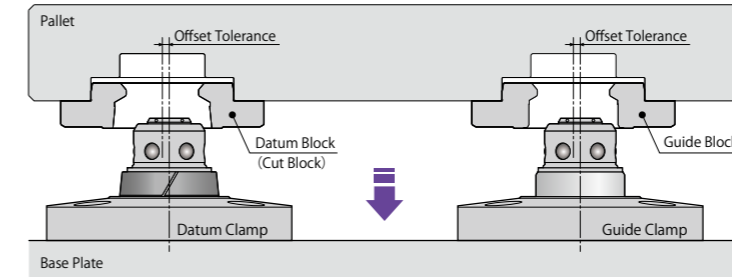
When clamped

- When release air pressured is OFF and lock pneumatic pressure is ON, the pneumatic pressure and the spring force, mechanical lock mechanism lowers the piston rod and the steel balls engage the block bringing it to the seating surface. (It holds the condition by mechanical lock function.)
- The pallet is positioned with high precision via the taper sleeve as it contacts the taper surface of the block.
- The seating surface includes an air vent for seating confirmation (via air catch sensor).

When clamped

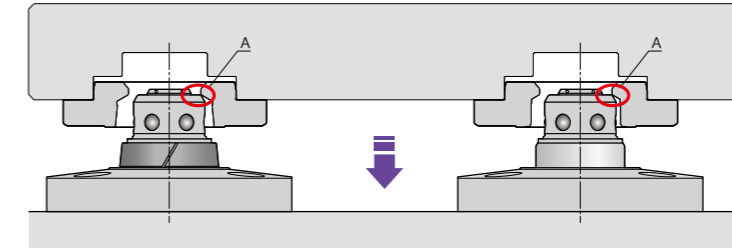
## Action Description during Loading/Unloading

1. Pneumatic pressure releases the clamp. Position of pallet while loading must be kept within the allowable eccentricity.

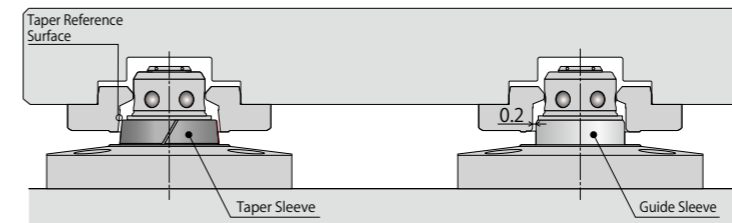


It is recommended to use rough guides to contain the pallet within the allowable eccentricity.

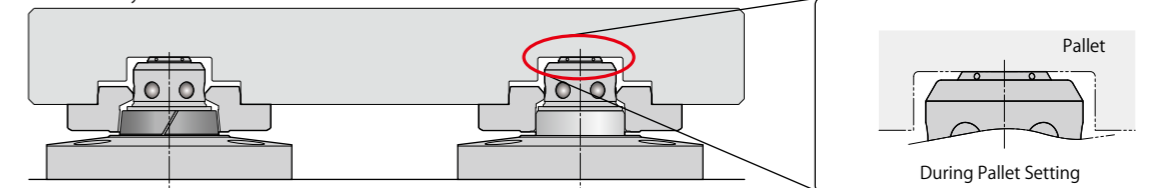
2. When the pallet is lowered, it should be positioned so the blocks contact the rod as shown on A.



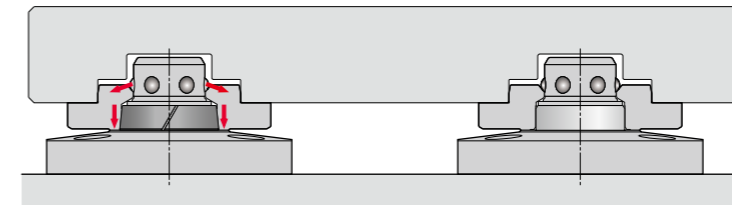
3. As the pallet is further lowered, it is positioned within 0.2mm of the reference axis via the guide sleeve and guide block.



4. Loading is finished when pallet is resting on piston rod. At this time there is clearance for air flow to clean the taper surfaces. At this time, the appropriate clearance between seating surface and taper reference is created by lift up function, which makes it thus more effective that the cutting chips are removed by air flow.



5. When the release pneumatic pressure is OFF and the lock pneumatic pressure is ON, the block is pressed on the seating surface with pneumatic pressure and clamp spring, mechanical lock mechanism. When the block is pressed, the taper reference surface is contacted for locating.

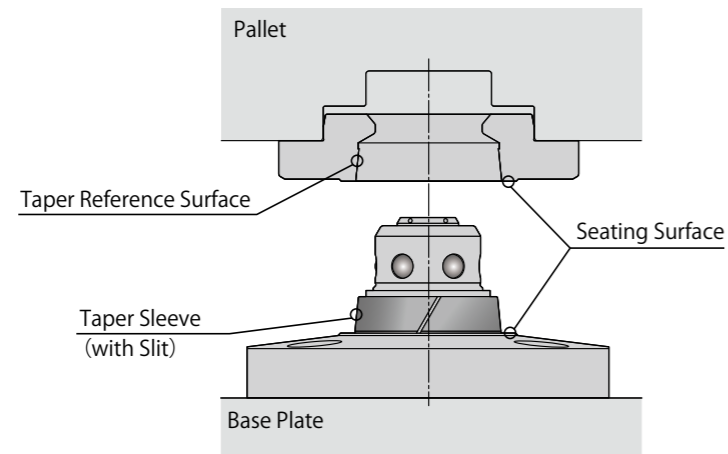


Locating + Clamp
Locating
Clamp
Support
Valve · Coupler
Cautions · Others
Robotic Hand Changer
SWR
Pneumatic Location Clamp
SWT
High-Power Pneumatic Pallet Clamp
WVS



● Description of Movable Taper Sleeve

Locating Method: Dual Surface with Movable Taper Sleeve

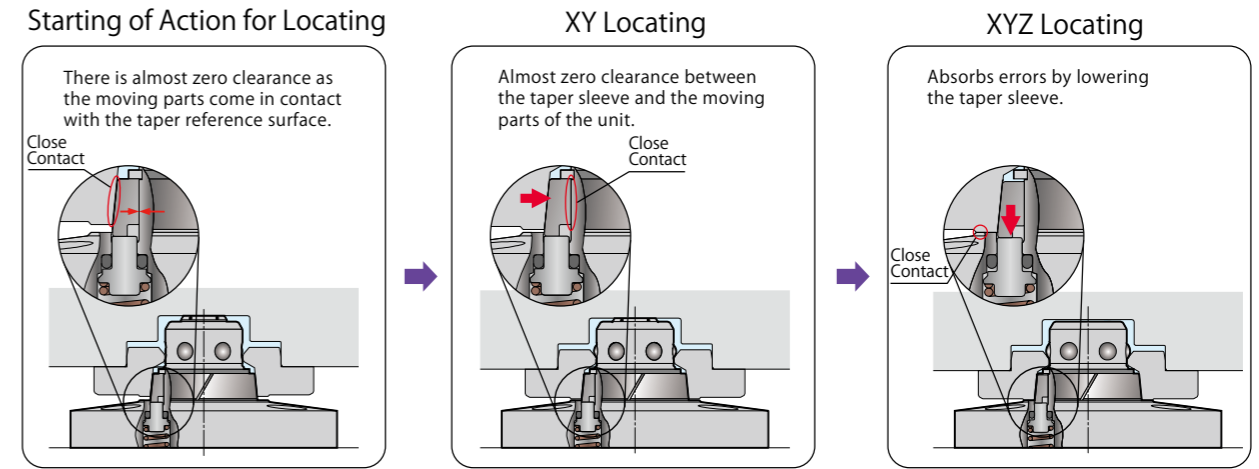


The Benefits of Movable Taper Sleeve

With marginal error absorbed by the movable taper sleeve, the clearance between the clamp unit, taper sleeve and block is eliminated enabling the repetitive location accuracy and stabilized clamping force.

- ① Absorbs tolerance variations in each location clamp and block.
- ② Absorbs wear of locating part due to long time use.
- ③ Absorbs space variations of mounting holes.
- ④ Absorbs space variations due to temperature change.

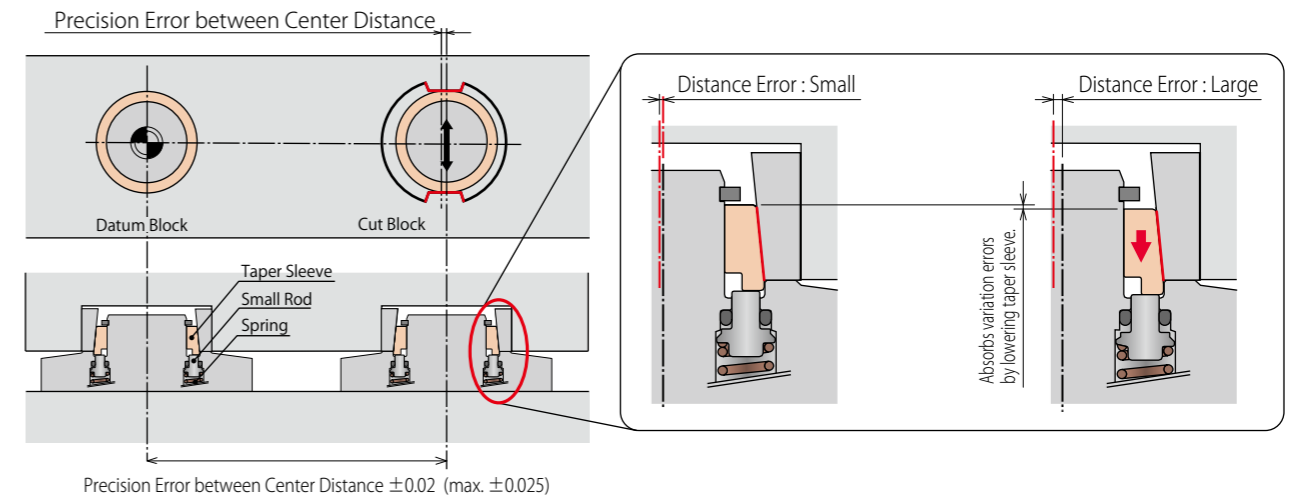
Movement and Error Absorbed by the Movable Taper Sleeve (①/②)



Movable taper sleeve absorbs distance error. (③/④)

Absorbs distance variations minimizing the wear of locating parts and prevents deformation of clamp/block.

※The precision assurance function is absolutely necessary especially when plates are transported or multiple fixture changeovers are needed.



## Model No. Indication (Clamp)

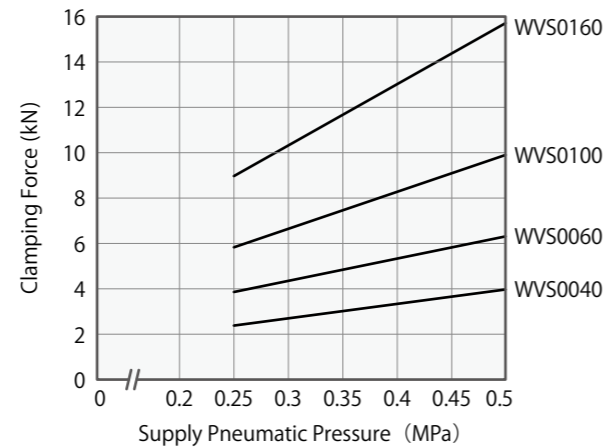
**WVS 0 06 0 - M D**

06
0
M
D

1
2
3

### 1 Clamping Force

- 04** : Clamping Force 4.0kN (Pneumatic Pressure 0.5MPa)
  - 06** : Clamping Force 6.3kN (Pneumatic Pressure 0.5MPa)
  - 10** : Clamping Force 9.9kN (Pneumatic Pressure 0.5MPa)
  - 16** : Clamping Force 15.7kN (Pneumatic Pressure 0.5MPa)
- ※ Refer to clamping force.  
Refer to Performance Curve and Specification.

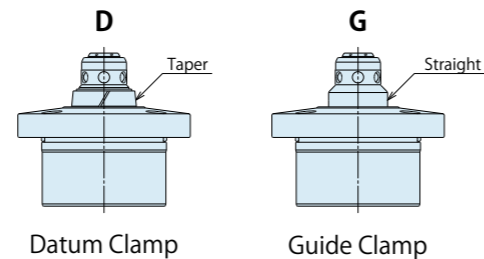


### 2 Design No.

**0** : Revision Number

### 3 Functions

- D** : Datum Clamp (Especially Used for Locating)
- G** : Guide Clamp (Especially Used for Guide)



## Combination of Clamp and Block

Clamp model	Block model	Function
WVS-MD (Datum Clamp)	VSB□-D / VSJ□-D (Datum Block)	Clamping + Locating at a Reference Point
WVS-MD (Datum Clamp)	VSB□-C / VSJ□-C (Cut Block)	Clamping + One Direction Locating
WVS-MG (Guide Clamp)	VSB□-G / VSJ□-G (Cut Block)	Clamping + Guide
WVS-M□ (Datum / Guide Clamp)	VSB□-F / VSJ□-F (Free Block)	Clamping

Notes

- Please refer to the following [ WVS (VS/VT) - VSB/VSJ Block Compatible Lists] for the detailed form of the combination.

## WVS (VS/VT) - VSB/VSJ Block Compatible Lists

Clamp Model	WVS0040	WVS0060	WVS0100	WVS0160
Block Model	VSB020	VSB060	VSB100	VSB160
(Material : SCM)	VSJ020	VSJ060	VSJ100	VSJ160
(Hydraulic Clamp Model No.)	(VS0040) (VT0040)	(VS0060) (VT0060)	(VS0100) (VT0100)	(VS0160) (VT0160)

Notes

- The function is described at combination of clamp and block.
- WVS and Block (VSB/VSJ) for Hydraulic clamp (VS/VT) are common.

## Model No. Indication (Block)

VSB : Embedded Block

VSJ : Flange Shaped Block

**VSB 06 0 - D**

06
0
D

1
2
3
4

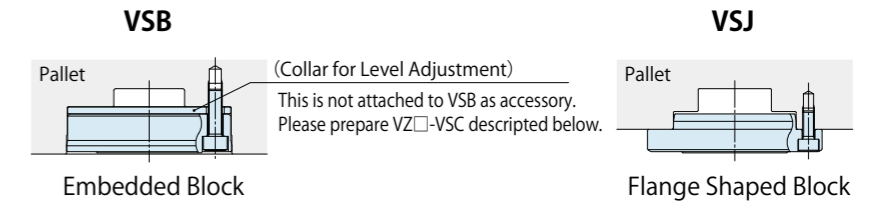
**VSJ 06 0 - D**

06
0
D

1
2
3
4

### 1 Shape of Block

- VSB** : Embedded Block
- VSJ** : Flange Shaped Block



### 2 Accommodate WVS/VS/VT Clamp Model

- 02** : WVS0040 / VS0020 / VS0040 / VT0040
- 06** : WVS0060 / VS0060 / VT0060
- 10** : WVS0100 / VS0100 / VT0100
- 16** : WVS0160 / VS0160 / VT0160

Notes

- VS/VT is hydraulic model.

### 3 Design No.

**0** : Revision Number

### 4 Functions

- D** : Datum Block (Especially Used for Reference Locating)
- C** : Cut Block (Especially Used for One Direction Locating)
- G** : Guide Block (Especially Used for Guide)
- F** : Free Block (Shared by Multiple Pallets with Different Sizes)

## Model No. Indication (Spacer for Level Adjustment)

※ This product is only for VSB's embedded block.

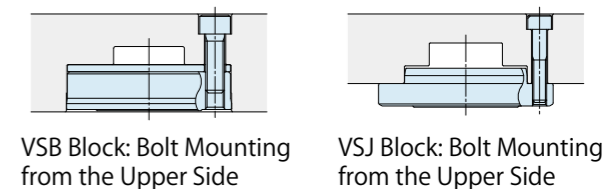
**VZ 0 06 0 - VSC**

06
0
VSC

1
2

## Other Mounting Examples (Reference)

※ Please contact us for mounting methods as shown in the drawing below.



### 1 Accommodate VSB Block Model No.

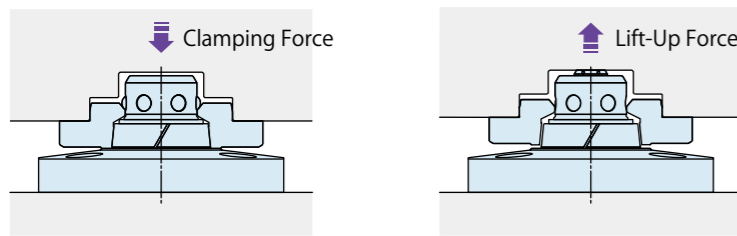
- 02** : VSB020-□
- 06** : VSB060-□
- 10** : VSB100-□
- 16** : VSB160-□

### 2 Design No.

**0** : Revision Number

## Clamping Force / Lift-Up Force

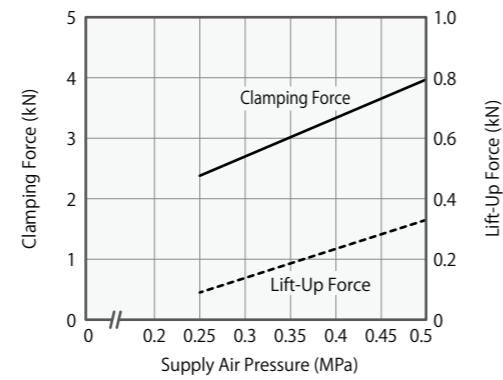
## MEMO



(Example)  
 When using WVS0060-M□  
 Supply Air Pressure 0.4MPa  
 Clamping force is about 5.3kN  
 Lift-up force is about 0.34kN.

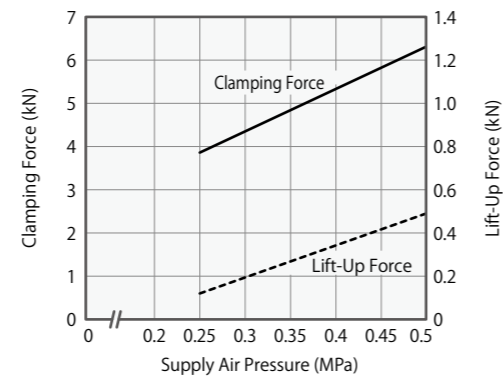
### WVS0040-M□

Supply Air Pressure (MPa)	Clamping Force(kN)	Lift-Up Force (kN)
0.5	4.0	0.33
0.45	3.6	0.28
0.4	3.3	0.23
0.35	3.0	0.19
0.3	2.7	0.14
0.25	2.4	0.09
Holding Force at 0 MPa ※1	0.8	-
Operating Pressure Range (MPa)	0.25 ~ 0.5	



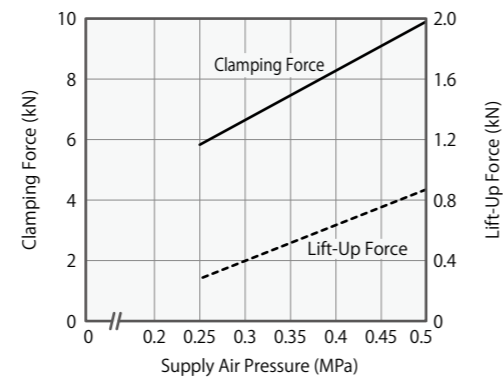
### WVS0060-M□

Supply Air Pressure (MPa)	Clamping Force(kN)	Lift-Up Force (kN)
0.5	6.3	0.49
0.45	5.8	0.42
0.4	5.3	0.34
0.35	4.8	0.27
0.3	4.4	0.20
0.25	3.9	0.12
Holding Force at 0 MPa ※1	1.4	-
Operating Pressure Range (MPa)	0.25 ~ 0.5	



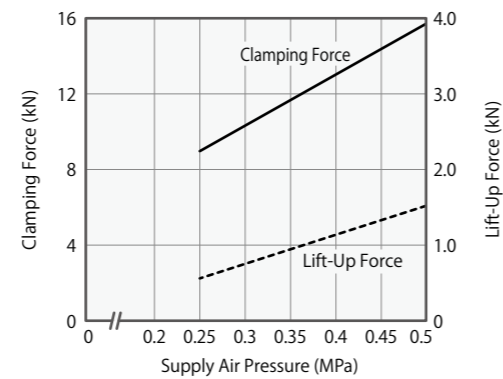
### WVS0100-M□

Supply Air Pressure (MPa)	Clamping Force(kN)	Lift-Up Force (kN)
0.5	9.9	0.87
0.45	9.1	0.75
0.4	8.3	0.64
0.35	7.5	0.52
0.3	6.6	0.40
0.25	5.8	0.28
Holding Force at 0 MPa ※1	1.8	-
Operating Pressure Range (MPa)	0.25 ~ 0.5	



### WVS0160-M□

Supply Air Pressure (MPa)	Clamping force(kN)	Lift-up force (kN)
0.5	15.7	1.52
0.45	14.4	1.33
0.4	13.0	1.14
0.35	11.7	0.94
0.3	10.3	0.75
0.25	9.0	0.56
Holding Force at 0 MPa ※1	2.2	-
Operating Pressure Range (MPa)	0.25 ~ 0.5	



### Notes

- This graph shows the value for single clamp.
  - This graph shows the relationship between Supply Air Pressure and Clamping Force (solid line) / Lift-Up Force (dotted line).
- ※1. It shows holding force at 0MPa air pressure and does not satisfy specifications.

- Locating + Clamp
- Locating
- Clamp
- Support
- Valve · Coupler
- Cautions · Others

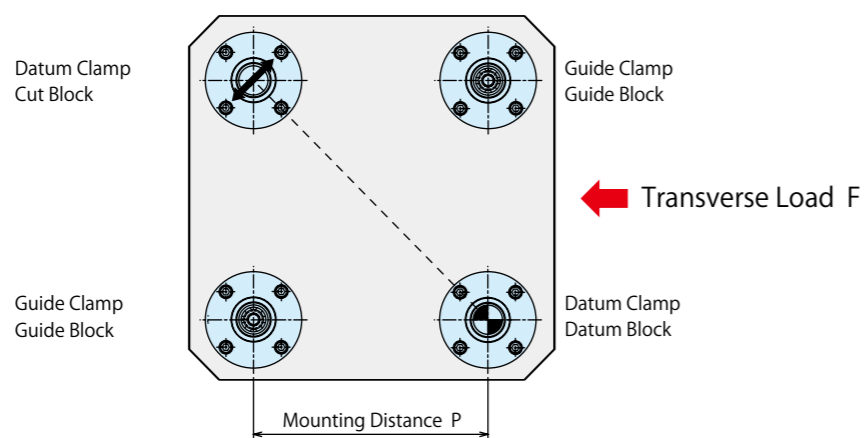
- Robotic Hand Changer
  - SWR
- Pneumatic Location Clamp
  - SWT

- High-Power Pneumatic Pallet Clamp
  - WVS

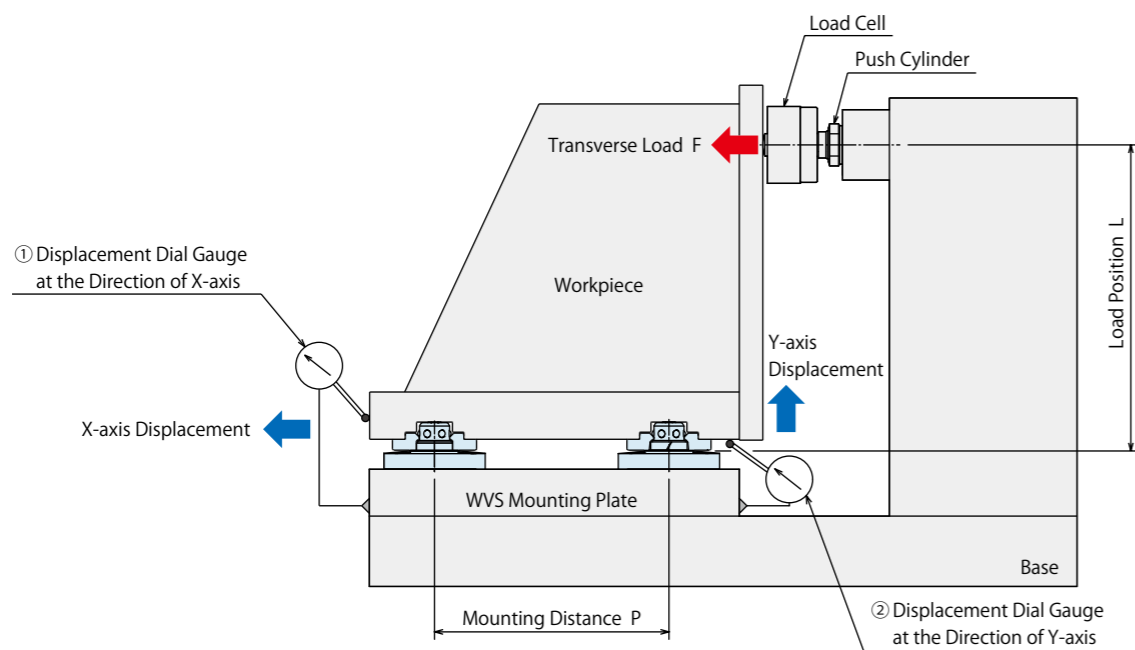
## Displacement against Transverse Load

※ The displacement is the predicted reference value based on the test data under the conditions shown below.  
Displacement may vary according to conditions of fixtures. The displayed values are reference based on the test data.

### Clamp/Block Layout



### Test Device



### How to Read Displacement

(Ex.) When using WVS0040

#### Components

- 【Clamp】 WVS0040-MD×2 Units, WVS0040-MG×2 Units
- 【Block】 VSJ020-D×1 Unit, VSJ020-C×1 Unit, VSJ020-G×2 Units

#### Conditions

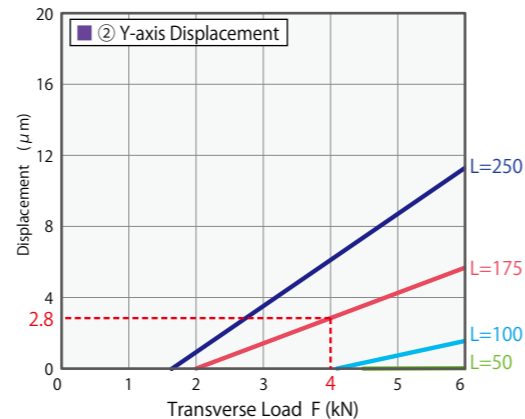
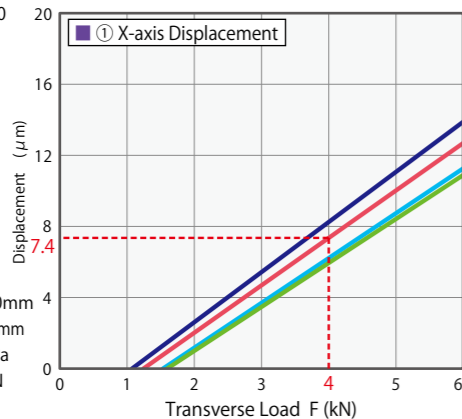
- Mounting Distance P=200mm
- Load Position L=175mm
- Supply Air Pressure 0.5MPa
- Transverse Load F=4kN

#### Displacement

- ① X-axis displacement is about 7.4 μm.
- ② Y-axis displacement is about 2.8 μm.

#### Note

- 1. Please contact us in case the conditions are different.



### WVS0040

#### Components

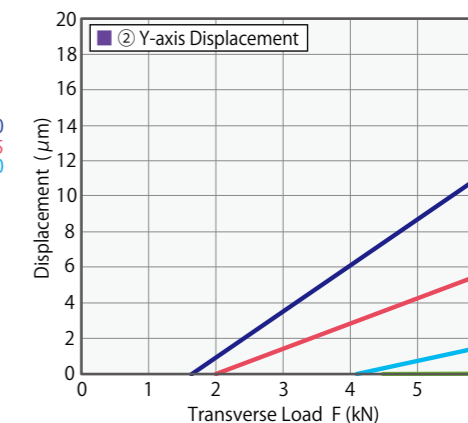
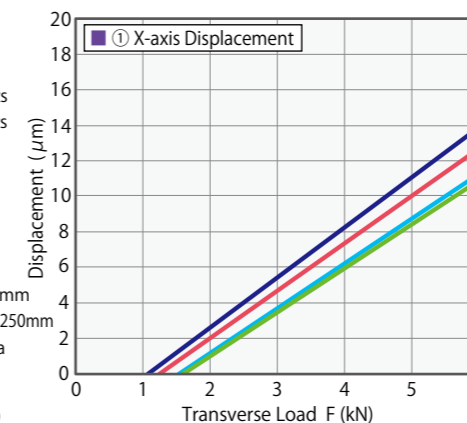
- 【Clamp】 WVS0040-MD×2 Units, WVS0040-MG×2 Units
- 【Block】 VSJ020-D×1 Unit, VSJ020-C×1 Unit, VSJ020-G×2 Units

#### Conditions

- Mounting Distance P=200mm
- Load Position L=50~250mm
- Supply Air Pressure 0.5MPa

#### Clamping Force

- Total 16kN (4.0kN×4)



### WVS0060

#### Components

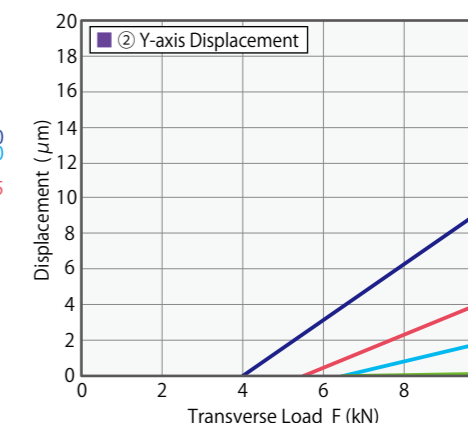
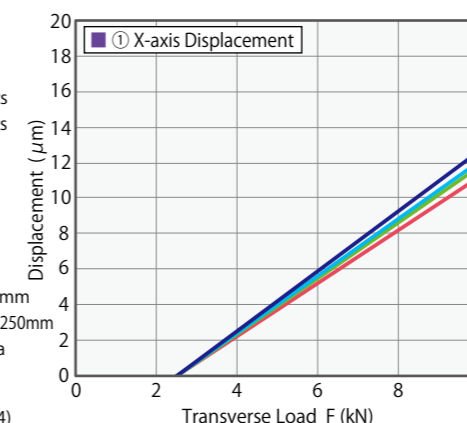
- 【Clamp】 WVS0060-MD×2 Units, WVS0060-MG×2 Units
- 【Block】 VSJ060-D×1 Unit, VSJ060-C×1 Unit, VSJ060-G×2 Units

#### Conditions

- Mounting Distance P=200mm
- Load Position L=50~250mm
- Supply Air Pressure 0.5MPa

#### Clamping Force

- Total 25.2kN (6.3kN×4)



### WVS0100

#### Components

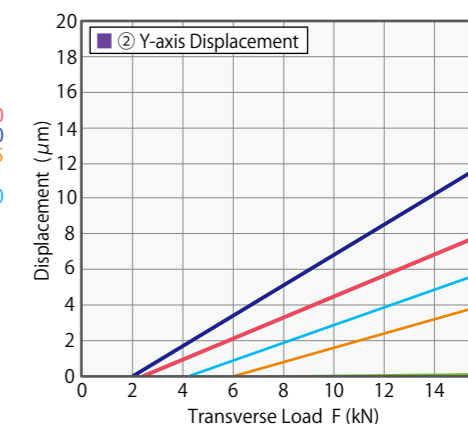
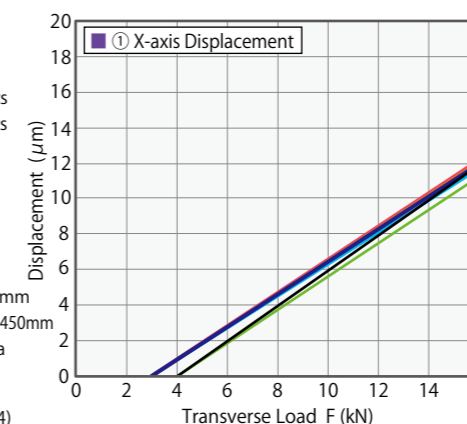
- 【Clamp】 WVS0100-MD×2 Units, WVS0100-MG×2 Units
- 【Block】 VSJ100-D×1 Unit, VSJ100-C×1 Unit, VSJ100-G×2 Units

#### Conditions

- Mounting Distance P=300mm
- Load Position L=50~450mm
- Supply Air Pressure 0.5MPa

#### Clamping Force

- Total 39.6kN (9.9kN×4)



### WVS0160

#### Components

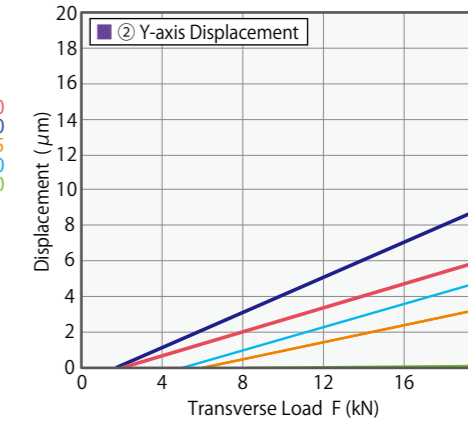
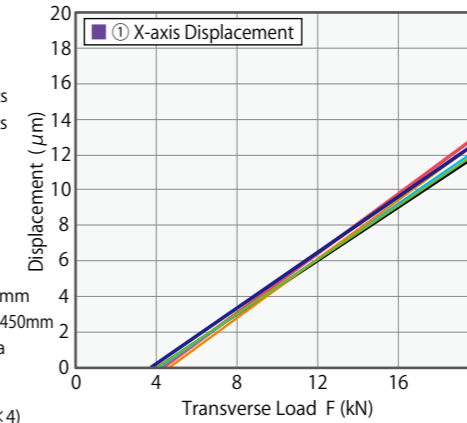
- 【Clamp】 WVS0160-MD×2 Units, WVS0160-MG×2 Units
- 【Block】 VSJ160-D×1 Unit, VSJ160-C×1 Unit, VSJ160-G×2 Units

#### Conditions

- Mounting Distance P=300mm
- Load Position L=50~450mm
- Supply Air Pressure 0.5MPa

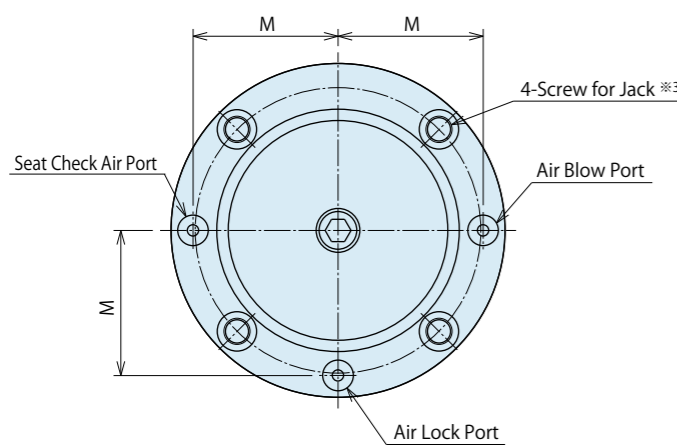
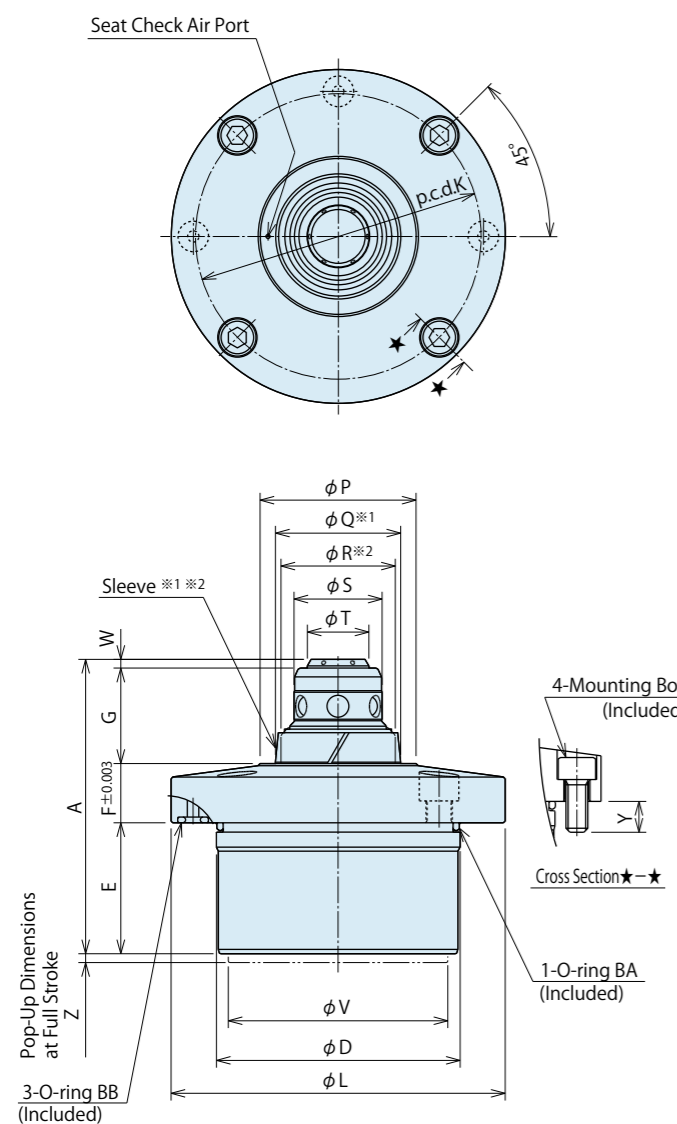
#### Clamping Force

- Total 62.8kN (15.7kN×4)



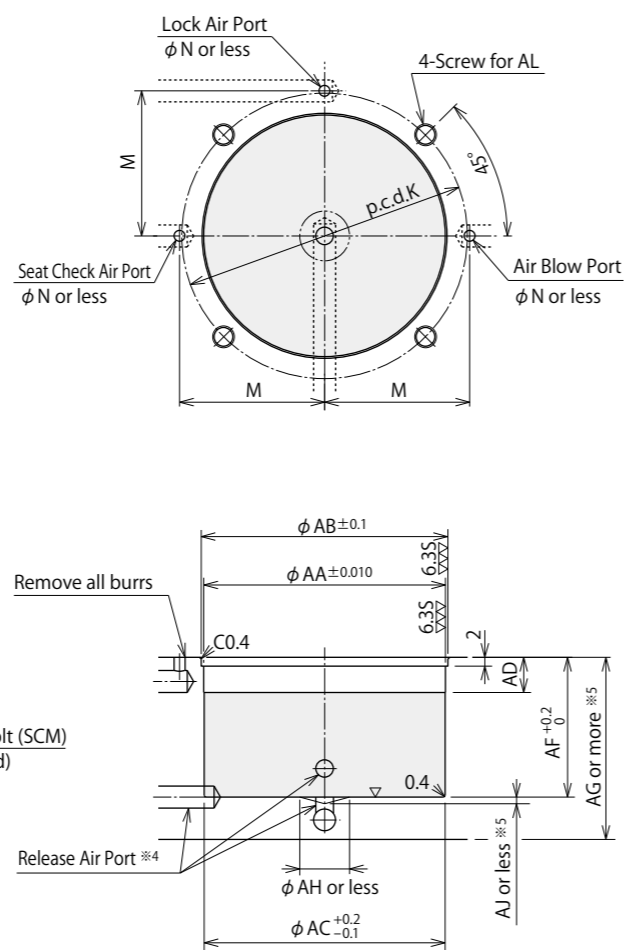
## External Dimensions

※This drawing shows the release state of WVS.



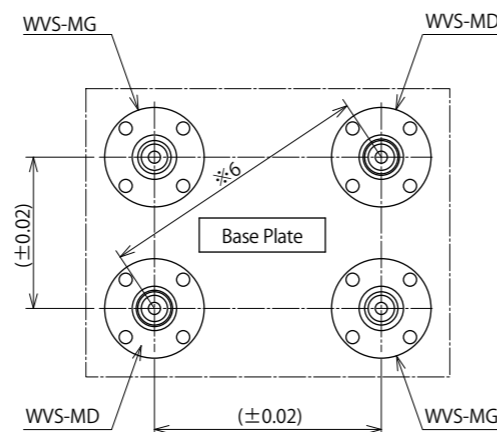
- Notes
- ※1.  $\phi Q$  shows the dimensions of sleeve (taper) of datum clamp (WVS-MD).
  - ※2.  $\phi R$  shows the dimensions of sleeve (straight) of guide clamp (WVS-MG).
  - ※3. The screw for jack is used when removing the clamp. (See P.94 for usage.)

## Machining Dimensions of Mounting Area



- Notes
1. Make sure no burrs are on or around the hole intersection.
  - ※4. The release air port is within  $\square$  range.
  - ※5. The base thickness (AG) and remaining depth after boring (AJ) are reference values when the base material is S50C.

## Distance Accuracy of Each Clamp



- Note
- ※6. Please make sure the distance accuracy of each datum clamp is below  $\pm 0.025$ mm between the clamps with the longest distance.

## Specifications

Model	WVS0040-M□	WVS0060-M□	WVS0100-M□	WVS0160-M□
Locating Repeatability	mm 0.003			
Full Stroke	mm 3.4	mm 3.4	mm 4.0	mm 4.5
Lift Up Stroke	mm 1.0			
Offset Tolerance when fixture pallet is set	mm 1.0	mm 1.5	mm 1.5	mm 1.5
Max. Loading Weight ※8	kg 300	kg 600	kg 1000	kg 1500
Cylinder Capacity ※7	Lock	cm <sup>3</sup> 8.76	cm <sup>3</sup> 13.56	cm <sup>3</sup> 26.10
	Release	cm <sup>3</sup> 9.41	cm <sup>3</sup> 14.75	cm <sup>3</sup> 28.01
Holding Force at 0 MPa ※7 ※9	kN 0.8, 1.4, 1.8, 2.2			
Max. Operating Pressure	MPa 0.5			
Min. Operating Pressure	MPa 0.25			
Withstanding Pressure	MPa 0.75			
Air Blow Pressure	MPa 0.4~0.5			
Operating Temperature	°C 0~70			
Usable Fluid	Dry Air			
Mass※7	kg 0.7	kg 1.0	kg 1.8	kg 3.5

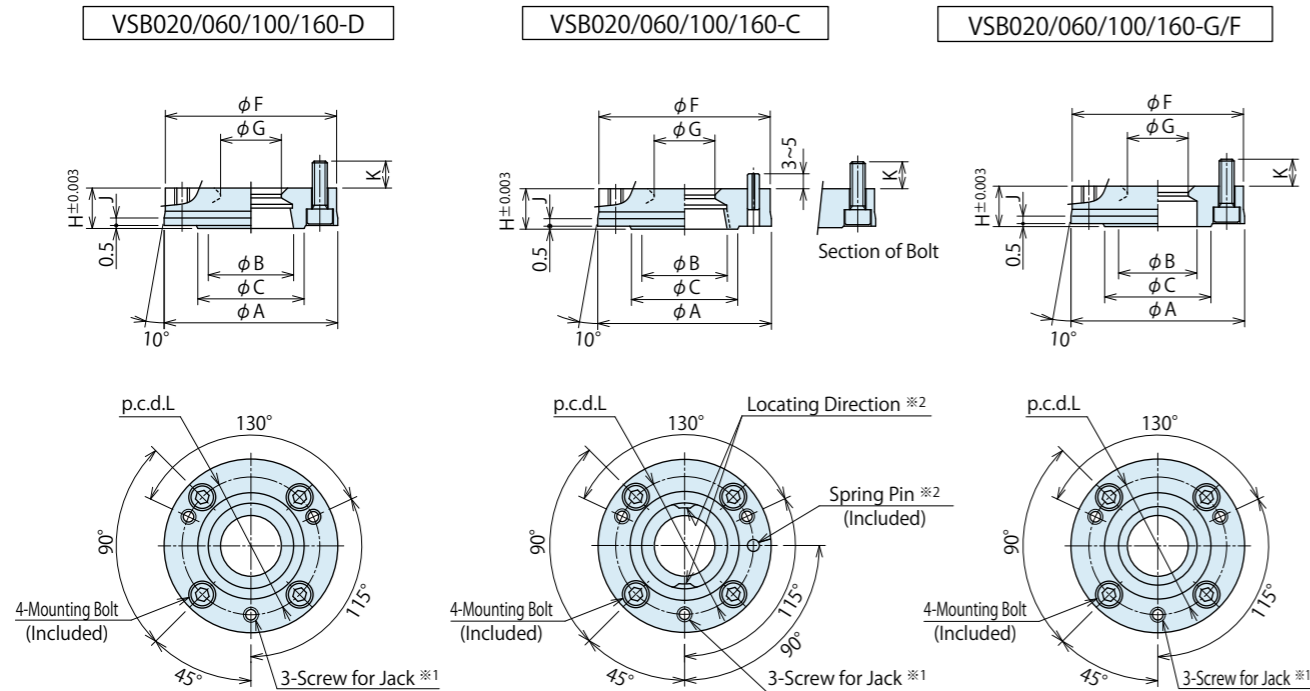
- Notes
- ※7. The specifications show one unit.
  - ※8. When the pallet is in horizontal position (leveled), make sure the weight of the workpiece & fixture is less than the lift force of the clamps and maximum load of the machine. The release pneumatic pressure is decided with the loaded mass (fixture) considered. (Please set the loaded mass below 80% of the lift force (number of clamps X lift force).) Please let us know if you are going to use it in vertical position.
  - ※9. It shows holding force at 0MPa air pressure and does not satisfy specifications.

## External Dimensions and Machining Dimensions for Mounting

Model	WVS0040-M□	WVS0060-M□	WVS0100-M□	WVS0160-M□
A	65.7	67.2	78.2	90.2
D	WVS-MD	45 <sup>+0.030</sup> <sub>+0.011</sub>	55 <sup>+0.030</sup> <sub>+0.011</sub>	69 <sup>+0.030</sup> <sub>+0.011</sub>
	WVS-MG	45 <sup>0</sup> <sub>-0.020</sub>	55 <sup>0</sup> <sub>-0.020</sub>	69 <sup>0</sup> <sub>-0.020</sub>
E	30	30	34	39
F	12	13.5	16	20
G	21.7	21.7	26.5	29.5
K	55	65	81	102.5
L	66	76	94	118.5
M	28	33	41	51.5
N	2.5	2.5	3	5
P	32	35.5	44	51
Q	25	28.5	36	42
R	22.5	26	32.3	38.3
S	18	20	26	32
T	12	14	18.8	22.4
V	40	50	63	80
W	2	2	1.7	1.7
Y	8	7	8	11.8
Z	0.5	0.5	1	1
AA	45	55	69	87.5
AB	45.2	55.2	69.2	87.7
AC	44.8	54.8	68.8	87.3
AD	8	8	9	10
AF	30.5	30.5	35	40
AG	35	35	40	45
AH	9	9	14	17
AJ	2.5	2.5	2.5	2.5
AL (Nominal×Pitch×Depth)	M5×0.8×10	M5×0.8×10	M6×1×10	M8×1×14
1-O-ring BA	AS568-030(70°)	AS568-033(70°)	AS568-037(70°)	AS568-042(70°)
3-O-ring BB	AS568-007(70°)	AS568-007(70°)	1AP5	1AP7
Mounting Bolt	M5×0.8×12	M5×0.8×12	M6×1×14	M8×1.25×20
Screw for Jack	M6×1	M6×1	M8×1.25	M10×1.5

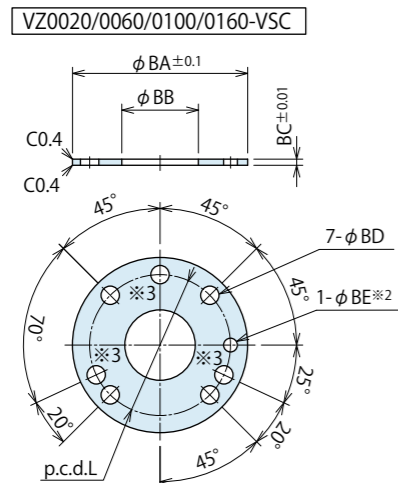
Locating + Clamp
Locating
Clamp
Support
Valve + Coupler
Cautions + Others
Robotic Hand Changer
SWR
Pneumatic Location Clamp
SWT
High-Power Pneumatic Pallet Clamp
WVS

External Dimensions



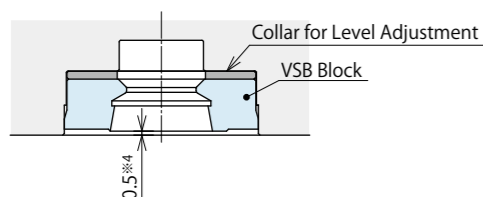
- Notes
- ※1. The screw for jack is used when removing VSB block.
  - ※2. The spring pin is used for phasing of VSB-C locating direction.

Dimensions of Collar for Level Adjustment



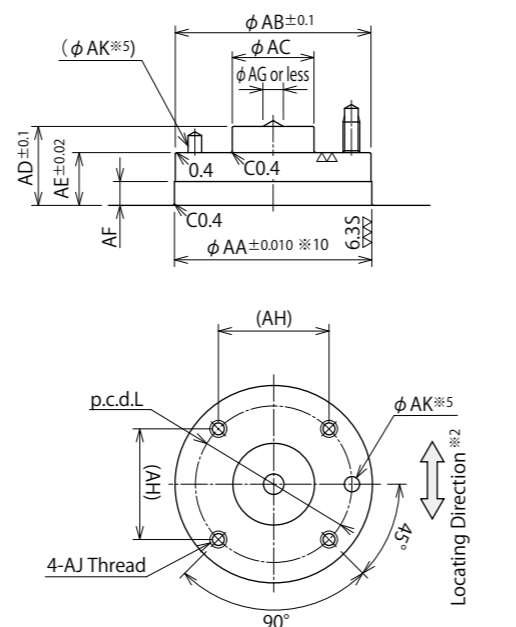
- Notes
- 1. Please refer to the drawing above in case the collar for level adjustment is prepared by yourself.
  - ※3. The screw for jack is used when VSB block is removed.

※Mounting of Collar for Level Adjustment.



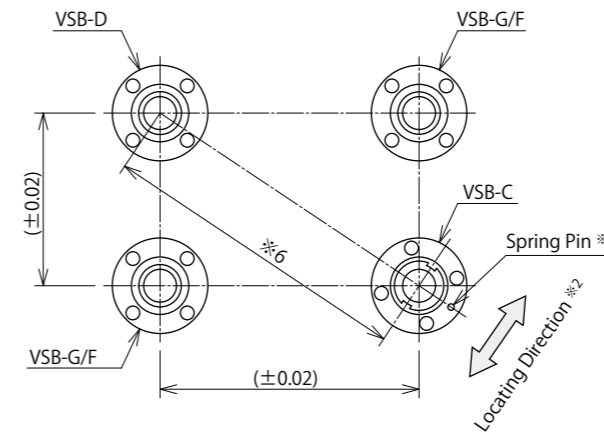
※4. Clearance between the seating area of VSB block and block bottom.

Machining Dimensions of Mounting Area



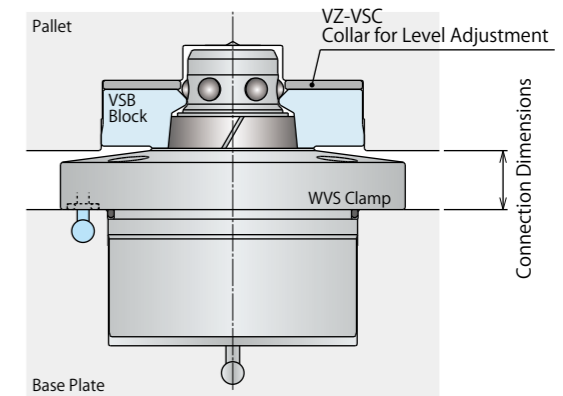
- Notes
- 1. This graph shows the case where the clearance between the seating area of VSB block and pallet bottom is 0.5mm when the collar for level adjustment is used.
  - ※5. phi AK hole is used for phasing of VSB-C positioning direction. Please make sure phi AK hole is at the line connecting the centers of VSB-D and VSB-C. This processing is only necessary for VSB-C.

Mounting Distance Accuracy and VSB-C Phase



- Note
- ※6. Please make sure the precision between block pitches is within ±0.025mm between the blocks with the longest distance.

Connection Dimensions



External Dimensions and Machining Dimensions for Mounting

Model No.	VSB020-D VSB020-C	VSB020-G VSB020-F	VSB060-D VSB060-C	VSB060-G VSB060-F	VSB100-D VSB100-C	VSB100-G VSB100-F	VSB160-D VSB160-C	VSB160-G VSB160-F
A	50 <sup>+0.027</sup> / <sub>+0.011</sub>	50g7 <sup>-0.009</sup> / <sub>-0.034</sub>	58m6 <sup>+0.030</sup> / <sub>+0.011</sub>	58g7 <sup>-0.010</sup> / <sub>-0.040</sub>	70m6 <sup>+0.030</sup> / <sub>+0.011</sub>	70g7 <sup>-0.010</sup> / <sub>-0.040</sub>	83m6 <sup>+0.035</sup> / <sub>+0.013</sub>	83g7 <sup>-0.012</sup> / <sub>-0.047</sub>
B	25	22.7 (25.5) <sup>※7</sup>	28.5	26.2 (29) <sup>※7</sup>	36	32.5 (36.5) <sup>※7</sup>	42	38.5 (42.5) <sup>※7</sup>
C	32		35.5		44		51	
F	49.2		57.2		69.2		82.2	
G	18.3		20.3		26.3		32.3	
H	13		13		16.5		17.5	
J	2.5		2.5		2.5		3	
K	8		9		10.5		16.5	
L	40		46		56		66	
AA <sup>※10</sup>	50		58		70		83	
AB	49.5		57.5		69.5		82.5	
AC	22		24		30		36	
AD	23.2		23.2		27.7		30.7	
AE	15.5		15.5		20		21	
AF	7		7		8		8	
AG	3		3		5		5	
(AH)	28.28		32.53		39.6		46.67	
AJ (Nominal×Pitch×Depth)	M4×0.7×7		M5×0.8×8		M6×1×10		M8×1.25×14.5	
AK	phi 3.4 Depth 5	-	phi 4.5 Depth 5	-	phi 4.5 Depth 5	-	phi 4.5 Depth 5	-
Mounting Bolt	M4×0.7×16		M5×0.8×16		M6×1×20		M8×1.25×25	
Screw for Jack	M4×0.7		M5×0.8		M6×1		M8×1.25	
Spring Pin <sup>※8</sup>	phi 3×10	-	phi 4×10	-	phi 4×10	-	phi 4×10	-
Mass	0.15kg		0.2kg		0.35kg		0.5kg	
Appropriate Clamp	WVS0040-MD VS0020-MD VS/VT0040-MD	WVS0040-MG WVS0040-MD <sup>※9</sup> VS0020-MG VS/VT0040-MG VS0020-MD <sup>※9</sup> VS/VT0040-MD	WVS0060-MD VS/VT0060-MD	WVS0060-MG WVS0060-MD <sup>※9</sup> VS/VT0060-MG VS/VT0060-MD <sup>※9</sup>	WVS0100-MD VS/VT0100-MD	WVS0100-MG WVS0100-MD <sup>※9</sup> VS/VT0100-MG VS/VT0100-MD <sup>※9</sup>	WVS0160-MD VS/VT0160-MD	WVS0160-MG WVS0160-MD <sup>※9</sup> VS/VT0160-MG VS/VT0160-MD <sup>※9</sup>
Connection Dimensions	When Lock	11.5	13	15.5	19.5			
WVS/VS	When Release	12.5	14	16.5	20.5			

Model	VZ0020-VSC	VZ0060-VSC	VZ0100-VSC	VZ0160-VSC
BA	49.2	57.2	69.2	82.2
BB	23	25	32	38
BC	2	2	3	3
BD	5	6	7.5	10
BE	3.4	4.5	4.5	4.5

- Notes
- ※7. The dimensions in ( ) display that of VSB-F.
  - ※8. The spring pin is included only in VSB-C.
  - ※9. The guide block (VSB-G) is used only for guide clamp (WVS-G) and the free block (VSB-F) can be used for both datum clamp (WVS-D) and guide clamp (WVS-G).
  - ※10. Pallet with low rigidity (thin pallet or pallet made of aluminum etc.) may be deformed when mounting VSB block. In this case, tolerance of mounting hole machining dimension AA±0.010 should be close to +0.010 (the upper limit of the tolerance).

Locating + Clamp

Locating

Clamp

Support

Valve · Coupler

Cautions · Others

Robotic Hand Changer

SWR

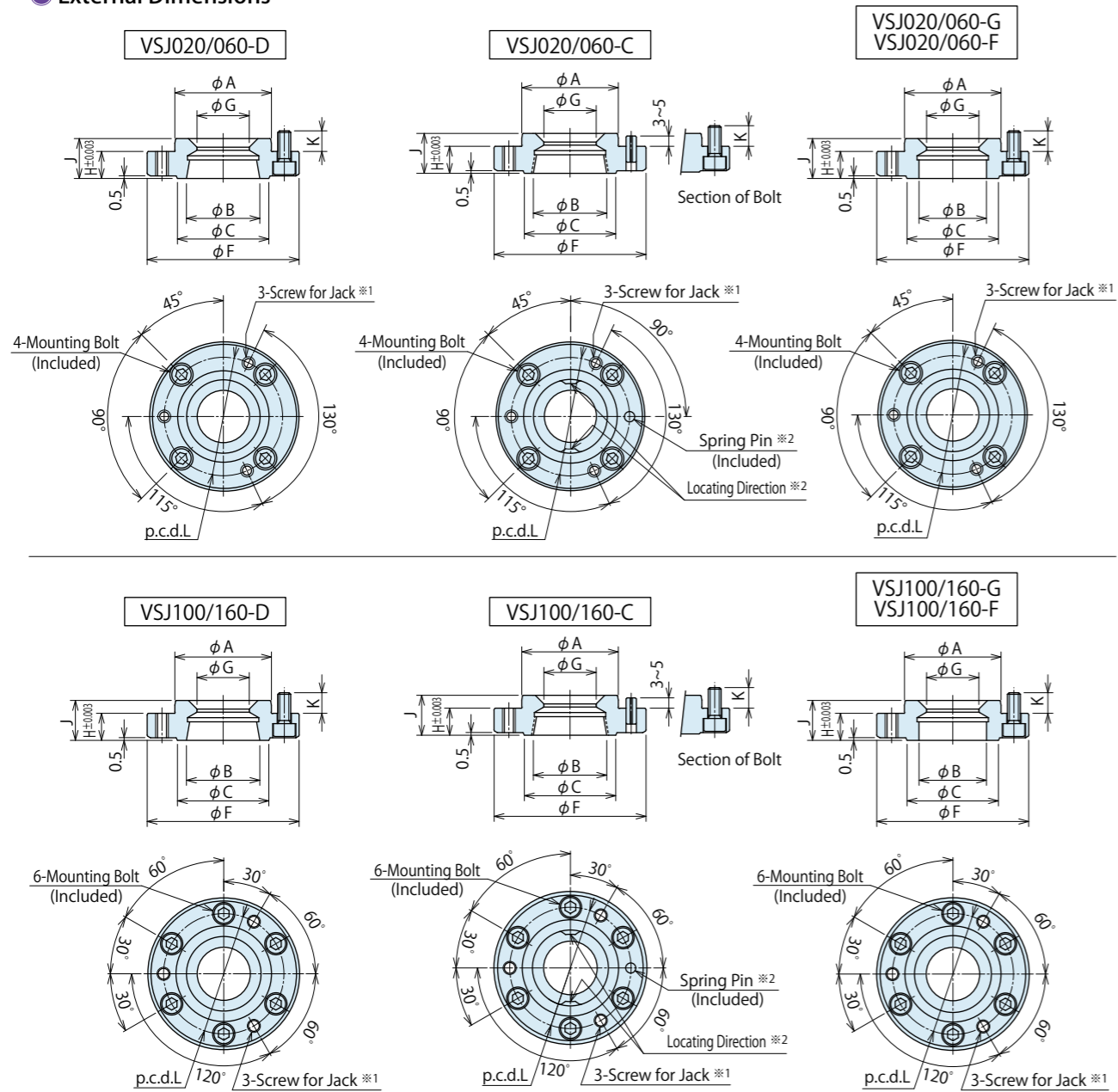
Pneumatic Location Clamp

SWT

High-Power Pneumatic Pallet Clamp

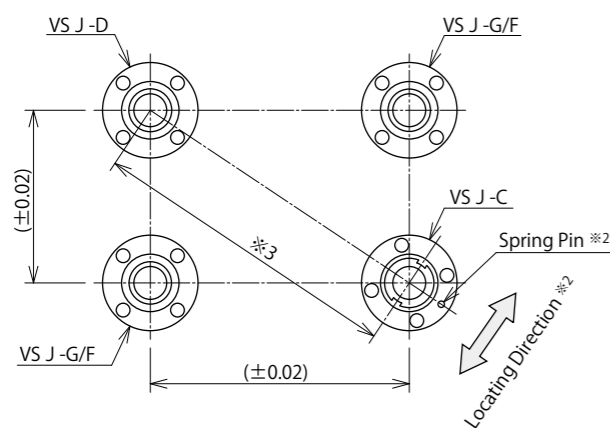
WVS

External Dimensions



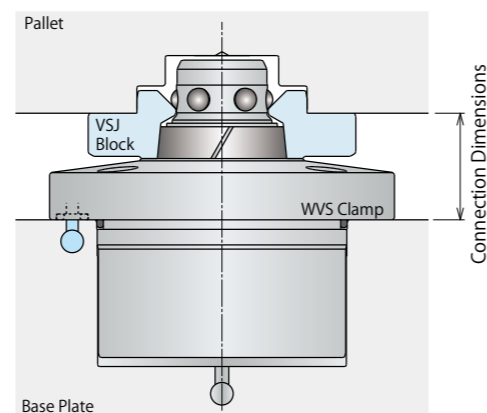
- Notes
- ※1. The screw for jack is used when VSJ block is removed.
  - ※2. The spring pin is used for phasing of VSJ-C locating direction.

Mounting Distance Accuracy and VSJ-C Phase

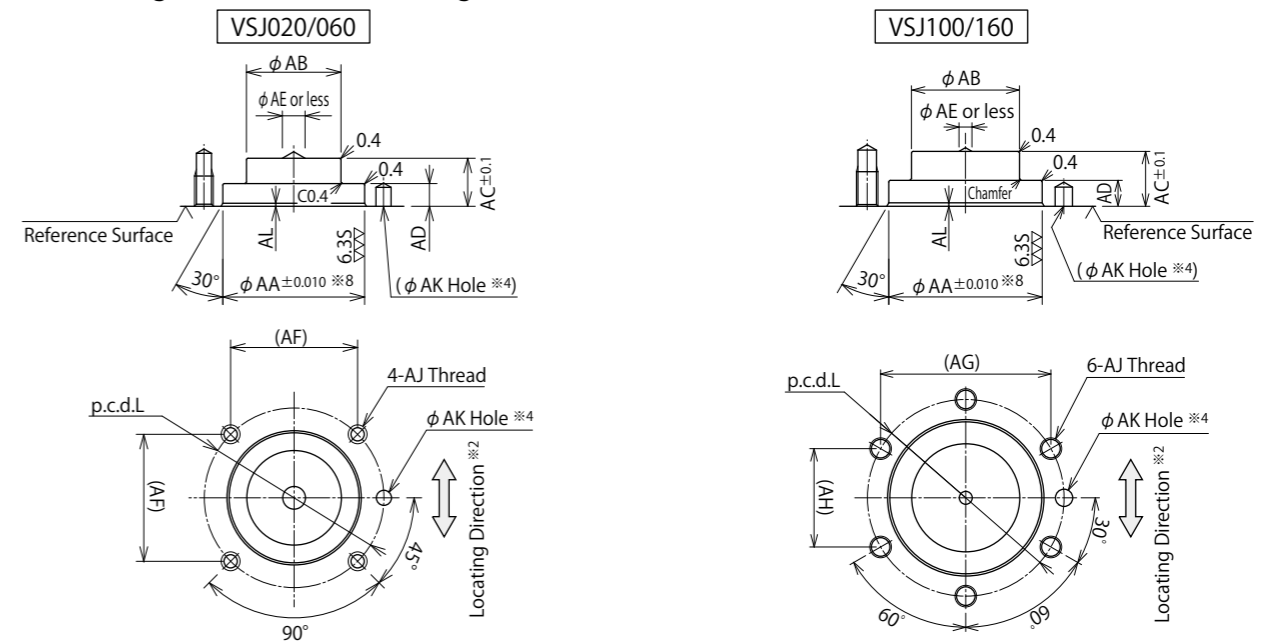


- Note
- ※3. Please make sure the precision between block pitches is within ±0.025mm between the blocks with the longest distance.

Connection Dimensions



Machining Dimensions of Mounting Area



- Note
- ※4. φ AK hole is used for phasing of VSJ-C locating direction. Please make sure φ AK hole is at the line connecting the centers of VSJ-D and VSJ-C. This machining is only necessary for VSJ-C.

External Dimensions and Machining Dimensions for Mounting

Model No.	VSJ020-D VSJ020-C	VSJ020-G VSJ020-F	VSJ060-D VSJ060-C	VSJ060-G VSJ060-F	VSJ100-D VSJ100-C	VSJ100-G VSJ100-F	VSJ160-D VSJ160-C	VSJ160-G VSJ160-F
A	31.5 <sup>+0.027</sup> <sub>+0.011</sub>	31.5g7 <sup>-0.009</sup> <sub>-0.034</sub>	37.5 <sup>+0.027</sup> <sub>+0.011</sub>	37.5g7 <sup>-0.009</sup> <sub>-0.034</sub>	52m6 <sup>+0.030</sup> <sub>+0.011</sub>	52g7 <sup>-0.010</sup> <sub>-0.040</sub>	62m6 <sup>+0.030</sup> <sub>+0.011</sub>	62g7 <sup>-0.010</sup> <sub>-0.040</sub>
B	25	22.7 (25.5) <sup>※5</sup>	28.5	26.2 (29) <sup>※5</sup>	36	32.5 (36.5) <sup>※5</sup>	42	38.5 (42.5) <sup>※5</sup>
C		32		35.5		44		51
F		49		59		74		89
G		18.3		20.3		26.3		32.3
H		8		10		10		12
J		13		15		16.5		18.5
K		6.7		7.8		7.8		8.8
L		40		47.5		62.5		75
AA <sup>※8</sup>		31.5		37.5		52		62
AB		22		25		31		38
AC		14.7		12.7		17.2		18.2
AD		6		6		7.5		7.5
AE		3		3		5		5
(AF)		28.28		33.59		-		-
(AG)		-		-		54.13		64.95
(AH)		-		-		31.25		37.5
AJ (Nominal×Pitch×Depth)	M4×0.7×8		M5×0.8×9		M5×0.8×9		M6×1×10	
AK	φ3.4 Depth 5	-	φ4.5 Depth 5	-	φ4.5 Depth 5	-	φ4.5 Depth 5	-
AL	0.8		0.8		0.8		0.8	
Chamfer	-		-		C0.4		C0.4	
Mounting Bolt	M4×0.7×10		M5×0.8×12		M5×0.8×12		M6×1×14	
Screw for Jack	M4×0.7		M5×0.8		M5×0.8		M6×1	
Spring Pin <sup>※6</sup>	φ3×10	-	φ4×10	-	φ4×10	-	φ4×10	-
Mass	0.1kg		0.18kg		0.3kg		0.55kg	
Appropriate Clamp	WVS0040-MD VS0020-MD VS/VT0040-MD	WVS0040-MG WVS0040-MD <sup>※7</sup> VS0020-MG VS/VT0040-MG VS0020-MD <sup>※7</sup> VS/VT0040-MD	WVS0060-MD VS/VT0060-MD	WVS0060-MG WVS0060-MD <sup>※7</sup> VS/VT0060-MG VS/VT0060-MD <sup>※7</sup>	WVS0100-MD VS/VT0100-MD	WVS0100-MG WVS0100-MD <sup>※7</sup> VS/VT0100-MG VS/VT0100-MD <sup>※7</sup>	WVS0160-MD VS/VT0160-MD	WVS0160-MG WVS0160-MD <sup>※7</sup> VS/VT0160-MG VS/VT0160-MD <sup>※7</sup>
Connection Dimensions	When Lock	20	23.5	26	32			
WVS/VS	When Release	21	24.5	27	33			

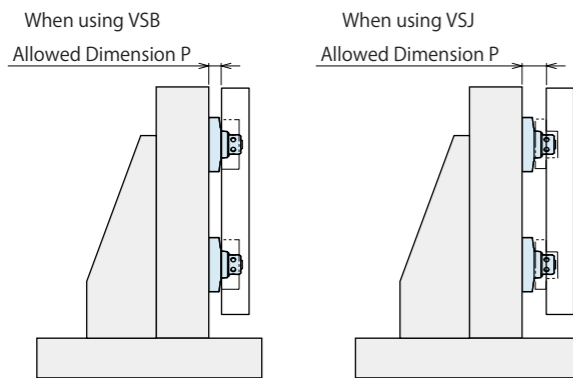
- Notes
- ※5. The dimensions in ( ) display that of VSJ-F.
  - ※6. The spring pin is included only in VSJ-C.
  - ※7. The guide block (VSJ-G) is used only for guide clamp (WVS-G) and the free block (VSJ-F) can be used for both datum clamp (WVS-D) and guide clamp (WVS-G).
  - ※8. Pallet with low rigidity (thin pallet or pallet made of aluminum etc.) may be deformed when mounting VSJ block. In this case, tolerance of mounting hole machining dimension AA±0.010 should be close to +0.010 (the upper limit of the tolerance).

Locating + Clamp
Locating
Clamp
Support
Valve · Coupler
Cautions · Others
Robotic Hand Changer
SWR
Pneumatic Location Clamp
SWT
High-Power Pneumatic Pallet Clamp
WVS

**Cautions**

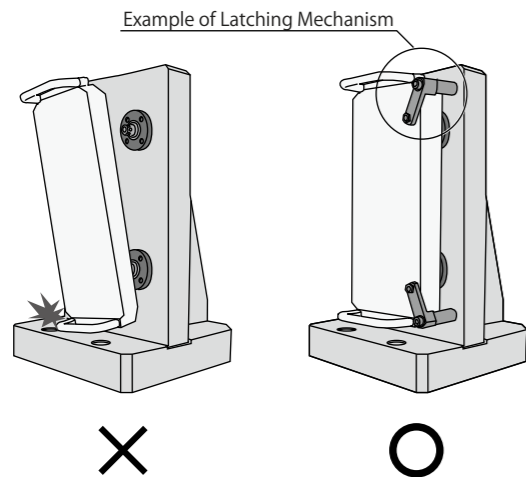
**Notes for Design**

- 1) Check Specifications
  - Please use each product according to the specifications.
- 2) Notes for Circuit Design
  - Never supply pressure simultaneously to lock and release ports. If incorrectly designed, the machine may malfunction, sustain damage or have reduced performance.
  - It is recommended to use the air flow path over  $\phi 6\text{mm}$ .
- 3) When the pallet is in vertical position.
  - When the workpiece fixture plate is being set, make sure it is in proper proximity and square to the clamps. If it is locked out of position, the machine or clamps may be damaged.



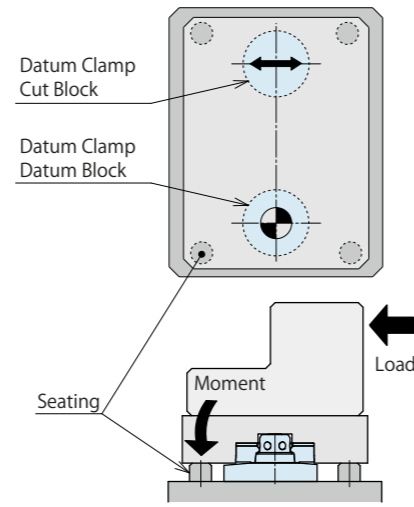
Model No.	WVS0040	WVS0060	WVS0100	WVS0160
VSB Block	13	14.5	17	21
VSJ Block	21.5	25	27.5	33.5

- As the workpiece fixture plate may fall down during releasing, it is recommended to set up the latching mechanism to prevent it from falling down.
- When the pallet is used in vertical position (hanging on the wall), the internal moving parts tend to wear out. Confirm the positioning precision in a regular manner. In case the allowed range is exceeded, change the machine.

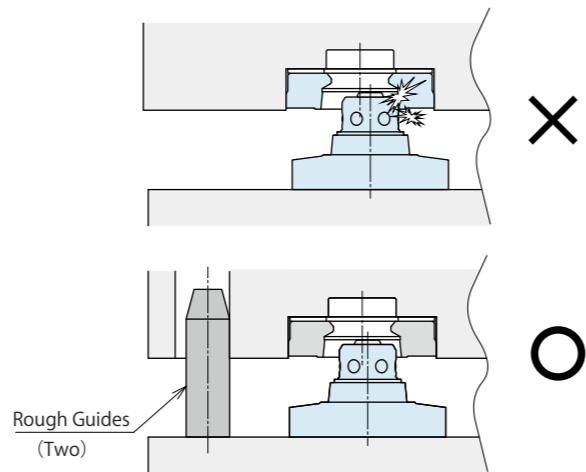


- When the pallet is in horizontal position (leveled), make sure the weight of the workpiece fixture is less than the lift force of the clamps and maximum load of the machine.
- When the pallet is in vertical position, make sure the weight of workpiece fixture pallet is 10% of the clamping force.
- Please contact us in case the pallet is in other positions.

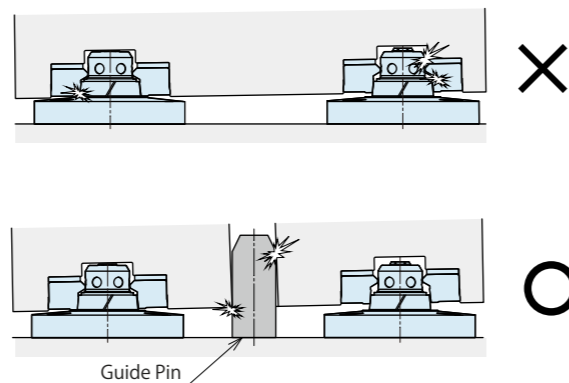
- 4) Seat Setting
  - In case the clamp/block configuration is linear, it is recommended to provide additional supports for stability.



- 5) Setting of Rough Guide
  - If the position of the pallet during loading is outside the clamp allowable tolerance, the clamp may prematurely contact the block taper surface causing damage affecting locating precision. It is recommended to use rough guides to contain the pallet within the allowable tolerance.



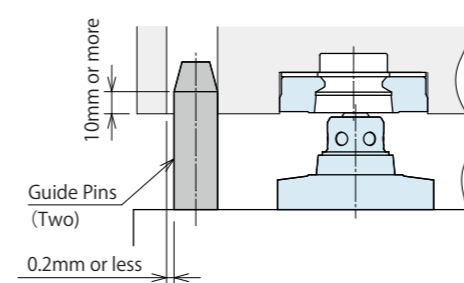
- The pallet must be level when lowering or lifting from the pallet clamps. If necessary, provide guide pins to keep the pallet level during loading and unloading.



- 6) It is necessary to have a guide in case the guide block (VSB/VSJ-G) is not used.
  - The combination of guide clamp (WVS-G) and guide block (VSB/VSJ-G) ensures the protective function of datum clamp. The guide should be set up in case the guide block is not used in the applications below.

When only the combination of datum clamps (2) and datum block (VSB/VSJ-D) cut block (VSB/VSJ-C) is used.

When only the combination of datum clamp and free block (VSB/VSJ-F) is used to rotate the fixture plate.

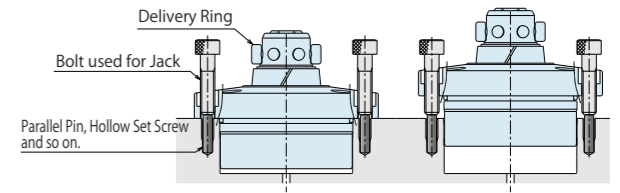


**Installation Notes**

- 1) Check the fluid to use.
  - Please supply filtered clean dry air.
  - Oil supply with a lubricator etc. is unnecessary.
- 2) Procedure before Piping
  - The pipeline, piping connector and fixture circuits should be cleaned and flushed thoroughly. The dust and cutting chips in the circuit may lead to fluid leakage and malfunction.
  - There is no filter provided with this product for prevention of contaminants in the air circuit.
- 3) Applying Sealing Tape
  - Wrap with tape 1 to 2 times following the screwing direction. Wrapping in the wrong direction will cause leaks and malfunction.
  - Pieces of the sealing tape can lead to air leaks and malfunction.
  - When piping, be careful that contaminant such as sealing tape does not enter in products.
- 4) Mounting the body
  - When mounting the product use all hexagon socket bolts (with tensile strength of 12.9) and tighten them with the torque shown in the chart below. Tighten them evenly to prevent twisting or jamming.

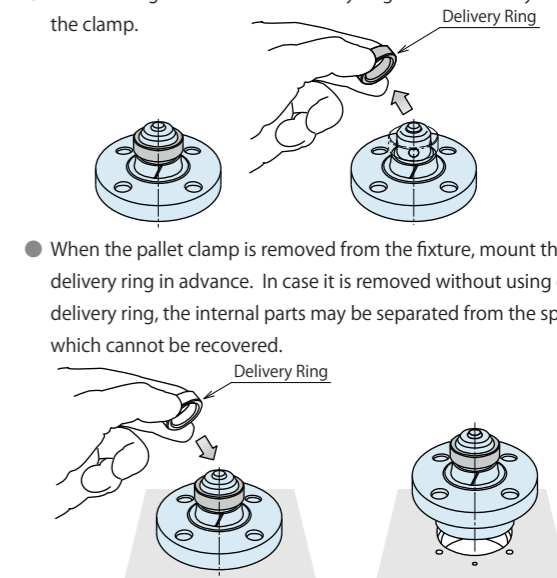
Clamp Model	Block Model		Thread Size	Tightening Torque (N·m)
WVS	VSB	VSJ		
-	VSB020	VSJ020	M4×0.7	3.2
WVS0040	VSB060	VSJ060	M5×0.8	6.3
WVS0060	VSB100	VSJ100	M6×1	10
WVS0100	VSB160	-	M8×1.25	25

- 5) Removal
  - Mount the delivery ring.
  - Remove mounting bolts. Insert jack bolts and tighten evenly to lift clamp.
  - Protect the screw parts with parallel pins as shown in the graph below in order for the bolts used for jack not to damage the surface of mounting screws.

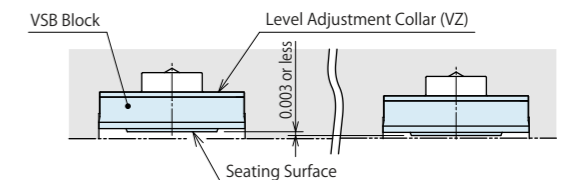


**6) Delivery Ring (Important)**

- The delivery ring is used to prevent separation of parts of individual clamps.
- The clamp will be equipped with a delivery ring for shipment. After the pallet clamp is mounted on the fixture, remove the delivery ring before use. (When the delivery ring is removed, ensure to supply the release pneumatic pressure.)
- Please take good care of the delivery ring as it is necessary to remove the clamp.



- 7) Level Adjustment of VSB Block Seating Surface.
  - When the fixture plates are assembled in the blocks, adjust the level of block seating surface in the way described below. (Recommended level adjustment: within  $\pm 0.003\text{mm}$ )
  - ① Assemble the fixture plate in the sequence of collar used for level adjustment and block in the, and tighten them with specified torque.
  - ② Measure the level of different block seating surfaces.
  - ③ In case the levels are not even, remove the blocks, and grind the collars used for level adjustment so that the level range is within 0.003mm.
  - ④ Once again, assemble the block and collar used for level adjustment into the fixture plate, and confirm the levels.



※ Please refer to P.363 for common cautions. • Notes on Handling • Maintenance/Inspection • Warranty

Locating + Clamp

Locating

Clamp

Support

Valve • Coupler

Cautions • Others

Robotic Hand Changer

SWR

Pneumatic Location Clamp

SWT

High-Power Pneumatic Pallet Clamp

WVS